

Subject		Market
Target Placement for LSS and BSM Calibration		USA
Service Category	Section	
Vehicle Interior	Pre-Collision Safety	
Applicability		
Models with LSS or BSM		

## APPLICABLE VEHICLES

2017-2022	IS350	2018-2022	LS500
2016-2022	RX450H	2018-2021	NX300
2016-2022	ES300H	2016-2020	GS F
2016-2022	IS300	2016-2020	GS350
2018-2022	RX350	2018-2022	LS500H
2016-2022	ES350	2016-2018	GS450H
2016-2017	IS200T	2018-2021	NX300H
2018-2021	LX570	2018-2022	RC300
2018-2022	RC350	2018-2022	RC F

## CONDITION

When used in conjunction with the Repair Manual, these Blind Spot Monitor, Forward Recognition Camera, and Front Millimeter Wave Radar tips leverage SSTs and readily available tools to support target placement in varying shop environments.

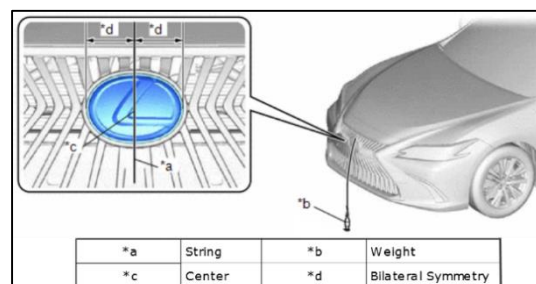
## RECOMMENDATIONS

**Creating the Centerline** – Marking/securing the centerline of the vehicle is the first step to ensure correct target placement.

### A. Creating a Centerline Using a 90-degree Laser (for Blind Spot Monitor)

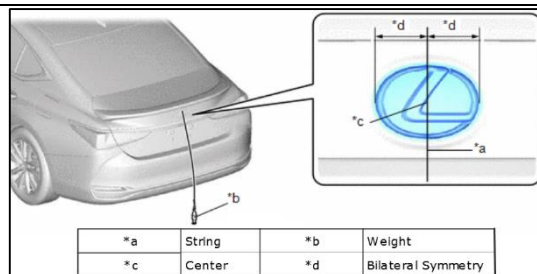
**Hint:** The vehicle centerline needs to extend past the rear of the vehicle for Blind Spot Monitor procedures.

1. Hang a plumb bob from the vehicle's front emblem, per the Repair Manual instructions, and mark the vehicle's front center point on the ground.

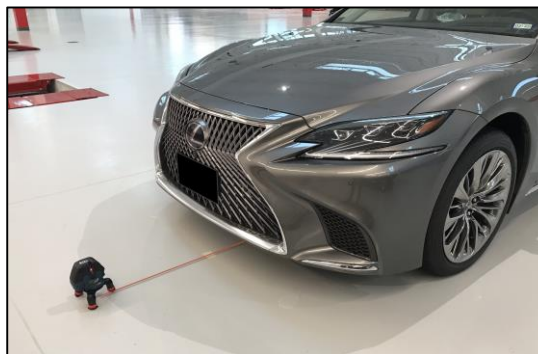


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2. Hang a plumb bob from the vehicle's rear emblem/center point, per the Repair Manual instructions, and mark the vehicle's rear center point on the ground.



3. Place the 90-degree laser from the SST kit (PN 00816-00103) approximately one foot in front of the **FRONT** vehicle centerline point so that the laser hits the center line mark.



4. Place the laser target from the SST kit (PN 00816-00103) on the **REAR** vehicle centerline mark.

**Hint:** A solid object with a 90-degree face can be used if the laser target is not available.



5. Align the laser with both vehicle centerline marks.

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- Remove the laser target at the rear of the vehicle to extend the centerline far enough to mark a perpendicular cross line required for target placement. Refer to the **“Creating a Perpendicular Line”** section (Pg. 6) for more information.

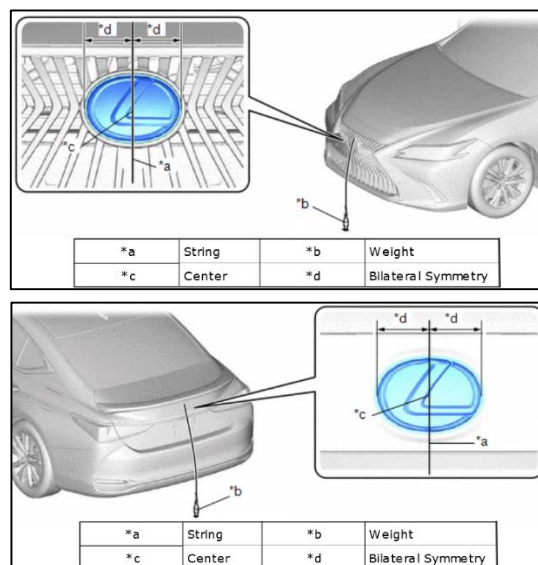
Hint: This laser line can now be used as the vehicle centerline.



## B. Creating a Centerline Using a 90-Degree Laser (for Forward Recognition Camera and Front Millimeter Wave Radar)

Hint: The vehicle centerline needs to extend past the front of the vehicle for Forward Recognition and Front Millimeter Wave Radar procedures.

- Hang a plumb bob from the vehicle's front emblem, per the Repair Manual instructions, and mark the vehicle's front center point on the ground.
- Hang a plumb bob from the vehicle's rear emblem/center point, per the Repair Manual instructions, and mark the vehicle's rear center point on the ground.



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- Place the 90-degree laser from the SST kit (PN 00816-00103) approximately one foot behind the **REAR** vehicle centerline point so that the laser hits the centerline mark.



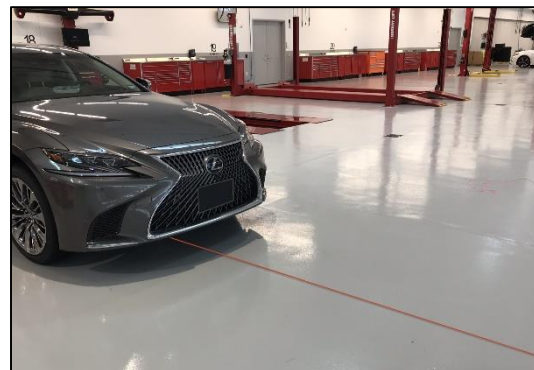
- Place the laser target from the SST kit (PN 00816-00103) on the **FRONT** vehicle centerline mark.

Hint: any solid, 90-degree block can be used if laser target is not available.



- Align the laser with both vehicle centerline marks.
- Remove the laser target to extend the centerline far enough to mark the perpendicular cross line required for target placement. Refer to the "**Creating a Perpendicular Line**" section (Pg. 6) for more information.

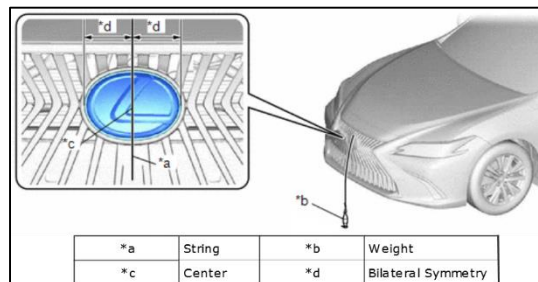
Hint: This laser line can now be used as the vehicle centerline.



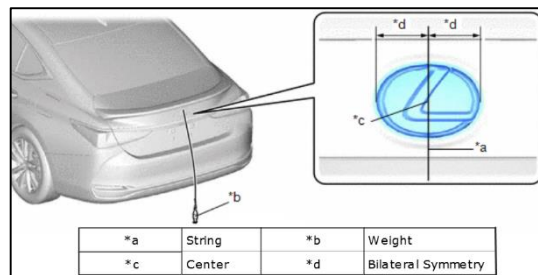
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### C. Creating a Centerline Using a String with Weight (All Systems)

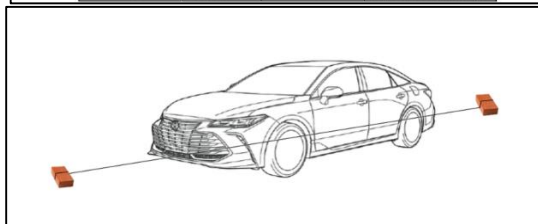
1. Hang a plumb bob from the vehicle's front emblem, per the Repair Manual instructions, and mark the vehicle's front center point on the ground.



2. Hang a plumb bob from the vehicle's rear emblem/center point, per the Repair Manual instructions, and mark the vehicle's rear center point on the ground.



3. Tie each end of a long string around separate solid objects. Stretch the string under the vehicle through both center point marks far enough to mark the perpendicular cross line required for target placement. Refer to the **“Creating a Perpendicular Line”** section (Pg. 6) for more information.



**Hint:** This string line can now be used as the vehicle centerline.



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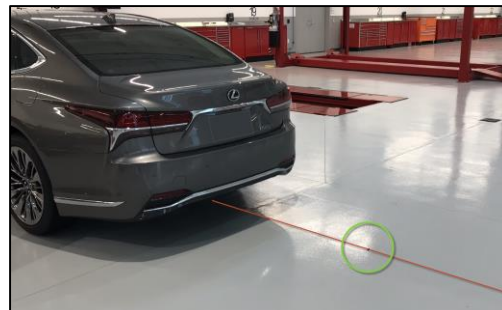
**Creating a Perpendicular Crossline** – Marking a perpendicular line off the vehicle centerline is the next step to ensure correct target placement.

**A. Creating a Perpendicular Crossline with a 90-Degree Laser (Forward Recognition Camera and Blind Spot Monitor)**

1. Mark the vehicle centerline.

**Hint:** Refer to “Creating the Centerline” (Pg. 1) or applicable Repair Manual.

2. Use the **Blind Spot Monitor Calculator, Forward Recognition Camera Calculator** (located in “Linked References” on Pg. 13), or the Repair Manual for this measurement. Mark the point on the vehicle centerline where the perpendicular crossline will intersect.



**Hint:** The example photo is displaying the perpendicular crossline point in the **rear** of the vehicle for Blind Spot Monitor, but this tip can also be used for Forward Recognition Camera, where this point will be at the **front** of the vehicle.

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- Place the 90-degree laser from the SST kit (PN 00816-00103) over the perpendicular line mark on the vehicle centerline.



- Place the laser target from the SST kit (PN 00816-00103) on the vehicle's marked center point farthest from the 90-degree laser.

Hint: For Blind Spot Monitor (shown), place laser target on the vehicle's **front** centerline point. For Forward Recognition Camera, place the laser target on the vehicle's **rear** centerline point.



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5. Create a laser line that intersects both vehicle centerline points by using the 90-degree laser and the laser target from the SST kit.



6. Create the perpendicular line using the 90-degree laser.





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- Refer to the **Blind Spot Monitor Calculator**, **Forward Recognition Camera Calculator**, or the applicable Repair Manual for this measurement. On the perpendicular crossline, mark the distance away from the vehicle centerline where the target/marker will be placed.

**Hint:** As an alternative measuring method, use the laser distance measurer from the SST kit (PN 00816-00103).



- Without moving the base, rotate the laser 90 degrees counter-clockwise to extend your perpendicular line towards the opposite target/marker, then repeat Step 7.

## **B. Creating a Perpendicular Crossline with a Carpenters Square (for Forward Recognition Camera)**

- Mark the vehicle centerline.

**Hint:** Refer to “Creating the Centerline” (Pg. 1) or applicable Repair Manual.

- Open **Forward Recognition Camera Calculator** (located in “Linked References” on Pg. 13). Use this calculator to determine the point on the vehicle centerline where the perpendicular crossline will intersect.

**Hint:** The perpendicular line point is also the center target placement point.

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- Using the square, align one leg along the centerline, with the other leg perpendicular to the vehicle centerline.



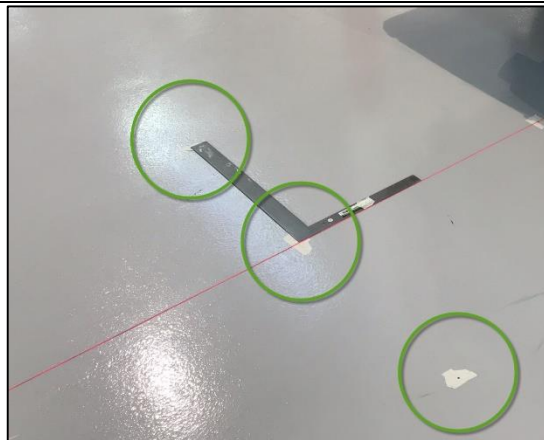
- Refer to the **Forward Recognition Camera Calculator** or the applicable Repair Manual for this measurement. On the perpendicular crossline, mark the distance away from the vehicle centerline where the target will be placed.

**Hint: Use a square that is at least 600mm long.**



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- Repeat Step 4 on the opposite side of vehicle's centerline for third target placement point.



### C. Creating a Perpendicular Crossline with a Carpenters Square (for Blind Spot Monitor)

- Mark the vehicle centerline.

**Hint:** Refer to "Creating the Centerline" (Pg. 1) or applicable Repair Manual.

- Use the **Blind Spot Monitor Calculator** (located in "Linked References" on Pg. 13) or the Repair Manual for this measurement. Mark the point on the vehicle centerline where the perpendicular crossline will intersect.
- Using the square, align one leg along the centerline, with the other leg perpendicular to the vehicle centerline. Mark the furthest point out on the square.

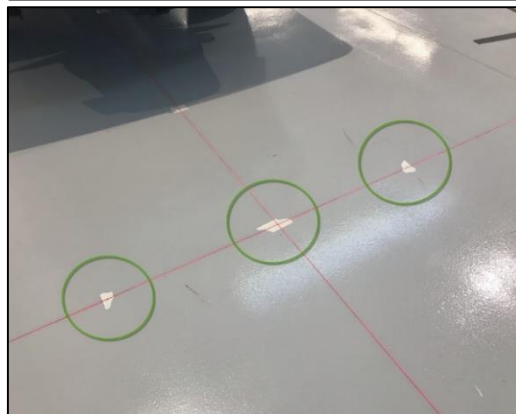


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- Using the square on the **opposite** side, align one leg along the centerline, with the other leg perpendicular to the vehicle centerline. Mark the furthest point out on the square.



- Create a perpendicular crossline that intersects all 3 points (two points created by the square and the vehicle centerline point) and extend the perpendicular line past the target/marker placement point.



- Refer to the **Blind Spot Monitor Calculator** or the applicable Repair Manual for this measurement. On the perpendicular crossline, mark the distance from the vehicle centerline where the target will be placed.





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#### LINK REFERENCES

4. [Forward Recognition Camera Calculator](#)
5. [Blind Spot Monitor Calculator](#)