

EA02-025

**FORD
OCTOBER 27, 2003**

**APPENDIX N
BOOKS 59 OF 61**

PART 2 OF 4



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3 TEST PROCEDURES AND REQUIREMENTS (cont'd)

3.3 Functional Tests (cont'd)

3.3.6 Extended Accelerated Life Test

This is a continuation of the 4 hour Accelerated Life Test 3.3.5 and is considered consistent with never ending improvement. The outcome of this test is to be used for informational purposes to identify potential product improvements. On termination of Test 3.3.5 and subsequent inspection, this test is to be done. It is the same cycle as Test 3.3.5 and is to be continued until all modules no longer conform to sections 3.3.1,2,3 or a maximum of 24 hours.

3.3.7 Monitored Durability Test

3.3.7.1 Monitored Climatic Environment Tests

The Speed Control assembly must endure the Monitored Climatic Environment Tests as specified in Section 3.4.5.1 through 3.4.5.5, and 3.4.5.8 while undergoing the Monitored Durability Test Cycle. The modules are chamber mounted and shall sustain the temperature/voltage/humidity profiles per Figures 8, 8a, 9, and 9a. Each Speed Control module is run in an open control loop with the durability tester downloading test software into the micro.

3.3.7.2 Monitored 1000 Hour Demonstrated Life Test

The Speed Control assembly must endure the 1000 Hour Demonstrated Life Test as specified in Section 3.4.8 while undergoing the Monitored Durability Test Cycle. The modules are chamber mounted and shall sustain the temperature/voltage profile per Figure 8 and 8a. Each Speed Control module is run in the open control loop with the durability tester downloading test software into the microcontroller's RAM.

3.3.7.3 Monitored Extended Life Test

This is a continuation of the 1000 hour Life Test 3.3.7.2 and is considered consistent with never ending improvement. The outcome of this test is to be used for informational purposes to identify potential product improvements. Begin after termination of Test 3.3.7.2 and subsequent inspection. It is the same cycle as Test 3.3.7.2 and is to be continued until all modules no longer conform to section 3.2 or a maximum of 3000 hours.

3.3.7.4 Monitored Durability Test Cycle

Unless otherwise specified, the Speed Control assembly must comply with section 3.3.1,2,3 after sustaining any of the following durability tests. Under no circumstances shall a Speed Control unit, subjected to any of these durability tests, be shipped for vehicle installation.

The load fixture, mounted external to the test chamber, must provide the spring load function per Figure 6 as well as the lost motion device at the point of servo cable attachment. The fixture also contains a position sensing device providing signals to tester to monitor actuator output position.

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3 TEST PROCEDURES AND REQUIREMENTS (cont'd)

3.3 Operational Tests (cont'd)

3.3.7 Monitored Durability Test (cont'd)

3.3.7.4 Monitored Durability Test Cycle (cont'd)

The position sensor input is influenced by three members. They are the load spring, the last motion device and a 2 position, (ROT and idle), accelerator linkage, which is controlled by the test equipment. The accelerator linkage simulates the accelerator of an actual vehicle installation. The last motion device prevents any pushing on the cable core wire at the fixture end of the cable.

The load fixture, mounted external to the test chamber, must provide the spring load function per Figure 6 as well as the last motion device at the point of servo cable attachment. The fixture also contains a position sensing device providing signals to tester to monitor actuator output position.

The position sensor input is influenced by three members. They are the load spring, the last motion device and a 2 position, (ROT and idle), accelerator linkage, which is controlled by the test equipment. The accelerator linkage simulates the accelerator of an actual vehicle installation. The last motion device prevents any pushing on the cable core wire at the fixture end of the cable.

The last motion device and the accelerator member are connected to the position sensor such that either may increase the position sensor input.

The load fixture also contains a mechanical "idle" stop such that a fully relaxed Speed Control module has no load on the cable. This "stop" must be designed as durable as possible because the life cycle includes a hard servo release which will pound against the "stop".

The tester shall be capable of stopping on test fault or switching with test faults. This should be operator selectable at any time during the test for any combination of test stations.

In addition, should a test be interrupted, the state of the test cycle, including the chamber cycle state and power supply cycle state, should be fully recoverable to the previous drive cycle test segment letter A. Test hours and drive cycles should be tracked and recorded on the basis of individual test stations. Should a module be removed for analysis, the remaining stations can continue test. Later, the module under analysis may be returned to test without loss of test hours accountability.

The durability test cycle is comprised of five segments (A-E) as indicated below. Segment A is the I/O diagnostic segment where the I/O circuitry is verified. Segments B-E are the dithering segments where the motor, clutch & associated electronics are exercised.

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3 TEST PROCEDURES AND REQUIREMENTS (cont'd)

3.3 Functional Tests (cont'd)

3.3.7 Monitored Durability Test (cont'd)

3.3.7.4 Monitored Durability Test Cycle (cont'd)

The test cycles are to be loaded while in Monitor Mode (see Section 3.10) for Families C, D, F, G, H. The test cycles are to be loaded through SGP communication for Family S.

A. CHARGE I/O STATE AFTER CYCLES H,C,D,F,G - FAMILIES C,D,F,G,H

- 1) Apply main power and de-activator switch power to the module.
- 2) Take the monitor routine and download I/O diagnostic routines into RAM. Refer to Figure 16 for the diagnostic code listing. A JUMP command at the end of the code begins the routine. Once the I/O diagnostic is started, no 2-way RS-232 communication from the durability tester is required.
- 3) The I/O diagnostic routine will provide a continuous stream of characters (via RS-232) from the module defining the state the microcontroller interprets each input. The stream of characters will include 2 characters. The first character will define which I/O. For example, AL is defined as input SPEED as LOGIC LOW, AH is defined as input SPEED as LOGIC HIGH. Refer to table 16 for definition of all I/O.
- 4) The INDICATOR LAMP OUTPUT will be triggered by the state of the BRAKE SWITCH input. If the BRAKE SWITCH input is recognized as an "L", then the INDICATOR LAMP output should be high (lamp OFF). If the BRAKE SWITCH input is recognized as an "H", then the INDICATOR LAMP output should be low (lamp ON).
- 5) The COMMAND SWITCH character G will be followed by the 2 bytes A/B conversion of the COMMAND SWITCH INPUT. The tester must decode this conversion and verify the correct state is recognized. It is important that the tester decodes and compare the value after the character G, and not confuse it with one of the other valid characters, since it is possible the converted state could be the ASCII representation of one of the other valid characters.
- 6) The durability tester reads the continuous stream of characters along with applying commands to verify I/O functionality.

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3 TEST PROCEDURES AND REQUIREMENTS (cont'd)

3.3 Functional Tests (cont'd)

3.3.7 Monitored Durability Test (cont'd)

3.3.7.4 Monitored Durability Test Cycle (cont'd)

A The dwell time for this segment is 30 ms. - FAMILY 3 ONLY

- 1) Initialize each individual module into normal control mode by turning on power and sending the "BRAKE OFF" command over the SGP network.

note: the brake off command and speed message must be sent within 3 seconds of power-up or the module will store a fault in EEPROM.

- 2) The taster shall transmit to each individual unit a vehicle set speed of 96 Km/h (60 mph or 3000 bpm).
- 3) The taster shall then wait for each unit to echo back this vehicle speed in low resolution form.
- 4) The unit must respond with the actual vehicle speed within 2 seconds of the set command to the unit.

B The dwell time for this segment is 240 seconds. - ALL FAMILIES

- 1) Open the DEACT input at Pin 1-9 (no power applied).
- 2) Download the dithering diagnostic code into RAM. Refer to Figure 16 for dithering diagnostic code listing.
- 3) Close the DEACT input (apply power). Verify the actuator output angular position moves to 64 steps for the 10 second period.
- 4) Verify the actuator dithers ± 11 steps for the remaining 230 seconds.
- 5) Remove Deactivator power from Pin 1-9. Verify a fast return of the actuator output to closed throttle position within 750 ms.

C The dwell time for this segment is 240 seconds. - ALL FAMILIES

- 1) Turn main power off & on for 200 ms.
- 2) Open the DEACT input at Pin 1-9 (no power applied).
- 3) Download the dithering diagnostic code into RAM. Refer to Figure 16 for dithering diagnostic code listing.
- 4) Close the DEACT input (apply power). Verify the actuator output angular position moves to 64 steps for the 10 second period.

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3 TEST PROCEDURES AND REQUIREMENTS (cont'd)**3.3 Functional Tests (cont'd)****3.3.7 Monitored Durability Test (cont'd)****3.3.7.4 Monitored Durability Test Cycle (cont'd)**

- 5) Verify the actuator dithers ± 12 steps for the remaining 230 seconds.
- 6) Remove Deactivator power from Pin 1-9. Verify a fast return of actuator output to the closed throttle position within 750 ms.
7. The dwell time for this segment is 240 seconds. - ALL FAMILIES
 - 1) Turn main power off & on for 200 ms.
 - 2) Open the DEACT input at Pin 1-9 (no power applied).
 - 3) Download the dithering diagnostic code into RAM. Refer to Figure 16 for dithering diagnostic code listing.
 - 4) Close the DEACT input (apply power). Verify the actuator output angular position moves to 124 steps for the 10 second period.
 - 5) Verify the actuator dithers ± 12 steps for the remaining 230 seconds.
 - 6) Remove Deactivator power from Pin 1-9. Verify a fast return of the actuator output to closed throttle position within 750 ms.
8. The dwell time for this segment is 240 seconds. - ALL FAMILIES
 - 1) Turn main power off & on for 200 ms.
 - 2) Open the DEACT input at Pin 1-9 (no power applied).
 - 3) Download the dithering diagnostic code into RAM. Refer to Figure 16 for dithering diagnostic code listing.
 - 4) Close the DEACT input (apply power). Verify the actuator output angular position moves to 460 steps for the 10 second period.
 - 5) Verify the actuator dithers ± 12 steps for the remaining 230 seconds.
 - 6) Remove Deactivator power from Pin 1-9. Verify a fast return of the actuator output to closed throttle position within 750 ms.

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3.3.7.4 Monitored Durability Test Cycle (cont'd)
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3 TEST PROCEDURES AND REQUIREMENTS (cont'd)

3.4 Environmental Tests

3.4.1 Acceptance Criteria

Modules must meet requirements of Functional Tests outlined in section 3.3.1, 3.3.2, 3.3.3

SECTION 3.4 - ENVIRONMENTAL TESTS			
TEST NUMBER	REFERENCE SPECIFICATION	MODULE CLASS	TEST
3.4.2 thru 3.4.4	ES-F2AF-1A269-AA Electrical Environment Sections 3.4.2 - 3.4.4 & ES-F2AF-1316-AA	A	
3.4.5.1	ES-F2AF-1A269-AA Section 3.4.5 Climatic Environment	V	3.4.5.1 - LOW TEMPERATURE EXPOSURE T2=-40° C 72 Hour Soak See Figure 8
3.4.5.2		V	3.4.5.2 - LOW TEMPERATURE OPERATION T1=-40° C 72 Hour Soak while Monitored See Figure 8
3.4.5.3		V	3.4.5.3 - HIGH TEMPERATURE EXPOSURE T6=+125° C 72 Hour Soak See Figure 8
3.4.5.4		V	3.4.5.4 - HIGH TEMPERATURE OPERATION T2=+115° C 72 Hour Soak while Monitored See Figure 8
3.4.5.5		V	3.4.5.5 - RAPID THERMAL CYCLE T1=-40° C, T2=+115° C 30 Cycles per Time/Temp. Profile (See Figure 8)
3.4.5.6		V	3.4.5.6 - THERMAL SHOCK RESISTANCE T5=-40° C, T6=+125° C 6 cycles / 2 hour soak @ each temp. >10° C/min.
3.4.5.7		V	3.4.5.7 - THERMAL SHOCK RESISTANCE T5=-40° C, T6=+125° C 1000 cycles / 30 min soak @ each temp. >10° C/min. NOTE: -SD644- ONLY
3.4.5.8		V	3.4.5.8 - HUMIDITY/TEMPERATURE CYCLE 5 cycles per Time/Temp./Humidity Profile See Figure 9

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SECTION 3.4 - ENVIRONMENTAL TESTS

TEST NUMBER	REFERENCE SPECIFICATION	MODULE CLASS	TEST
3.4.5.9.2	ES-P2AF-1A269-AA Section 3.4.5 Climate Environment: (cont'd)	IV	3.4.5.9.2 - WATER/WASHING IMPACT CAR WASH SPRAY Install Cable & Seal on Servo before test
3.4.5.9.3			3.4.5.9.3 - WATER/WASHING IMPACT HEAVY SPLASH SHOWER Install Cable & Seal on Servo before test
3.4.5.10		II	3.4.5.10 - DUST
3.4.6.1.1	ES-P2AF-1A269-AA Section 3.4.6 Mechanical Environment:	II	3.4.6.1.1 - VIBRATION ENDURANCE Method (B)
3.4.6.1.2		II	3.4.6.1.2 - VIBRATION OPERATIONAL Method (B)
3.4.6.2		II	3.4.6.2 - AUDIBLE NOISE VIBRATION Method (B)
3.4.6.3.3		IV	3.4.6.3.3 - BENCH DRIP
3.4.7.1	ES-P2AF-1A269-AA Section 3.4.7 Chemical Environments	IV	3.4.7.1 - SALT MIST ATMOSPHERE
3.4.7.2		I	3.4.7.2 - CHEMICAL RESISTANCE
3.4.8.1	ES-P2AF-1A269-AA Section 3.4.8 Deconcentrated Life	V	3.4.8.1 - HIGH TEMPERATURE ENDURANCE NOTE: -90044- ONLY
3.4.8.3		N/A	3.4.8.3 - MECHANICAL WEAR-CHE

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JOINTLY DETERMINE WHICH PROCESSUAL CHANGES TO THE PROCESS, MANUFACTURER OR MATERIAL SOURCE would have significant impact on the product's function, performance, durability or appearance. The supplier will describe these conditions in the Control Plan, along with either

- (1) the re-validation plan that would be followed in each case, or
- (2) a provision to submit an amended Control Plan for approval if any of these process changes are planned.

The Control Plan must include a provision that, for any significant change in processing, ACD-FED and the manufacturing location (internal or supplier) shall jointly determine if PV re-casting is required, and, if so, to what degree, i.e., Full or Mini-PV.

No change to processing may be allowed without prior engineering approval of the process changes and the attendant Control Plan changes.

5 INSTRUCTIONS AND NOTES

5.1 Control Plans

Control Plans address all significant design and process characteristics, which include all ES tests and Control Item characteristics. They describe the process potential studies that will be performed for product validation (including PV tests) and the ongoing product and process evaluation for continuing improvement (including IF tests). They include acceptance criteria, sample sizes, frequencies, data analysis methods and rejection plans.

The Control Plan is developed, and updated as necessary, by the manufacturing source in conjunction with the design responsible Product Engineering Office and other appropriate functions such as SQA. The Control Plan defines the management of the upstream production process and part variables (significant process characteristics) that affect the outcome of the ES tests or other significant design characteristics. The Control Plan also identifies the specific ES tests, with their sample sizes and frequencies, that will be performed in order to:

1. Confirm whether the process is being managed effectively.
2. Further identify significant process characteristics.
3. Evaluate performance of marginal processes.
4. Better anticipate the customer effect of proposed process improvements.

For any part on which ES tests have been specified, the manufacturing source must present the Control Plan and any revisions to the design responsible Product Design Office for approval. This Product Engineering Office has flexibility to honor business relationships with suppliers having proprietary processes.

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3 INSTRUCTIONS AND NOTES**5.2 Lot Definition**

A lot consists of no more than eight hours of production. When shifts are extended beyond eight hours, the product should be separated into at least two lots to provide the additional inspection required by overtime operations. The size of the lot does not affect the minimum sample size. The audit sample sizes are not to be reduced due to short production runs even though 100 percent inspection results.

5.3 Test Reporting and Record Retention

Recording and record retention shall conform to Ford QI-9000.

5.3.1 Production Validation

All PV samples and the test results and data from Production Validation testing must be submitted in report form to ED-PED prior to IIR. Product Engineering Office shall have final authority to approve PV testing.

5.3.2 In-Process

The IP test variable data produced as a result of performing the sample lot test requirements outlined in Section II must be collected and stored for ED-SQA review.

5.3.3 Test Report Contents

Equipment serial numbers, most recent date of calibration and test sample serial number must be recorded on all data sheets. Test summaries must be sorted by test temperatures -40°C, 25°C or 125°C, and contain:

- 1) Sample Size
- 2) X - BAR
- 3) High Reading
- 4) Low Reading
- 5) Standard Deviation
- 6) Cp and Cpk
- 7) Upper Test Limit
- 8) Lower Test Limit

The records must be stored such that all parametric data for any one sample piece may be recalled with traceability to the lot in which the sample was taken.

5.3.4 Reporting Frequency

Once a month a summary of the reject rates for incoming inspection, line fallout, repair stations, final test and audit tests, separated by part numbers and suppliers, shall be transmitted to ADD-CM20 and STA.

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5 INSPECTION AND TESTS**5.4 Test Correlation**

Equipment calibration must be demonstrated at the beginning and middle of each shift by the supplier. Also, test equipment correlation between on-line and audit test equipment shall be performed by supplier. The procedure must be approved by ACD-CRSO and documented in the supplier control document.

5.5 Fallout Analysis**5.5.1 In-line Fallout**

The assembly supplier is required to analyze all in-line fallout at the module level. All components from "isolated case" fallout and a sufficient quantity of "pattern" fallout must be analyzed to determine the root cause. All test methods and data used to identify the root cause will be submitted together with a report in an East-West ES format. Summary data of these results must be provided to ACD-CRSO monthly.

5.5.2 Returns - Body & Assembly Division/Field

The supplier shall have the capability to analyze all returns and shall identify the root cause of the returns. A report for each identified root cause is to be delivered to ED-PDC on a timely basis. All test methods and data used to identify the root cause will be submitted together with a report in an ES format. Summary data of these results must be provided to ACD-CRSO monthly.

5.6 Traceability

The manufacturer shall institute a traceability program per Ford Q-101 3.14 for all components:

Electronic Servo Assembly, Electronic Amplifier Assembly, Mechanical Actuator Assembly, Screws and Brackets.

In addition, each time a module is subjected to any of the daily IF indicated in Figure 1, the test number, test results, (parametric data), and date tested shall be traceable from the clearly marked bar coded module serial number. The module serial number shall be contained in the bar code permanently marked on the module housing.

5.7 Repair**5.7.1 Definition**

A repair is defined as the rework required for a module to pass a test requirement. The following restrictions apply.

- A module may be repaired no more than a total of 2 times.
- Any component which has been replaced during rework must be marked for visual identification.

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3 INSTRUCTIONS AND NOTES**3.7 Repairs (cont'd)****3.7.2 Procedure**

Repair of the modules may not be done until the manufacturer's repair procedure is approved by ACD-CENCO.

The repair procedure must:

- a. Identify the test station and report weekly results to the manufacturing responsible engineer and be available to ED-FEO on request.
- b. Define how the repair is to be performed for each component at each station reporting.
- c. Define an acceptance standard to verify the repair was done to the proper component on the proper module.
- d. Provide a method of identification and retrieval of the defective component part.
- e. Identify the responsible party for investigating the defective component.

3.8 Packaging and shipping

The packaging and shipment of parts must conform to the packaging and shipping guide, latest revision, as defined by the Material Handling Engineering Department, Manufacturing Engineering Office. The packaging must also be approved by ACD-CENCO before PWV.

3.9 Other Engineering PWV Requirements

This section should be understood as an engineering requirement controlled by ACD-CENCO.

1. Equipment list for: PV, Lot Testing and IP Test Stations.
2. All procedures (i.e., calibration, maintenance, equipment set up, station aids etc.) must be completed for production and IP test stations. The above procedures must be on display at all times or as specified by ACD-CENCO.
3. An EDL tester handler must default to rejecting assemblies. The method must be approved by ACD-CENCO.
4. The PWV pilot run must be performed with the same methods and control documents and quality inspection as during production. ACD-CENCO must be informed of the pilot run one week prior and be allowed to observe.
5. The supplier must establish a key yield point weekly report form and submit the report to ED-FEO monthly or as requested.

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3 INSTRUCTIONS AND NOTES**5.10 SYSTEM MONITOR OPERATION - FAMILIES C, D, E, G, H****5.10.1 General**

The system monitor is utilized by the functional In-Process testers and Accelerated Life Testers for communication with the amplifier microcontroller. The communication is RS-232.

5.10.2 Format and Configuration

The system monitor uses a synchronous serial communication interface in the microcontroller. Figure 3 illustrates the diagram of the system interface. For BASE SPEED CONTROL MODULES, the RECEIVE DATA (RDI) line shares the Speed Signal input pin (J1-3) and the TRANSMIT DATA OUT (TDO) line shares the Transmission Interface output pin (J1-2). For DIAGNOSTIC SPEED CONTROL MODULES, the RECEIVE DATA (RDI) line shares the Brake input pin (J1-4) and the TRANSMIT DATA OUT (TDO) line shares the Transmission Interface output pin (J1-2). The communication has the following format:

- A character has 1 start bit, 8 data bits, 1 stop bit, no parity.
- All characters are in uppercase ASCII format.
- Data is transmitted and received Least Significant Bit first.
- Transmission/Receive rate is 2400 baud.
- Memory and Data bytes are sent Most Significant Byte first.

5.10.3 Entering System Monitor (Sections 3.3.1.10, 3.3.2.12)

The system monitor is entered with the following sequence:

1. Apply power to the module.
2. Transmit an "M" to the module until the module replies with a ">" prompt. The power-up reset takes approximately 1 second.
3. Transmit a "PW" as the 2 character password.
4. Once the password matches, the module will respond with a SOFTWARE VERSION LEVEL (1 byte that is 2 ASCII characters) and the result of the microcontroller's self-test ("P" = Pass, "F" = Fail). The self-test tests the internal RAM, ROM, and A/D of the microcontroller.
5. The monitor routine is now activated and ready to receive instructions.

5.10.4 Monitor Commands

The system monitor routine will respond to three types of commands: Read, write, and jump. The following is the format for each command:

Command	Character Sent	Module Response
READ	RAAA	DD>> AA,AAA - address
WRITE	WAAD	<>> DD - data
PROGRAM	PAAD	<>> <>> - carriage
JUMP	JAATA	<>> return

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3 DEFINITIONS AND NOTES (cont'd)3.11 Serial Communication Link (SCF)3.11.1 General

The Serial Communication Link is a hard-wired physical interface between the tester and the DUT. The Ford SCF (Standard Corporate Protocol) Serial Communication Link, which is based on SAE J1850, uses a twisted wire pair to provide a physical communication path between a Vehicle ECU and tester connected to the Data Link. For more information about Ford SCF Serial Communications Link's protocol and message structure, refer to the Subsystem Design Specification for Standard Corporate Protocol (SCF Diagnostic System (ESD-SCF-002) or latest rev.

3.11.2 Downloading Data to ECU Memory

The DUT must be placed in the Diagnostic State in order to download data into the ECU memory. The Tester must be capable of supporting and meeting all requirements related to the downloading data to ECU Memory section of the Part-One Diagnostic Specification (GFD-ESDSD-VD001.4 or latest rev.).

In addition to the above specifications, a DUT shall meet all entry conditions specified below in order to enter into the Diagnostic State.

- a) Power must be applied to the module.
- b) DUT must receive the Park Command over the SCF Link.
- c) DUT must receive a valid node-to-node message within every 5.0 seconds upon receiving the Diagnostic Command request message. Once all the data has been downloaded to the DUT's RAM, this criteria is no longer necessary since the DUT will be executing the downloaded code.

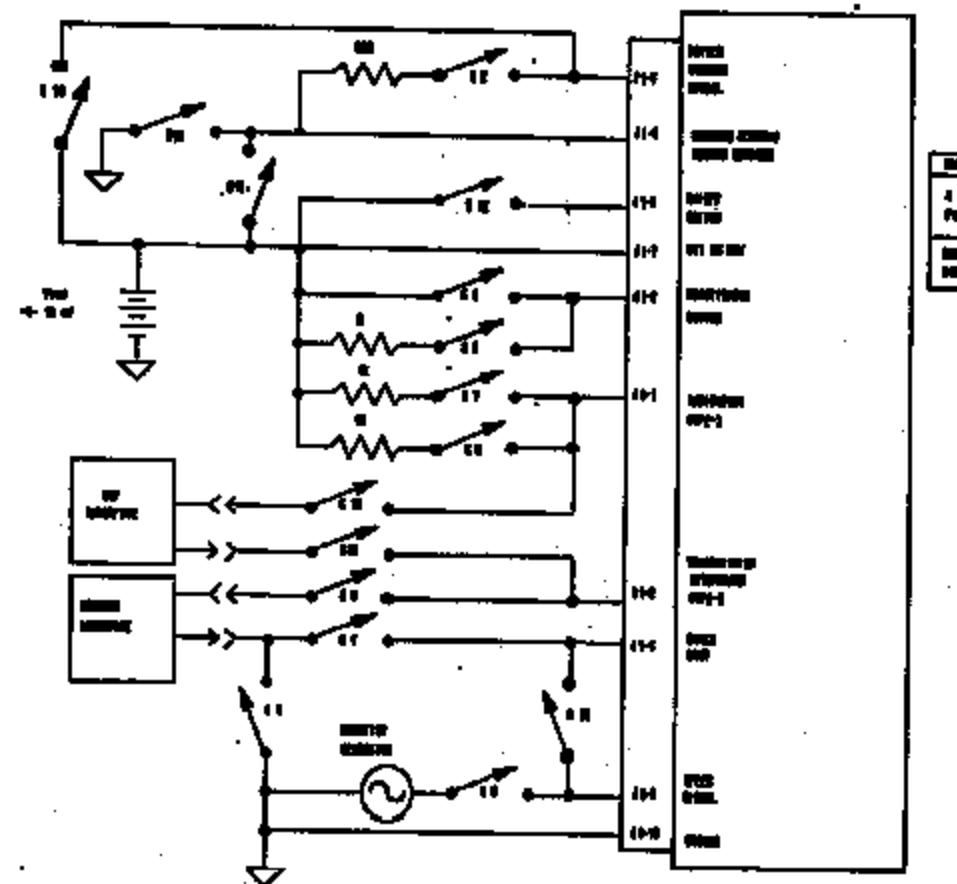
NOTE: The tester must enter into the Diagnostic State within 5 seconds of Power being applied to the module. Failure to enter into the Diagnostic State within this time will result in Fault Data being stored in the modules EEPROM.

4 COMPILED LIST OF REFERENCE DOCUMENTS

ES-P2V7-9A819-AA	HOUSING ASY-SPEED CONTROL ACTUATOR
ES-P2V7-9D854-AA	AMPLIFIER ASSEMBLY SPEED CONTROL
ES-P2AY-1316-AA	ELECTROMAGNETIC COMPATIBILITY COMPLIANCE
(SDD-SCF-002)	Subsystem Design Specification for Standard Corporate Protocol (SCF Diagnostic System)
GFD-ESDSD-VD001.4	Part One Diagnostic Specification
Q-101 LPPO	FORD QUALITY CONTROL
SAE Form #1638, or approved equivalent	
TMRA Form #QFD-9168 or approved equivalent	
CONTINUING PROCESS CONTROL AND PROCESS CAPABILITY IMPROVEMENT, FORD	
FORD RELIABILITY STANDARDS, INC	

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NOTE: ALL REQUIREMENTS ARE MET.

FUNCTIONAL TEST CIRCUIT FIGURE 3

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FIGURE 4 - FUNCTIONAL TEST STIMULUS AND MEASUREMENT MODES - FAMILY C, F, G ONLY

Test / Command	Part No.	Version 4.0V 5.0V	MEASURED OUTPUT / TEST MODE												Comments
			11	12	13	14	15	16	17	18	19	20	21	22	
Supply Sequence Control	3.3.1.1	14.00	0	0	0	0	0	0	1	0	0	0	0	0	17
Software Version	3.3.1.2	14.00	0	0	1	0	0	0	0	1	0	0	0	0	0
Micro Self Test	3.3.1.3	14.00	0	0	1	1	0	0	0	1	0	0	0	0	0
Power. Switch Threshold	LOW	3.3.1.4.1	14.00	0	0	1	1	0	0	0	1	0	0	0	0
	HIGH	3.3.1.4.2	14.00	1	0	1	1	0	0	0	1	0	0	0	0
System Voltage A/B	3.3.1.5	14.00	1	0	1	1	0	0	0	1	0	0	0	0	0
Current Output A/B	OFF	3.3.1.6.1	14.00	1	0	1	1	0	0	0	1	0	0	0	0
	ON	3.3.1.6.2	14.00	1	0	1	1	0	0	0	1	0	0	0	0
Battery Voltage	3.3.1.7	14.00	1	0	1	1	0	0	0	1	0	0	0	0	0
Temperature	3.3.1.8	14.00	1	0	1	1	0	0	0	1	0	0	0	0	0
Set Indicator - LOW LEVEL (A5, A2, A3, A6, B6, B5, AF, CF, DF, HF, VF)	LOW	3.3.1.9.1	14.00	1	0	1	1	0	1	0	1	0	0	0	V1-10
	HIGH	3.3.1.9.2	14.00	1	0	1	1	0	0	1	1	0	0	0	V1-10
Set Indicator - HIGH LEVEL (B5, B2, B3, B6, B5, B7, B1, B7, CF, HF, VF, DF, VF, DF)	LOW
FULL Load / Partial Stroke / Deadzone	SWR BOOT STROKEMAP RELEASE	3.3.1.10.1 3.3.1.10.2 3.3.1.10.3	14.00 14.00 14.00	1	0	1	1	0	1	0	1	0	0	0	THETA THETA
Full Load/Full Stroke	CLOCK SWELL RELEASE WOOD PARK	3.3.1.11.1 3.3.1.11.2 3.3.1.11.3	14.00 14.00 14.00	1	0	1	1	0	1	0	1	0	0	0	THETA THETA
No-Load Release/Retracing Timer	RELEASE TIME RELEASE	3.3.1.12.1 3.3.1.12.2	14.00 14.00	1	0	0	0	1	0	1	1	0	0	0	THETA

Parameter Test Pattern Summary Test-40 - Test Nos. 5, 7, 8, 9, 10, 11, 12, 13, 14, 15, 16, 17, 18, 19, 20, 21, 22

Test	Time of 0.00 sec	Time of 0.01 sec	Offset of 0.01 sec	Time
Square	100.0	100.00	0.0	100.00
Square	100.0	100.00	0.0	100.00
Square	100.0	100.00	0.0	100.00
Square	100.0	100.00	0.0	100.00

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Test / Scenario	Test ID.	Worst (¹ = 0.00%)	WATCH FRAMES (ROWS) / FUNCTIONS												Notes			
			01	02	03	04	05	06	07	08	09	000	011	022	033	044	055	066
Initial Reference Current	3.3.1.1	10.00	0	0	0	0	0	0	1	1	0	0	0	0	0	0	0	1.7
Reference Voltage	3.3.1.2	10.00	0	0	1	1	0	0	0	1	0	0	0	0	0	0	0	0
Alarm Hold Time	3.3.1.3	10.00	0	0	1	1	0	0	0	1	0	0	0	0	0	0	0	0
Reset, Release Threshold	3.3.1.4.1 3.3.1.4.2	10.00 10.00	1	1	1	1	0	0	1	1	0	0	0	0	0	0	0	0
Release Voltage A/F	3.3.1.5	10.00	1	0	1	1	0	0	0	1	0	0	0	0	0	0	0	0
Command Release A/F	3.3.1.6.1 3.3.1.6.2	10.00 10.00	1	1	1	1	0	0	1	1	0	0	0	0	0	0	0	0
Not Indicator - LAMP SERVICE CALL PRIORITY 00	3.3.1.8.1 3.3.1.8.2	10.00 10.00	1	1	1	1	0	0	1	1	0	0	0	0	0	0	0	1.1-10 1.1-10
Partial Load / Partial Stroke / Reactivation	3.3.1.10.1 3.3.1.10.2 3.3.1.10.3	10.00 10.00 10.00	1	0	1	1	1	1	0	1	1	0	0	0	0	0	0	100%
Full Load/Full Stroke	3.3.1.11.1 3.3.1.11.2 3.3.1.11.3	10.00 10.00 10.00	1	0	1	1	1	1	0	1	1	0	0	0	0	0	0	100%
No-Load Release/Reactivation Timers	3.3.1.12.1 3.3.1.12.2	10.00 10.00	1	0	1	1	1	1	0	1	1	0	0	0	0	0	0	100%

NOTE: Function Generator not required for Diagnostic Check by 00 Modules

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P/N 72V7-10715-A

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TABLE 6 - ENGINEERED TEST REQUIREMENTS AND TESTS FOR F-1000

TEST / COMMENTS	TEST ID.	TEST NO. 10- 0.0002	SWITCH STATES (0=LOW / 1=HIGH)												STATUS					
			01	02	03	04	05	06	07	08	09	10	11	12	13	14	15	16		
Switch Assignment Checks	3.3.1.1	10.00	0	0	0	0	0	0	0	1	0	0	0	0	0	0	0	0	17	
Software Version	3.3.1.2	10.00	0	0	1	1	0	0	0	0	1	0	0	0	0	0	0	0	0	0
Micro Self Test	3.3.1.3	10.00	0	0	1	1	0	0	0	1	0	0	0	0	0	0	0	0	0	0
SWIFT Switch Threshold	100 3.3.2.4.1	10.00	1	0	1	1	0	0	1	1	1	0	0	0	0	0	0	0	0	0
	100 3.3.2.4.2	10.00	1	0	1	1	0	0	1	1	1	0	0	0	0	0	0	0	0	0
2nd Control Switch Threshold	100 3.3.2.5.1	10.00	1	0	1	1	0	0	1	1	1	0	0	0	0	0	0	0	0	0
	100 3.3.2.5.2	10.00	1	0	1	1	0	0	1	1	1	0	0	0	0	0	0	0	0	0
Smart Switch Threshold	100 3.3.2.6.1	10.00	0	0	1	1	0	0	1	1	1	0	0	0	0	0	0	0	0	0
	100 3.3.2.6.2	10.00	0	0	1	1	0	0	1	1	1	0	0	0	0	0	0	0	0	0
System Voltage A/B	3.3.2.7	10.00	0	0	1	1	0	0	0	0	1	0	0	0	0	0	0	0	0	0
Control Search A/B	OVER 3.3.2.8.1	10.00	1	1	1	1	0	0	0	0	1	0	0	0	0	0	0	0	0	0
	OVER 3.3.2.8.2	10.00	1	1	1	1	0	0	0	0	1	0	0	0	0	0	0	0	0	0
Over Voltage	3.3.3.1.7	10.00	1	0	1	1	0	0	0	1	0	0	0	0	0	0	0	0	0	0
Emergency	3.3.3.1.10	10.00	1	0	1	1	0	0	0	1	0	0	0	0	0	0	0	0	0	0
Set Indicator	10 3.3.3.11.1	10.00	1	1	1	1	0	0	0	1	1	0	0	0	0	0	0	0	0	0
	100 3.3.3.11.2	10.00	1	1	1	1	0	0	0	1	1	0	0	0	0	0	0	0	0	0
Fault Load / Partial Events / Breakthrough	100 3.3.3.12.1 100 3.3.3.12.2 100 3.3.3.12.3	10.00	1	0	1	1	0	0	1	1	1	0	0	0	0	0	0	0	0	0
Fault Load / Fault Strike	CLUTCH BRAKE 3.3.3.13.1 CLUTCH BRAKE 3.3.3.13.2 CLUTCH BRAKE 3.3.3.13.3	10.00	1	1	1	1	0	0	0	0	1	0	0	0	0	0	0	0	0	0
No-Load Release/Retarding Thresh	RELEASE 3.3.3.14.1 RELEASE 3.3.3.14.2	10.00	1	0	1	1	0	0	0	0	1	0	0	0	0	0	0	0	0	0

TABLE 6 - ENGINEERED TEST REQUIREMENTS AND TESTS FOR F-1000

Max	From +0.01% to	From +/- 0.01%		
Square	100.0	10.0pp	2.0 V	N/A

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ENGINEERING SPECIFICATION

PART NUMBER
ES-724P-97334A

REV

EFFECTIVE DATE
10/10/01

Test / Function	Test No.	Spec (S/N, R/R)	SYSTEM TESTS (S-0700 / T-02000)															Notes	
			01	02	03	04	05	06	07	08	09	010	011	012	013	014	015		
Module Reference Current	3.3.3.1	14.00	1	0	0	0	0	0	0	0	1	0	0	0	0	0	0	17	
Software Version	3.3.3.2	14.00	1	0	0	0	0	0	0	0	0	1	0	0	0	1	1	8	
Micro Self Test	3.3.3.3	14.00	1	0	0	0	0	0	0	0	0	1	0	0	0	0	1	8	
Boot. Watch Threshold	3.3.3.4.1 3.3.3.4.2	14.00 14.00	1	0	0	0	0	0	0	0	1	1	0	0	0	0	1	8	
System Voltage A/D	3.3.3.5	14.00	1	0	0	0	0	0	0	0	0	0	0	0	0	0	1	8	
Current Doubles A/D	3.3.3.6.1 3.3.3.6.2	14.00 14.00	1	0	0	0	0	0	0	0	1	0	0	0	0	0	1	8	
Poll Lead / Parallel Stacks / Isolators	3.3.3.7.1 3.3.3.7.2 3.3.3.7.3	14.00 14.00 14.00	1	0	0	0	0	0	0	0	1	0	0	0	0	1	1	8	
Poll Stacks / Poll Lead	3.3.3.8.1 3.3.3.8.2 3.3.3.8.3	14.00 14.00 14.00	1	0	0	0	0	0	0	0	1	0	0	0	0	0	1	8	
No-Load Recovery/Stacking Timeout	3.3.3.9.1 3.3.3.9.2	14.00 14.00	1	0	0	0	0	0	0	0	0	1	0	0	0	0	0	1	8

Parameter Test Function Generator Set-Up - Facility				
Max	From +/- 0.01 m	Min +/- 0.01 m	Offset +/- 0.01 V	Module
Square Wave	300.0 300.0	10 Vpp 10 Vpp	0.1 0.1	14

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FIGURE 4. - FUNCTIONAL TEST RESULTS AND INVESTIGATIVE NOTES - FAMILY C. F. G. GAY

Test / Comment	Test No.	Version 4.07- 5.007.2	Status Report - Software / Hardware												Comments	
			01	02	03	04	05	06	07	08	09	010	011	012		
Module Alignment Current	3.3.1.1	14.00	0	0	0	0	0	0	0	0	0	0	0	0	0	
Software Version	3.3.1.2	14.00	0	0	1	1	0	0	1	0	0	0	0	0	0	
Micro Self Test	3.3.1.3	14.00	0	0	1	1	0	0	1	0	0	0	0	0	0	
Power Switch Threshold	400 500	3.3.1.4.1 3.3.1.4.2	14.00 14.00	0	0	1	1	0	0	1	0	0	0	0	0	
Bridge Voltage A/D	3.3.1.5	14.00	1	0	1	1	0	0	1	0	0	0	0	0	0	
Current Bridge A/D	4000 5000	3.3.1.6.1 3.3.1.6.2	14.00 14.00	1	0	1	1	0	0	1	0	0	0	0	0	
Over Voltage	3.3.1.7	14.00	1	0	1	1	0	0	1	0	0	0	0	0	0	
Photometer	3.3.1.8	14.00	1	0	1	1	0	0	1	0	0	0	0	0	0	
Net Indicator - LOGIC LEVEL (00,01,02,03,04,05,07,09,0F,0F)	100	3.3.1.9.1	14.00	1	0	1	1	0	0	1	0	1	0	0	0	V1-70 V1-100
Net Indicator - LAMP INDICATOR (00,01,02,03,04,05,06,07,08,09,0A,0B,0C,0D,0E,0F)	100	3.3.1.9.2	14.00	1	0	1	1	0	0	1	1	0	0	0	0	
Wall Lamp / Partial Stroke / Smoothness	1000000 STROBE/PARK ROTATE	3.3.1.10.1 3.3.1.10.2 3.3.1.10.3	14.00 14.00 14.00	1	0	1	1	0	1	0	1	0	0	0	0	THIN THICK
PATI Lamp/Wall Stroke	1000000 ROTATE	3.3.1.11.1 3.3.1.11.2 3.3.1.11.3	14.00 14.00 14.00	1	0	1	1	0	1	0	1	0	0	0	0	THIN THICK
No-load Voltage/Decoding Timeout	0.000000 ROTATE	3.3.1.12.1 3.3.1.12.2	14.00 14.00	1	0	1	0	1	0	1	0	1	0	0	0	THIN THICK

Reorder Type: Function Generator Depth - Confirms G. L. S. - 007-00000000000000000000000000000000

BUDGETS AND SPECIFICATIONS

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ENGINEERING SPECIFICATION

PART NUMBER
ES-72707-90733-44

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FIGURE 2a - Standard Test Units (400 to 1000) - Profile & Displacement Only

Ref ID: 00, 01, 02, 03, 04, 05, 06, 07

Test	No.	Outputs	Min	Target @ 25°C	Max	Comments	Unit
Induced Current	3.3.1.1	I 1-7	-17	25	32		mA
Software Version	3.3.1.2	N	-	As Required	-	* See Figure 1b	
Start Self Test	3.3.1.3	N	-	-	-		s
Reactuator Switch Threshold SUS SH	3.3.1.4.1 3.3.1.4.2	N	-	0	1		PPR PPR
System Voltage A/B	3.3.1.5	N	110	140	170		volts
Current Sensors over current over current	3.3.1.6.1 3.3.1.6.2	N	-2	0	5		amps amps
Set Indicator	01 02	3.3.1.9.1 3.3.1.9.2	V 1-10 V 1-10	10.00 0	15.71 0.00	14.49 0.00	V V
Full Load / Partial Stroke / Repetitive							
ONE REV STROKE/PULSE RELEASE	3.3.1.10.1 3.3.1.10.2 3.3.1.10.3	THETA THETA	210	310	360		deg.
Full Load / Full Stroke CUTTER DRILL OPENING CLOSE PULSE	3.3.1.11.1 3.3.1.11.2 3.3.1.11.3	THETA	140	170	190		deg.
No Load Release and Holding Time							
OPEN LONG RELEASE	3.3.1.12.1 3.3.1.12.2	THETA	-5	0	5		deg.

16. The 00401/5149 part number

TABLE 16 - THERMAL TEST Limits (0-85°C IN TAFC) - RELIABILITY ONLY							
Test	No.	Outputs	Min	Target at 25°C	Max	Comments	Units
Relay Current	3.3.3.1	11-17	N	20	30		mA
Software Version	3.3.3.2	N	-	As Required	-	* See Figure 16	*
Wire Self Test	3.3.3.3	N	-	0	-		mV
0.00V Switch Threshold	Line	3.3.3.4.1	N	-	-		mV
	11	3.3.3.4.1	N	-	-		mV
2nd Com. Switch Threshold	Line	3.3.3.5.1	N	-	-		mV
	11	3.3.3.5.1	N	-	-		mV
Dec. Switch Threshold	Line	3.3.3.6.1	N	-	-		mV
	11	3.3.3.6.1	N	-	-		mV
System Voltage A/B	3.3.3.7	N	175	185	195		VOLTS
Demand Signals	OPEN CIRCUIT WITH GNDING	3.3.3.8.1	N	-5	0	5	
		3.3.3.8.2	N	-75	-72	-67	
Battery Voltage	3.3.3.9	N	45	50	55		VOLTS
Ammeter	3.3.3.10	N	3.742	4.000	4.000		mA
Set Indicator	0%	3.3.3.11.1	V-15	13.44	0.75	14.05	%
	100%	3.3.3.11.2	V-15	0	0.35	0.35	%
Full Load / Partial Stroke / Overdrive	100% LOAD OVERDRIVE OVERDRIVE	3.3.3.12.1	TEST	21	31	34	%
		3.3.3.12.2	TEST	21	31	34	%
		3.3.3.12.3	TEST	21	31	34	%
Full Load / Full Stroke	100% LOAD OVERDRIVE OVERDRIVE	3.3.3.13.1	TEST	160	177	185	%
No Load Release and Unloading Timers	NO LOAD RELEASE	3.3.3.14.1	TEST	2	8	5	%
		3.3.3.14.2	TEST	2	8	5	%

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REV. 00401-5149-A

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6 48.00/01/E, uq, passed

FIGURE 10 - Functional Test Limits (-40° to 125°C) - Assembly 2 (cont'd) Only

Test	No.	Output	Min	Target @ 25°C	Max	Comments	Unit
Reference Current	2.3.3.1	I 1-7	17	24	30		mA
Reference Revision	2.3.3.2	N	-	As Required	-	* See Figure 10	•
Start Self Test	2.3.3.3	N	-	0	-		s
Reactive Power Threshold	2.3.3.4						
System Voltage A/F	2.3.3.5	N	134	165	197		volts
Current Stacks							amps
OPEN CIRCUIT	2.3.3.6.1	N	-	0	-		amps
NET CURRENT	2.3.3.6.2	N	-27	-72	-48		amps
Pull Load / Partial Stroke / Positive OPEN CIRCUIT RELEASE	2.3.3.7.1 2.3.3.7.2 2.3.3.7.3	THETA	21	30	34		deg
Pull Load / Full Stroke							deg
OPEN CIRCUIT	2.3.3.8.1 2.3.3.8.2 2.3.3.8.3	THETA	100	110	100		deg
No Load Release and threading Flows OPEN LOAD RELEASE	2.3.3.9.1 2.3.3.9.2	amps	-6	0	3		amps

FUNCTIONAL SPECIFICATION
REV B
10-227-0025-02

10-227-0025-02
10-227-0025-02

SH-5207-50715A
MOTOR DIFFERENCE OF SWING SPECIFICATION

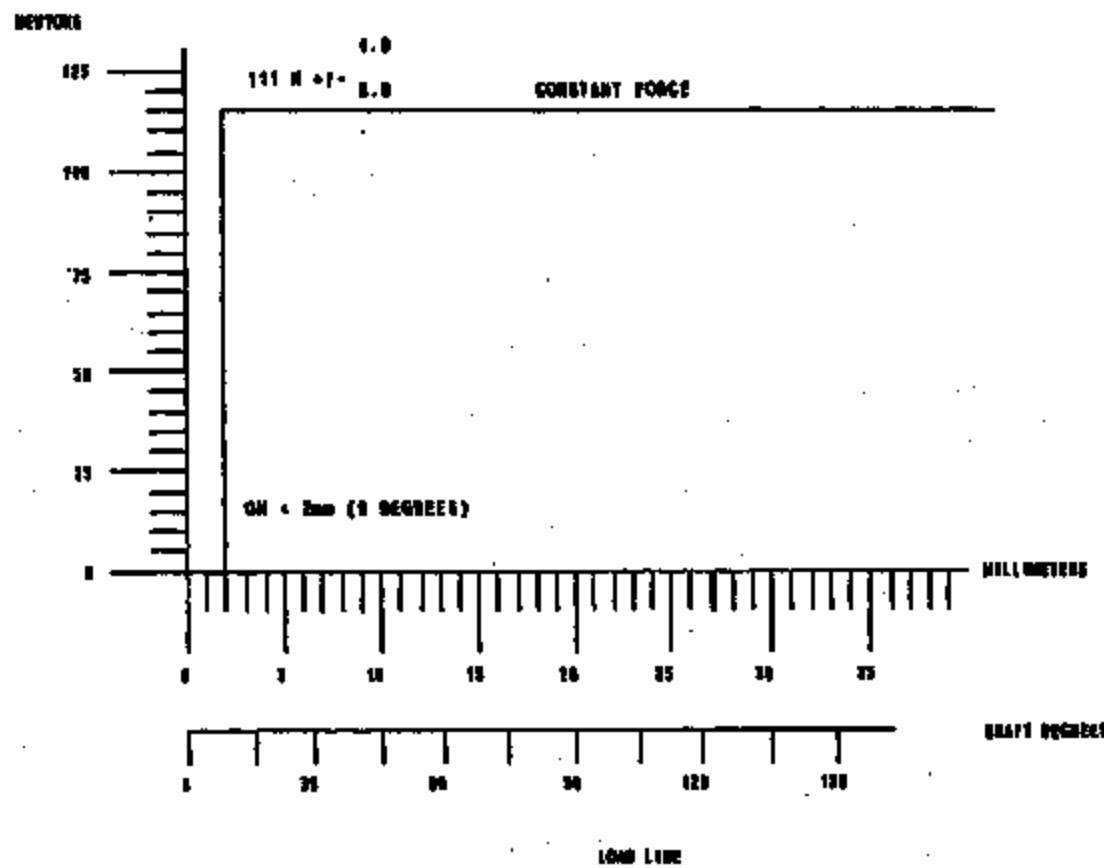


FIGURE 6

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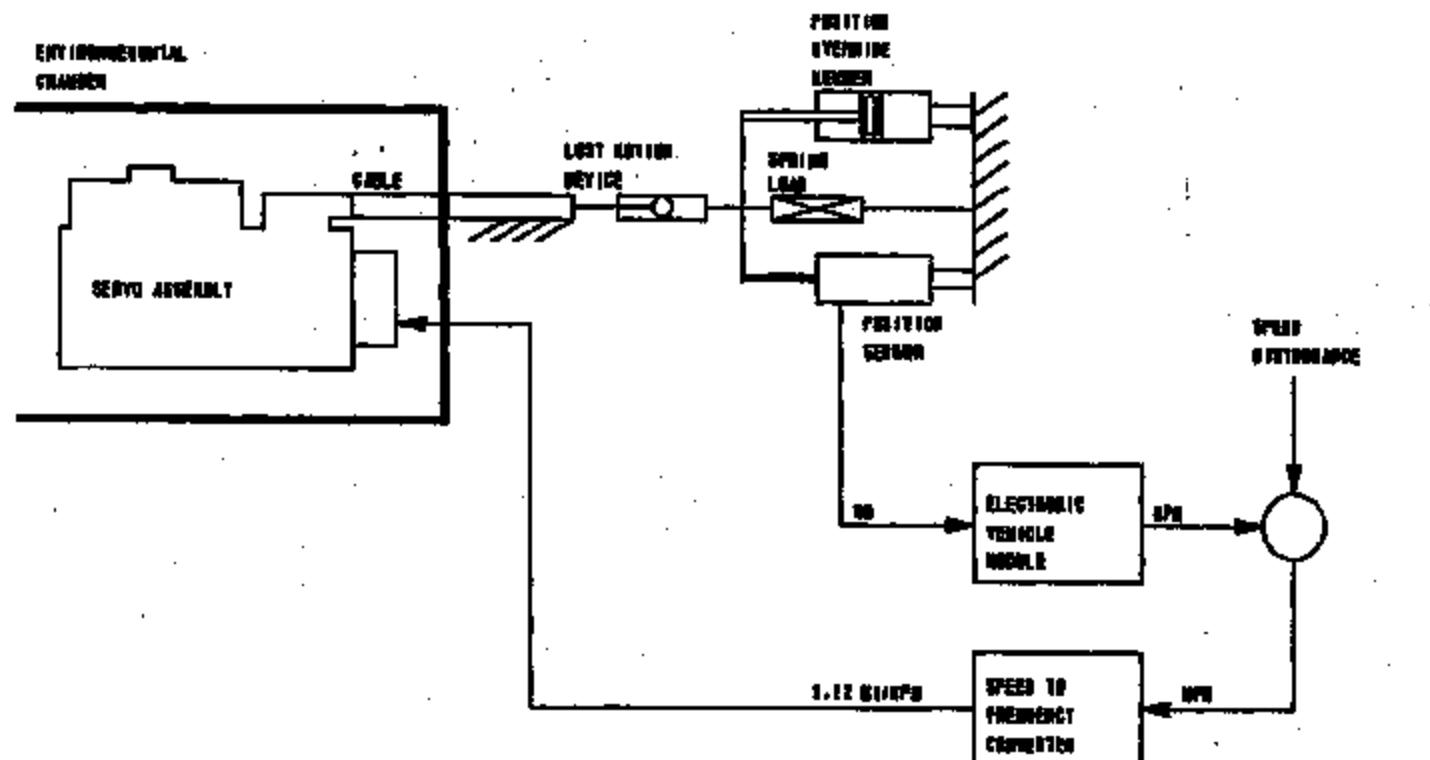


FIGURE 7

ENGINEERING SPECIFICATION

REV B
MIL-STD-461C-42173-4A

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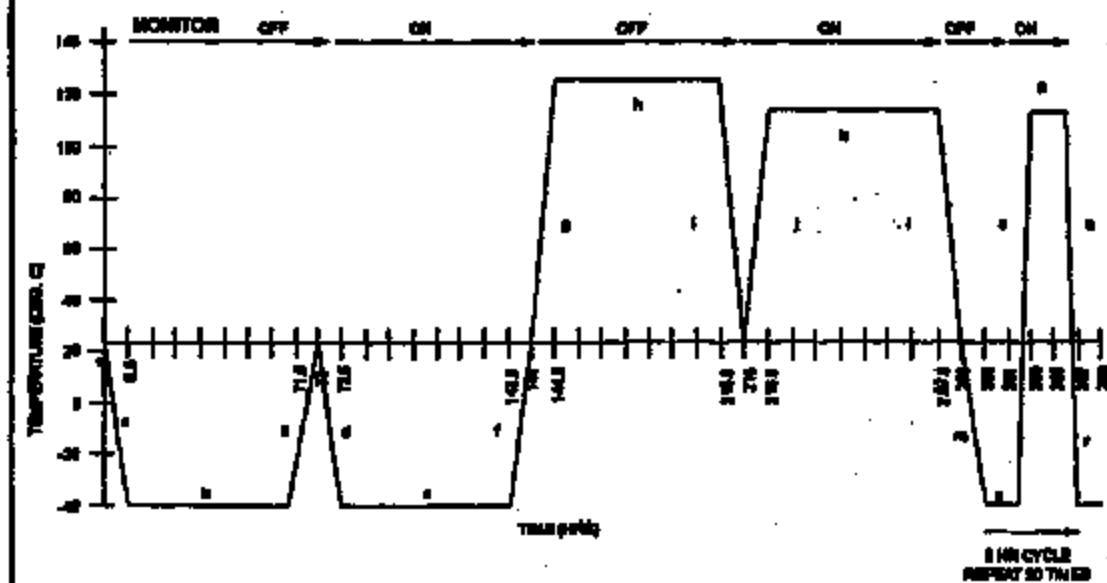
1998-00-149, P/N 5716700 DATE 8/8/91

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ES-F297-9C755-AA

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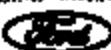
MONITORED CLIMATIC ENVIRONMENT TESTS
FIGURE 6

SEGMENT	ACTION	DURATION	CUMULATIVE TIME	MONITOR	VOLTAGE
a	Cool from 25°C to -40°C	0.5	0.5	off	13.25
b	Hold at -40°C	71	71.5	off	13.5
c	Heat from -40°C to 25°C	0.5	72	off	13.25
d	Cool from 25°C to -40°C	0.5	72.5	on	13.25
e	Hold at -40°C	71	143.5	on	13.5
f	Heat from -40°C to 25°C	0.5	144	on	13.25
g	Heat from 25°C to 125°C	0.5	144.5	off	13.5
h	Hold at 125°C	71	215.5	off	12.5
i	Cool from 125°C to 115°C	0.5	216	off	13.5
j	Heat from 25°C to 115°C	0.5	216.5	on	13.5
k	Hold at 115°C	71	287.5	on	12.5
l	Cool from 115°C to 25°C	0.5	288	on	13.5
m	Cool from 25°C to -40°C	1	289	off	13.25
n	Hold at -40°C	2	291	off	13
o	Heat from -40°C to 115°C	2	293	on	13.5
p	Hold at 115°C	2	295	on	12.5
q	Cool from 115°C to 25°C	1	296	on	13.5
r	(repeat a thru q 50 times)	232	232	-	-

FIGURE 6a
MONITORED CLIMATIC ENVIRONMENT TEST CYCLE

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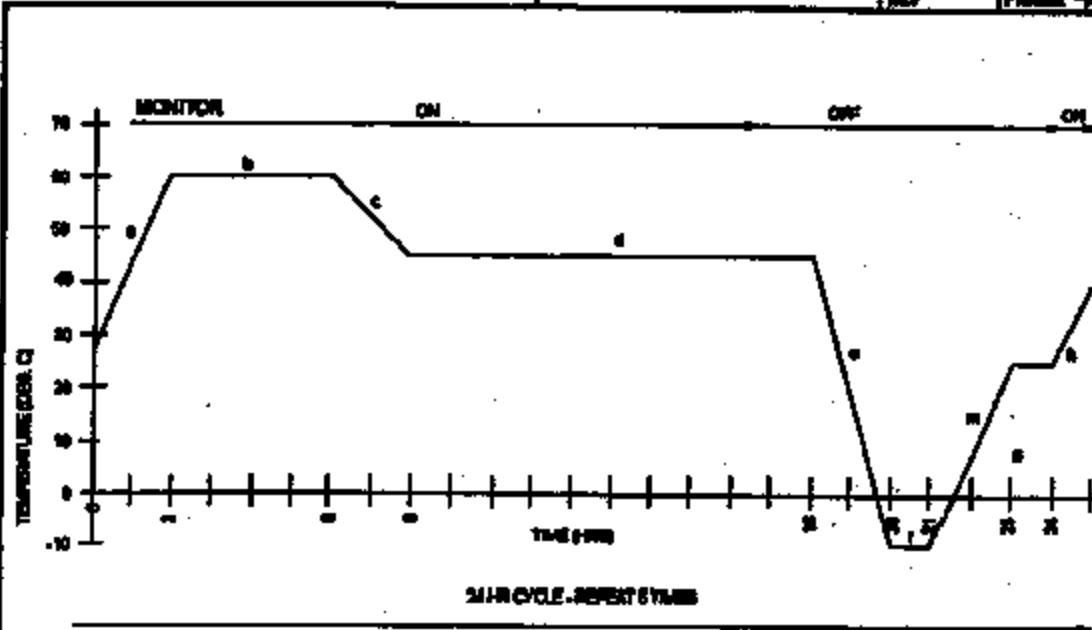
ENGINEERING SPECIFICATION

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HUMIDITY-TEMPERATURE ENVIRONMENT TEST CYCLE
FIGURE 8

ELEMENT	ACTION	RELATIVE HUMIDITY	HEAT	COLD	SWING
a	Heat from 25°C to 60°C	2	2	2	on
b	Hold at 60°C	90%	4	6	on
c	Cool from 60°C to 45°C	2	8	8	on
d	Hold at 45°C	95%	10	15	on
e	Cool from 45°C to -10°C	2	20	20	off
f	Hold at -10°C	1	21	21	off
g	Heat from -10°C to 25°C	2	23	23	off
h	Hold at 25°C	1	24	24	off
i	(repeat a thru h 3 times)	100	-	-	-

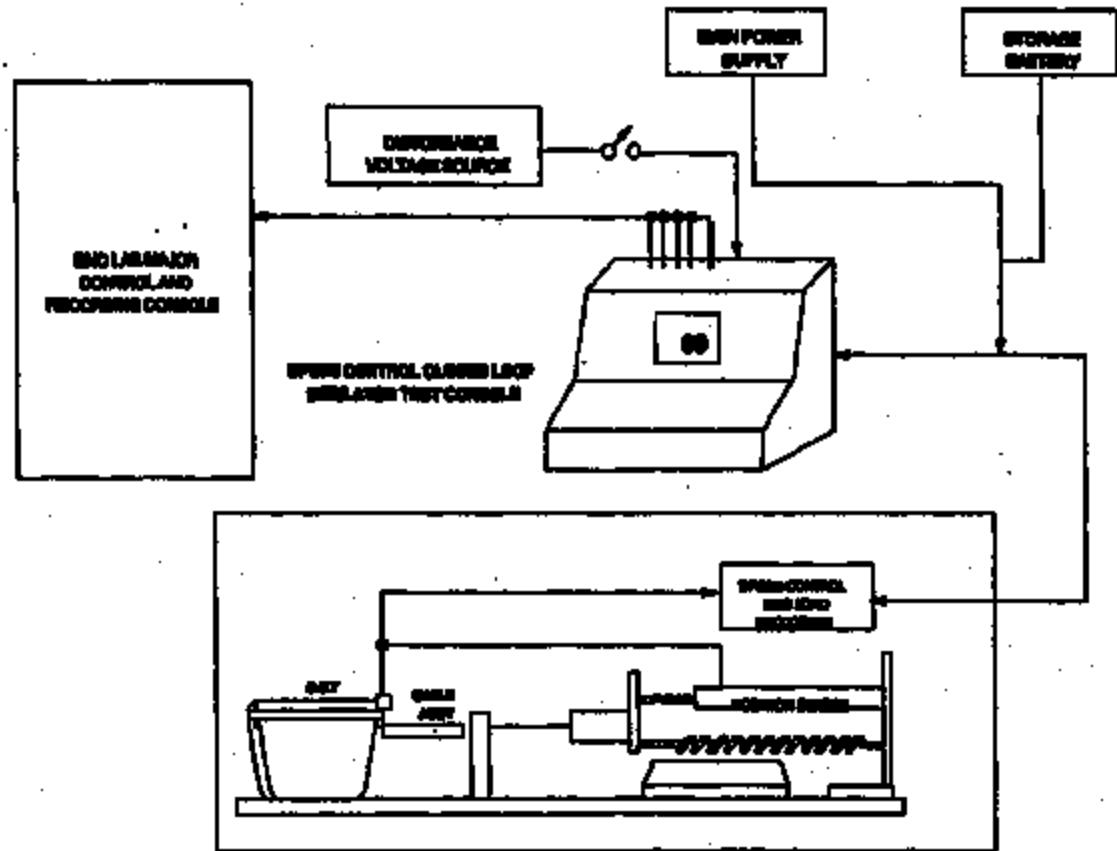
FIGURE 9a

HUMIDITY-TEMPERATURE ENVIRONMENT TEST CYCLE

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**END-SCREEN ROOM TEST CELL
FIGURE 59**

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ES-P2VZ-8C735-AA

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FIGURE 11SPEED CONTROL INITIALIZATION/SET-UP FOR EMC TESTINITIALIZATION

(Applicability: RI01-1, RI02, RI03, CI01-1A, CI01-1B, CI02-1A, CI02-1B, CI02-2, CI02-3A, CI02-3B, CI02-4, CI04, RI01, CI01)

1. Note the amplifier model type and set up the appropriate external speed signal type from the frequency generators per Figures 4, 4a, 4b, or 4c. Set at 100 Hz.
2. With the main power supply disconnected from the battery, set the power supply voltage to 12.7 +/- 0.1 Volts and the current limit set to 4 amps. Reconnect the power supply to the Speed Control Simulator Console and storage battery.
3. Turn on power to the module under test and Speed Control Console via console panel switch.
4. Momentarily depress the "SET" button and wait until the pointer on the Speed Control fixture advances, then stabilizes.
5. Adjust the pointer gage such that the pointer is in the center of the gage.
6. Adjust the video monitor so that the pointer/gage can be observed.
7. With the Speed Control set at 100 Hz, verify the main power has settled and at a steady 12.7 +/- 0.1 Volts. This settling may take a few minutes as the battery voltage stabilizes to match the power supply setting.
8. Proceed with test according to EMC specification ES-P2AF-1316-AA.

DRIVE TEST

(Applicability: RI01-1, RI02, RI03, CI01-1A, CI01-1B, CI02-1A, CI02-1B, CI02-2, CI02-3A, CI02-3B)

1. Apply "BRAKE" command from Speed Control Console and verify pointer returns to idle stop position through video monitor.

SET-UP: CI02-3 (LOAD SHIFT) CI02-4 (ROTATED SHIFT) and CI03-1 (REVVERSE PATTERN)

1. Apply Power to Pins 7, 9, Ground to Pin 10. For Family "W", also apply Power to Pin 8.

SET-UP: CI04-1 (END-DECODED)

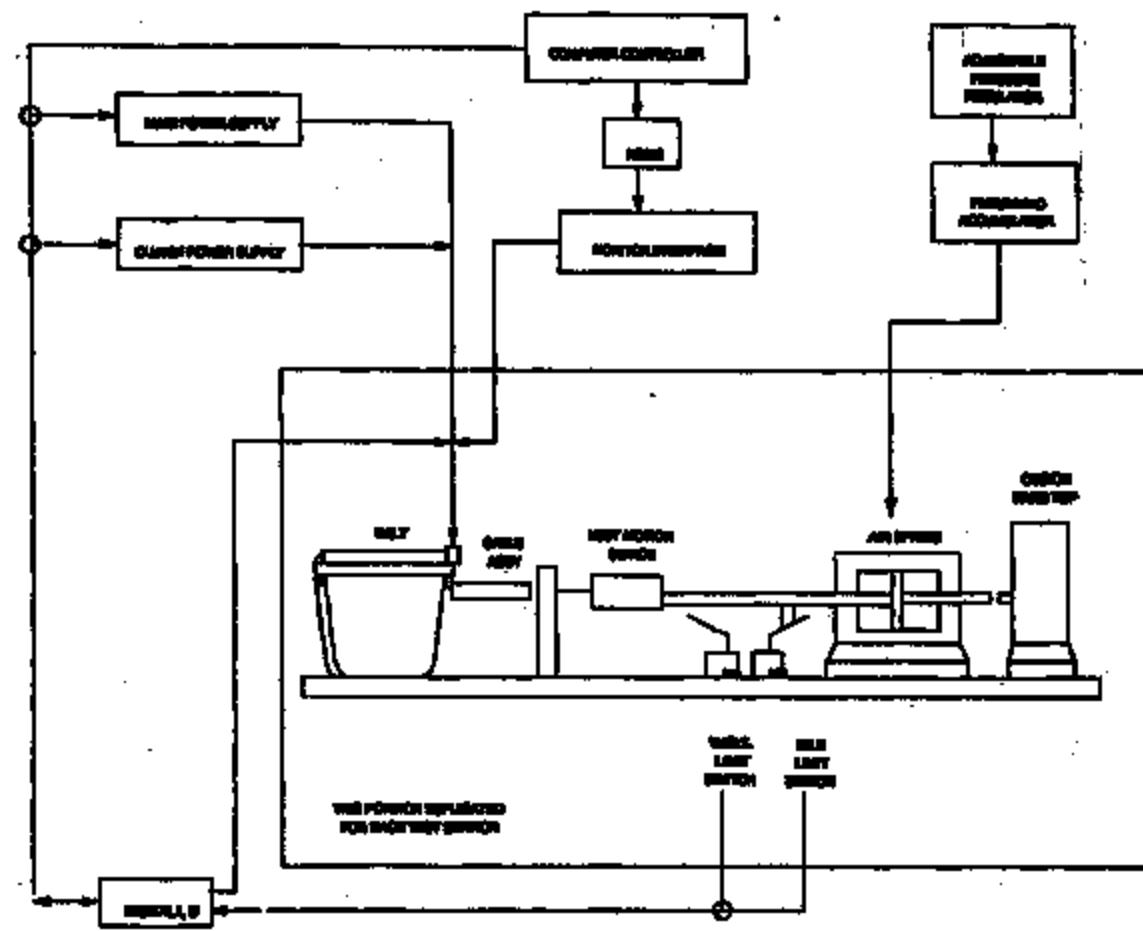
1. Discharge to 10 Pin connector only.

SET-UP: CI04-2 (END-OPERATING)

1. Discharge to Pins 5 and 6 only. For Family "W" also discharge to Pin 4.

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ANSWER



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FIGURE 11Accelerated Life Test ParametersEQUIPMENT DESCRIPTION:

- Computer Controller: Minimum - Capable of controlling two power supplies, sequencing and driving digital I/O, driving an RS232 line and transmitting an ASCII file to boot the Device Under Test (D.U.T.).
- Main Power Supply: Minimum - Preferably computer controllable, Voltage range adjustable 0 to 30V and output current capacity of 5A per test station.
- Clutch Power Supply: Minimum - Preferably computer controllable, Voltage range adjustable 0 to 30V and output current capacity of 5A per test station.
- Digital I/O: Minimum per station - Capable of driving the D.U.T. brake input and disconnecting from the brake input. Also capable of scanning the limit switches per station.
- Monitor Interface: Minimum - Capable of converting the ASCII transmission from the computer to the voltage levels needed by the D.U.T.. It must be capable of disconnecting from the D.U.T..
- Limit Switches: Two per station - One to determine the Idle position of the D.U.T. within 2mm. The other can determine the full stroke position within 2mm.
- Pressure Regulator: Note the pull force of the air spring by allowing air to flow into the system if the pressure falls below the set pressure. Note, this is a one way process. Should the pressure in the system increase, it does not allow air to back flow into the air supply. Some regulators will vent air to the atmosphere but this is a poorly regulated function and is more of a safety relief than regulation.
- Air Spring: An air cylinder having low static friction and pressurized to resist the pulling action of the D.U.T.. Using the air pressure regulator, it should have an adjustable pull force ranging from 10 to 40 pounds and a minimum usable stroke range of 3 inches.

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FIGURE 11 (cont'd)1000 Hour Accelerated Life Test ParametersEQUIPMENT DESCRIPTION (cont'd):Accumulator:

The accumulator lowers the rate of the air spring allowing it to have a near constant force over its full stroke. For example: If an air spring displaces 2 cubic inches of air and the accumulator contains 98 cubic inches of air, then the force of the spring will vary $2/(98+2)$ or 2t over the 2 inch stroke.

Also, the reservoir is used to supply the large demand for air when the D.U.T. allows the spring to snap against the hard stop/cushion. For example: If the air spring snaps into the hard stop in 10 ms and its displacement is 2 cubic inches, then the demand for air will be $2/.01 = 200$ cubic inches/second. Because of this large flow rate the line between the air spring and the accumulator should be as large as size as practical and length should be kept to a minimum. If the areas of both sides of the air cylinder are equal, then the air on the back side of the piston must be allowed to escape at the same 200 cubic inches per second rate.

Cushion/Hard Stop:

A device which prevents the air spring from transmitting static or dynamic force to the actuator when the D.U.T. is in its free deactivated position. The cushion action prevents damage to the fixture when the D.U.T. allows the air spring to snap into the hard stop position. The cushion action should occur only within 100 mils or less of the hard stop position of the fixture.

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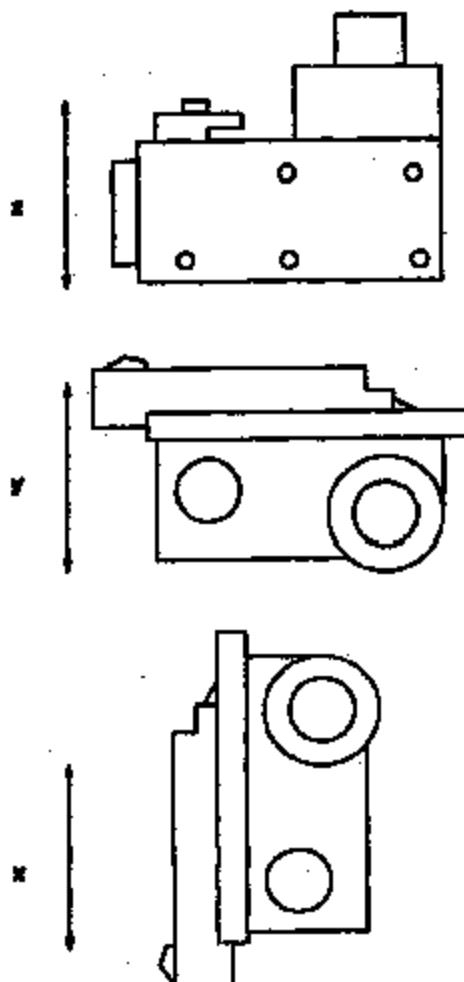
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AXIS OF VIBRATION
FIGURE 14

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FIGURE 15

BASIC FUNCTIONAL TEST DOWNLOAD CODE

BASE MODULE - P4 MICROPROCESSOR (MONITOR FILE BASEP4.MON)							
W9E3F	W9700	WA173	WB00C	WB550	WC11A	WC5CC	
W9E3F	W9887	WA246	WB003	WB648	WC121	WC120	
W9F30	W9773	WA334	WB00	WB777	WC126	WC122	
W9017	W9A46	WA420	WB00	WB837	WC202	WC20	
W9156	W9134	WA500	WB00F	WB951	WC31E	WC07K	
W9E16	W9020	WA687	WB050	WBAA0	WC450	J0060	
W9375	W9008	WA774	WB102	WBAB9	WC5DC		
W9418	W9245	WA810	WB250	WBAC8	WC600		
W9573	W9702	WA875	WB35C	WBAD0	WC728		
W9446	WA987	WA910	WB437	WB806	WC820		

BASE MODULE - P6 MICROPROCESSOR (MONITOR FILE BASEP6.MON)							
W9E3F	W9700	WA174	WB007	WB55C	WC110	WC9GA	
W9E3F	W9887	WA246	WB11F	WB637	WC006	WC120	
W9F30	W9774	WA334	WB00	WB750	WC11A	WCBCA	
W9017	W9A46	WA420	WB004	WB844	WC151	WC20	
W9157	W9134	WA500	WB00	WB977	WC216	WC200	
W9157	W9230	WA687	WB000	WBAA7	WC402	WC120	
W9376	W9008	WA775	WB10F	WBAB1	WC51E	WCFFK	
W9418	W9245	WA810	WB250	WBAC0	WC650		
W9574	W9702	WA876	WB302	WBAD9	WC726		
W9446	WA987	WA917	WB43C	WB806	WC800		

DIAGNOSTIC MODULE - P6 MICROPROCESSOR							
W9E3F	W9800	WA276	WB007	WB55C	WC050	WCAC8	
W9E3F	W9887	WA346	WB11F	WB73F	WC106	WC820	
W9F30	W9A76	WA434	WB00	WB850	WC21A	WC0CA	
W9117	W9246	WA520	WB00A	WB948	WC351	WC20	
W9230	W9034	WA600	WB000	WBAA7	WC426	WCED0	
W9316	W9020	WA787	WB10D	WBAB7	WC502	WCFF0	
W9478	W9006	WA877	WB20Y	WBAC1	WC61E	WC0FF	
W9518	W9745	WA910	WB350	WBAD0	WC730	J0062	
W9678	WA002	WA978	WB402	WBAD6	WCEDC		
W9746	WA187	WA94F	WB43C	WB806	WC900		

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EXHIBIT 16

2000 FORTRESS INTEGRITY TEST DOWNLOAD CODE

FAMILY C,F,G (BASIC) MODULE - P6 MICROPROCESSOR

FAMILY D (DIAGNOSTIC) MODULE - P6 MICROPROCESSOR

FAMILY E (MAZDA) MODULE - P6 MICROPROCESSOR

FAMILY F (ECU) MODULE - P6 MICROPROCESSOR

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FIGURE 17

SERVO ACCELERATED LIFE TEST DOWNLOAD CODE

BASE MODULE - 34 MICROPROCESSOR (MONITOR FILE A3T5.HEW)							
W9017	W993F	WA5FA	WB126	WC027	WCRA6	WD5B1	WE120
W9856	WRA74	WA617	WB2FB	WC074	WCAD0	WD6A3	WE2AC
W97AD	W97AD	WA775	WB316	WC07D	WCAB7	WD726	WE310
W9102	W9246	WA818	WB475	WC122	WCDB3	WD8F0	WE40C
W9182	W9203	WA875	WB5AD	WC102	WCDA5	WD9B6	WE50B
W9290	W9208	WA916	WB620	WC200	WCDE0	WD9A4	WE573
W93FB	W9FF9	WA900	WB7A6	WC37B	WCDF7	WD8B1	WE7FB
W94AD	W9AD0	WA9AE	WB801	WC4AD	WD074	WDCB4	WE81D
W95AD	WA1A1	WA9D2	WB8B7	WC51D	WCDA0	WD826	WE975
W9602	WA230	WA9AD	WB973	WC622	WD210	WDEEA	WEA81
W9700	WA3B4	WA9F3	WBAA6	WC700	WD3B5	WD917	JD00D
W98P6	WA426	WB05A	WBCE0	WC8F6	WD473	WD800	

BASE MODULE - 36 MICROPROCESSOR (MONITOR FILE P3A0T5.HEW)							
W9017	W993F	WA5FA	WB126	WC027	WCRA6	WD5B1	WE120
W9857	WRA75	WA617	WB2FB	WC075	WCAD1	WD6B6	WE2AC
W97AD	W97AD	WA775	WB316	WC07D	WCAB7	WD726	WE34F
W9052	W9C46	WA818	WB476	WC122	WC74	WD8F0	WE4C7
W9103	W9D04	WA876	WB5AD	WC102	WCDA5	WD9B6	WE51F
W9200	W9E06	WA918	WB62C	WC200	WC510	WD9A4	WE6F0
W93FB	W9FF9	WA900	WB7A6	WC37B	WCDF7	WD8B1	WE7FB
W94AD	W9AD0	WA9AE	WB801	WC4AD	WD075	WDCB7	WE874
W95AD	WA1A1	WA9D2	WB8B7	WC51D	WCDA0	WD826	WE9F9
W9602	WA230	WA9AD	WB974	WC622	WD210	WDEEA	WEA1D
W9700	WA3B7	WA9F3	WBAA6	WC700	WD3B5	WD917	JD176
W98P6	WA426	WB05A	WBCE0	WC8F6	WD474	WD800	WEA81

DIAGNOSTIC MODULE - 36 MICROPROCESSOR							
W9017	W9A3F	WA5FA	WB2AD	WC005	WCAB6	WD6B6	WE2G7
W9859	W9B77	WA717	WB32D	WC000	WC50	WD777	WE31F
W97AD	W9CAD	WA878	WB4A6	WC0F6	WCDB7	WD9B1	WE4F0
W914F	W9D43	WA918	WB501	WC1AD	WC77	WD9B9	WE50D
W9208	W9E04	WA978	WB6B7	WC21E	WC8AD	WD9A6	WE678
W9300	W9F00	WA9CD	WB776	WC308	WCFL1	WD9EA	WE7F9
W9478	W9OFF	WA901	WB8A6	WC400	WD0B6	WCC0	WE81D
W95AD	WA1A0	WA911	WB9E0	WC5F6	WD176	WD001	WE978
W96AA	WA232	WA9AD	WB9B7	WC6A5	WD281	WDEEA	WEA81
W9708	WA310	WA9F1	WBAA6	WC701	WD3B5	WD920	JD00D
W9800	WA482	WB016	WBCE0	WC8F7	WD426	WEA8F	
W99P6	WA526	WB178	WBCE0	WC976	WD5FU	WE1AF	

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EXHIBIT 1A

MONITORING DURABILITY L/C DEFINITION

I/O DEFINITION		
INPUT/OUTPUT	VALUE	
B - Brake	I = Logic Low Ind. Lamp = OFF	H = Logic High Ind. Lamp = ON
A = Speed	I = Logic Low	H = Logic High
C = On/Off Switch (FAMILY "W" ONLY)	I = Logic Low	H = Logic High
D = De-Activator Switch	I = Logic Low	H = Logic High
J = Clutch Switch (FAMILY "W" ONLY)	I = Logic Low	H = Logic High
G - Command Switch	A/B Conversion of Command Input: 00h to 4Fh = "CANCEL" 4Fh to AFh = "REV/COAST" (240 deg) AFh to Dah = "REVERSE/ACCEL" DHh to FFh = "REV" Command (open circ) FFh to FFh = "FAIL"	

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ENGINEERING SPECIFICATION

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PHONE 10 Test 3.3.1.2 Software Version Facility A,B,C			PHONE 10a Test 3.3.1.2 Software Version Facility D	PHONE 10b Test 3.3.2.2 Software Version Facility E	PHONE 10c Test 3.3.2.2 Software Version Facility F
Am. Date	Month	Am. Date	Month	Am. Date	Month
01	JAN	01	JAN	01	JAN
02	FEB	02	FEB	02	FEB
03	MAR	03	MAR	03	MAR
04	APR	04	APR	04	APR
05	MAY	05	MAY	05	MAY
06	JUN	06	JUN	06	JUN
07	JUL	07	JUL	07	JUL
08	AUG	08	AUG	08	AUG
09	SEP	09	SEP	09	SEP
10	OCT	10	OCT	10	OCT
11	NOV	11	NOV	11	NOV
12	DEC	12	DEC	12	DEC

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VINTAGE ENGINEERING SPECIFICATION

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PART NAME SPECIFICATION - SPEED CONTROL ASSEMBLY												PART NUMBER BL-E2VP-9A819-AA												
DET	C	C	C	C	C	C	C	C	C	C	C	C	C	C	C	C	C	C	C	C	C	C	C	
FR	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17							
DET	C	C	C	C	C	C	C	C	C	C	C	C	C	C	C	C	C	C	C	C	C	C	C	
FR	18	19	20	21	22	23	24	25	26	27	28	29	30	31										
DET																								
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DET																								
FR																								
DATE	REV	BY	REVISIONS												DR	CR	RESPONSIBILITY							
			C. WEBER (313) 845-1495														REVIEWED/APPROVED BY							
910404			PROD REL DE900-X-10023510-000														CONTRACTOR APPROVED SIGNATURES							
	A		ALL REVISED AND RENUMBERED FRAMES														CHECKED BY DESIGNED BY							
	A		C. WEBER (313) 845-1495														(ON FILE)							
911111	A		C-10154393														CONTRACTOR APPROVED SIGNATURES							
	B		REVISED TO AGREE WITH S.R.E.A.'S 6 RENUMBERED FRAMES 9-31														DESIGN ENGINEER APPROVED SIGNATURES							
	B		D. PORTER (313) 390-8674														(ON FILE)							
940913	B		PROD REL DE900-X-00107002-197														MANUFACTURING ENGINEER APPROVED SIGNATURES							
	C		REL 904000, REVISED AND RENUMBERED														(ON FILE)							
	C		D. PORTER (313) 390-8674														MANUFACTURING ENGINEER APPROVED SIGNATURES							
490373	C		REL DE900-X-1002356-000														(ON FILE)							
																	QUALITY CONTROL APPROVED SIGNATURES							
																	PURCHASING APPROVED SIGNATURES							
																	SUPPLIER QUALITY ASSISTANCE APPROVED SIGNATURES							
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 - b. Coil Resistance
 - c. Dynamic Surge Test
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 - e. Release voltage
 - f. Clutch Clamping Force
 - g. Output Gear
 - h. Bobbin
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 - b. Electrical Isolation
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 - c. Motor Dynamic Torque
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 - a. Dielectric Test
 - b. Dynamic Surge Test
 - c. Pull in voltage
 - d. Release voltage
 - e. Output Gear
 2. Stator
 - a. Electrical Isolation
 - b. Phase Resistance
 - c. Dynamic Surge Test

TABLE OF CONTENTS (cont'd)**3 TEST PROCEDURES AND REQUIREMENTS (cont'd)**

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4 REVALIDATION REQUIREMENTS**5 INSTRUCTIONS AND NOTES**

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- B. Lot Definition
- C. Test Reporting and Record Retention
 - 1. Production Validation
 - 2. In-Process
 - 3. Test Report Contents
- D. Test Correlation
- E. Returns - ELD/Body & Assembly Division/Field
- F. Traceability
- G. Repairs
 - 1. Definition
 - 2. Procedure

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TABLES

- Table 1

1 GENERAL

This specification governs the speed control assembly. The actuator subassembly is comprised of a housing with integrated motor, a clutch assembly gears and cable pulley.

This Engineering Specification is a supplement to the released drawing on the released part, and all requirements herein must be met in addition to all other requirements of the part drawing. Minimum measures necessary for demonstrating compliance to these requirements are given in each section.

The Engineering Specification is intended to evaluate specific characteristics as a supplement to normal material inspections dimensional checking, and in-process controls, and should in no way adversely influence other inspection operations.

Preparation and submission of an acceptable Control Plan are the responsibility of the manufacturing source. Control Plan approval by the Component Engineering and Manufacturing Operations and by other activities according to QS-9000 is a prerequisite for initial sample review and approval. The manufacturing source will retain the original of the approved Control Plan and any later revisions per QS-9000 and provide a copy to the design responsible CEMO.

2 SUMMARY OF PRODUCTION VALIDATION AND IN PROCESS TESTS

Production Validation (PV) tests are used to obtain an initial estimate of the process potential to produce parts that conform the engineering requirements, and to identify causal or predictive relationships between significant design and process characteristics (to be used for process control). These tests must be completed satisfactorily using initial parts from production tooling and processes before Initial Sample Report (PSR) approval and authorization of production parts can be issued. Sampling plans for PV testing must be included in the Control Plan.

In-Process (IP) tests are used to further understand the relationship between significant design and process characteristics and to establish a basis for continuing improvement. Tests must be completed with production parts on an ongoing basis. Sampling plans for both IP testing and evaluation of the significant process characteristics must be included in the Control Plan. When the process is found to be out of control or the test acceptance criteria are not met, the reaction plan approved in the Control Plan shall be invoked.

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PRODUCTION VALIDATION AND IN-PROCESS TESTS
FIGURE 1

TEST NUMBER	TEST CHARACTERISTIC	TEST TYPE	TEST LIMITS OVER SPECIFIED TEMPERATURE			MINIMUM COMPONENT SO TOLERANCE	SPECIFIED SAMPLE SIZE /FREQUENCY
			MIN	TARGET	MAX		
	Lot Control:						
III.B	Functional Tests						
III.B.1	Clutch Assembly Functional	PV/EP					
III.B.1.a	Dielectric Test		-	-	95	mΩ	2/
III.B.1.b.1	Coil Resistance at 25°C	23.5	-	25.4	ohm	Cpk > 1.33	
III.B.1.b.2	Coil Resistance at -40°C	-4	B	+4	t		2/
III.B.1.b.3	Coil Resistance at +150°C	-4	B	+4	t		2/
III.B.1.c	Dynamic Surge Test		-	B	-	R/F	2/
III.B.1.d	Pull in voltage (-40°C)		-	-	5.2	V	Cpk > 1.33
	Pull in voltage (25°C)		-	-	7.0		
	Pull in voltage (150°C)		-	-	16.4		
III.B.1.e	Release voltage	50	300	-	607		2/
III.B.1.f	Clutch Clamping Force	89.0	104.0	-	t	Cpk > 1.33	
III.B.1.g	Output Gear		-	F	-	R/F	2/
III.B.1.h	Bobbin		-	F	-	R/F	2/
III.B.2	Grove Functional Tests	PV/EP					
III.B.2.a	Antibacklash Gear		-	F	-	R/F	2/
III.B.2.b	Electrical Isolation	50	-	-	MΩ		1/
III.B.2.c.1	Phase Resistance at 25°C	2.30	2.65	2.81	ohm	Cpk > 1.33	
III.B.2.c.2	Phase Resistance at -40°C	-4	0	+4	t		2/
III.B.2.c.3	Phase Resistance at +150°C	-4	0	+4	t		2/
III.B.2.c.4	Phase - Phase Ohmic Variance		-	0.0	0.11	ohm	Cpk > 1.33
III.B.2.d	Inductance at 1 KHz	7.5	9.5	11.5	nH	Cpk > 1.33	
III.B.2.e	Minimum Pull Voltage		-	-	9.5	V	2/
III.B.2.f	Maximum Stroke Test	177	178	179	Deg.		2/
III.B.2.g	No Load Deactivate to Idle	-3.0	0	+3.0	Deg.		2/
III.B.2.h	Full Load Deactivate to Idle	-9.0	0	+3.0	Deg.		2/
III.C	Audit tests						
III.C.1	Clutch Tests	PV/EP					10%
III.C.1.a	Pull in voltage				7.0	V	Cpk > 1.33
III.C.2	Motor/Housing Assembly	PV/EP					10%
III.C.2.a	Inductance at 1 KHz.		7.5	9.5	11.5	nH	Cpk > 1.33
III.C.2.b	Motor Static Torque	23.5	27.0	30.5	oz-in	Cpk > 1.33	5/hr
III.C.2.c	Motor Dynamic Torque		16.0		21.0	oz-in	1/

1/ Capability to be within 3 SIGMA of tolerance limit.

2/ GO/NO-GO type test - all must pass

* It is strongly recommended that ES test sample sizes and frequencies be developed by the manufacturer, with concurrence by the OEMO, and documented in the Control Plan.



PRODUCTION VALIDATION AND IN-PROCESS TESTS
FIGURE 1 - (cont'd)

TEST NUMBER	TEST CHARACTERISTIC	TEST TIME	TEST LIMITS OVER-SPECIFIED REQUIREMENTS			MINIMUM CONFORMANCE TO TOLERANCE	RECOMMENDED SAMPLE SIZE /FREQUENCY
			MIN	TARGET	MAX		
III.D	100% In-process Tests						
III.D.1	Clutch Tests	PW/IP					100%
III.D.1.a	Dielectric Test		-	-	95 mA	2/	
III.D.1.b	Dynamic Surge Test		-	P	-	2/	
III.D.1.c	Fall in voltage		-	-	7.0 V	2/	
III.D.1.d	Release voltage	100	-	-	87	2/	
III.D.1.e	Output Gear		-	P	-	P/T	2/
III.D.2	Stator	99/IP					100%
III.D.2.a	Hi Pot		-	1000	-	Volts	2/
III.D.2.b.1	Phase Resistance	2.3	2.55	2.81	ohm	2/	100%
III.D.2.b.2	Phase - Phase Charge Variance		-	-	0.11 ohm	2/	
III.D.2.c	Dynamic Surge Test		-	P	-	P/T	2/
III.D.3	MOTOR/Rolling Assembly	PW/IP					100%
III.D.3.a	Inductance at 1 kHz		7.5	-	11.5 mA	2/	
III.D.3.b	Motor Static Torque	23.5	27.0	30.5	oz-in	1/	5/hr
III.D.3.c	Dielectric Test		-	-	1.0 mA	2/	
III.D.4	Actuator Assembly	PW/IP	-4	0	+4	0	2/
	End of Line Tests						2/
III.D.4.a	Electrical Isolation		5	-	-	Mohm	1/
III.D.4.c	Minimum Full Voltage		-	-	9.5 V	2/	
III.D.4.d	Maximum Stroke Test	177	178	179	Deg.	2/	
III.D.4.e	No Load Reactivates to Idle	-3.0	0	+3.0	Deg.	2/	
III.D.4.f	Full Load Reactivates to Idle	-3.0	0	+3.0	Deg.	2/	
III.D.4.h	Rotor Run Test		-	4.0	-	g	2/
III.E	Durability Tests						
	Lot Control						
III.E.1	6 Hour Accelerated Life Test	PW/IP	-	P	-	P/T	2/
							6/shift/ft/wk
	Audit						
III.E.2	Humidity Test	PW/IP	-	P	-	P/T	2/
III.E.3	Phase Resistance		2.30	2.55	2.81	ohm	Cpk > 1.33

1/ Capability to be within 3 SIGMA of tolerance limit.
2/ GO/NO-GO type test - all must pass

* It is strongly recommended that EG test sample sizes and frequencies be developed by the manufacturer, with concurrence by the OEM, and documented in the Control Plan.

3 TEST PROCEDURES AND REQUIREMENTS**A. General**

Every Speed Control Servo assembly or subassembly shall be capable of passing the Functional, Production Validation, In-Process and End of Line Test specified. Factory ambient tests shall be conducted at 25°C ± 5°C. In addition to all the tests specified herein, all actuator assemblies P2VF-9A819, must meet the Speed Control Actuator final assembly (electronics installed) specification NS-P2VF-9C735-AA.

B. Functional Tests**Three Temperature Functional (-40°C, 25°C, 150°C)**

Unless otherwise specified, assemblies must meet this specification in the temperature range of -40°C to 150°C. Sample testing must be performed at -40°C, 25°C, and 150°C ambient. Unless the procedure itemized below is used, the environmental chamber soak time when performing functional tests at temperature extremes shall be 2 hours. This allows the servo to stabilize at the final test temperature for most chamber capacities and loading. The limiting factor being the chamber cooling capacity when fully loaded.

The soak time in the QC audit area may be reduced for three temperature functional testing if the time required to reach the temperature extremes, both hot and cold, is determined using a thermocouple type thermometer and a thermocoupled sample module. Procedure:

- Prepare a test sample module by drilling and tapping a #6-32 thread in an area of the module casting having the thickest cross section next to the motor. (This test sample should be saved for future use.)
- Using a #6-32 screw and washer, clamp a thermocouple under the washer firm against the module. (Alternate methods for attachment are not permitted).
- Load the chamber with the necessary fixtures, the maximum number of modules to be tested including the temperature verification module having the threaded hole in the casting and the thermocouple clamped using a screw and washer. Be sure the module containing the thermocouple is mounted at the station closest to the door.
- Record the time required for the verification module to stabilize within 2 degrees of final value.
- Take the stabilization times for hot and cold and adjust by multiplying each by 1.1 to account for unknown factors that will occur during normal testing.
- Use the adjusted time as the soak requirement. Post the soak time and date of validation and date of next revalidation on the front of the test equipment. Submit the adjusted soak times to CEMO.

The chamber soak time must be revalidated as follows:

- Every 6 months
- If any chamber service is done to correct a chamber problem,
- If the thermal loading of the chamber is increased (more things added to chamber since the last time Validated),
- If a different chamber is used.

3 TEST PROCEDURES AND REQUIREMENTS (cont'd)

B. Functional Tests (cont'd)

1. Clutch Subassembly Functional Test (reference Figure 3)

Passive tests (-40°C, 25°C and 150°C)

Use an external clamp to close the clutch so the drive teeth are meshed together resulting in the minimum air gap and verify these electrical parameters.

a. Dielectric test (25°C Only)

This test is designed to measure dielectric strength of the clutch and is sometimes referred as a "HIPOT" test.

Make an electrical connection across one lead of the clutch and the clutch shaft. Apply 1500 volts, 60 Hz a.c. to the connection and measure the resultant current flow. The high voltage stimulus is not to exceed a duration of 1 second.

b. Coil Resistance

The measurement method below verifies the integrity of the part at three temperatures as well as the sample temperature when the data is collected. If the test sample is defective or the test temperature is incorrect, the result will be out of specified limits.

1. With the coil at 25°C, measure and record the resistance.

2. With the coil temperature at -40°C, calculate the test result using:

$$\text{Result} = \frac{(R_{-40^\circ\text{C}} \times 1.334 - R_{25^\circ\text{C}})}{(R_{25^\circ\text{C}})} \times 100$$

Where:

1) R-40°C is the coil resistance measurement at -40°C

2) R25°C is the resistance value recorded at test III.B.1.b.1

3. With the coil temperature at 150°C, calculate the test result using:

$$\text{Result} = \frac{(R_{150^\circ\text{C}} \times 0.675 - R_{25^\circ\text{C}})}{(R_{25^\circ\text{C}})} \times 100$$

Where:

1) R150°C is the coil resistance measurement at 150°C

2) R25°C is the resistance value recorded at test III.B.1.b.1

3 TEST PROCEDURES AND REQUIREMENTS (cont'd)**B. Functional Tests (cont'd)****1. Clutch Subassembly Functional Test (cont'd)****c. Dynamic Surge Test (25°C Only)**

Use a Slaughter Co. Model 1640-1.5 Dynamic Surge Tester for this test. This test verifies consistency in the device magnetics and is most sensitive to detection of shorted turns. It is a GO/NO-GO type test calibrated using GO/NO-GO masters.

Gage Masters

The GO and the NO-GO calibration masters are to be verified as dimensionally correct. The GO master is to be verified magnetically and electrically correct using a high voltage RF inductance meter. The NO-GO master shall be constructed to contain 30 shorted turns. The specific details for construction of these masters is the responsibility of the supplier and documentation to be available to Ford ELD upon request.

Calibration

Calibrate the Slaughter Model 360 using the provided Phase and Balance controls to consistently pass the GO master and reject the NO-GO master. The transient wave form of the GO master is to be digitally stored in the tester memory for use during the normal test cycle. The tester reject limits must be verified to consistently reject a part containing 30 shorted turns.

Stimulus

Stimulate the part under test using a single 500 volt, 1 millisecond impulse. The test equipment will automatically compare the tested part transient wave form to the digitally stored wave form produced by the "GO" master during calibration. The deviation in the wave form shall be less than the "NO-GO" master containing 30 shorted turns.

Active Tests (-40°C, 25°C and 150°C)**d. Pull in voltage**

Apply a voltage to the clutch terminal contacts at a rate of 0.5 volts per second and record the voltage the clutch engages.

e. Release voltage

1. To initialize the clutch magnetics, energize the coil to $16.0 \pm .1$ volts and verify the output gear engages with the pole piece face teeth and is fully clamped.

2. With the face teeth fully engaged, reduce the voltage to 50 ± 1 mV, the clutch must release within 250ms

f. Clutch Clamping Force (Performed at Factory Ambient Temperature Only)

1. Energize the clutch coil to 287 ± 1 mA and verify the output gear engages with the pole piece face teeth and is fully clamped.

2. Apply an external force to the rim of the output gear. Record the peak force required to separate the output gear from the pole piece.

3 TEST PROCEDURES AND REQUIREMENTS (cont'd)

B. Functional Test (cont'd)

1. Clutch Subassembly Functional Test (cont'd)

Free Motion Tests (performed at -40°, 25° and 150°C)

The clutch assembly contains three parts which must demonstrate free relative motion. These are the output gear, coil bobbin, and shaft/pole piece.

a. Output Gear

When de-energized, the output gear must freely rotate 360 degrees relative to the output shaft.

b. Bobbin

The bobbin connector, relative to the shaft flat, must freely rotate 180 degrees with the clutch energized to 16 volts.

2. Servo Three Temperature Functional Tests (-40°C, 25°C, 150°C)

Passive tests

a. Antibacklash Gear (Performed at Factory Ambient Temperature Only)

Antibacklash gear bias springs are to be checked for correct installation.

b. Electrical Isolation (25°C Only)

Electrical isolation from phases to shaft to be checked at 500 volts DC.

c. Phase Resistance.

The measurement method below verifies the integrity of the part at three temperatures and well as the sample temperature when the data is collected. If the test sample is defective or the test temperature is incorrect, the result will be out of specified limits.

1. With the motor at 25°C, measure and record the resistance of phase A.

2. With the motor temperature at -40°C, calculate the phase A test result using:

$$\text{Result} = \frac{(R_{-40^\circ\text{C}} \times 1.334 - R_{25^\circ\text{C}})}{(R_{25^\circ\text{C}})} \times 100$$

Where:

1) R-40°C is the phase resistance measurement at -40°C

2) R25°C is the resistance value recorded at test III.B.2.c.1.

3. With the motor temperature at 150°C, calculate the Phase A test result using:

$$\text{Result} = \frac{(R_{150^\circ\text{C}} \times 0.675 - R_{25^\circ\text{C}})}{(R_{25^\circ\text{C}})} \times 100$$

Where:

1) R150°C is the phase resistance measurement at 150°C

2) R25°C is the resistance value recorded at test III.B.2.c.1.

Repeat for phases B and C.

4. Check the phase to phase resistance variance.

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3 TEST PROCEDURES AND REQUIREMENTS (cont'd)**B. Functional Test (cont'd)****2. Servo Three Temperature Functional Tests (cont'd)****d. Inductance at 1 kHz (Series Method) (25°C only)**

Align the motor shaft in the phase A detent position and measure phase A inductance. Repeat for phases B and C.

Three Temperature Active Tests (-40°C, 25°C, 150°C):

Setup the gearbox assembly with output shaft position sensor and load as shown in figure 4 and perform the following set of tests. Be sure an axial load of 22+2N is transferred to the actuator output pulley per figure 4, all motor stepping sequences are executed exactly per Figures 6A & 6B and the power drive suppression circuits are the same as shown in Figure 5.

a. Minimum Pull Voltage:

1. With the actuator output shaft unloaded and clutch disengaged, save the shaft angular position for use in the "No Load deactivate to Idle" test III.B.2.g.

2. Apply a load to the actuator as shown in Figure 7, keep the clutch disengaged, and save the output shaft position for use in test III.B.2.e.9.

3. Power up the clutch using a constant current source set for 287 ± 1 ma and dwell 150ms minimum to allow time for the clutch to close.

4. Set the motor supply voltage to 14 ± 0.1 volts.

5. To pickup the load and minimize all lash within the actuator assembly and test equipment, advance the output shaft angle making an initial move of 50 motor steps per starting/stopping phase stepping sequences of Figures 6A and B. Save the output shaft angle for use in test III.B.2.e.8.

6. Reduce the motor supply voltage to $9.5 \pm .05$ volts.

7. Advance the motor shaft 50 steps per starting/stopping phase stepping sequences of Figures 6A and B.

8. Measure the angular rotation of the loaded output shaft. To verify there were no step errors, for each 50 steps, the angle of rotation must be $18.65^\circ \pm 0.75^\circ$.

f. Maximum Stroke Test:

Continuing from the "minimum Pull Voltage" test III.B.2.e.9, return the motor supply to 14 ± 0.1 volts and verify the maximum allowable angular displacement from the idle position is attainable. The shaft angle measurement is to be referenced to the saved reading in test step III.B.2.e.2. The steps required to achieve full stroke should be calculated. It is not intended that the actuator be driven into the internal high end hard stop by the motor. Calculate the required number of steps using:

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3 TEST PROCEDURES AND REQUIREMENTS (cont'd)**B. Functional Test (cont'd)****2. Servo Three Temperature Functional Tests (cont'd)****Three Temperature Active Tests (-40°C, 25°C, 150°C):****f. Maximum Stroke Test (cont'd)**

$$\text{Steps} = \left\lceil \frac{\text{Upper Spec. - Total angle from Headed limit}}{\text{III.B.2.e.9}} \right\rceil \times 2.001$$

g. No Load Deactivate to Idle:

Continuing from the "Maximum Stroke" test III.B.2.f., remove the load from the actuator.

Remove power from the motor and clutch and verify the internal actuator return spring moves the output to the idle position saved in test III.B.2.e.1.

h. Full Load Deactivate to Idle:

1. Power up the clutch using a constant current source set for 287 ± 1 mA and dwell 150ms minimum to allow time for the clutch to close.

2. Apply a load to the gearbox as shown in Figure 7 and save the shaft position of the actuator with the output shaft loaded and clutch disengaged for use in test III.B.2.h.4.

3. Advance the motor shaft 74 steps per starting/stopping phase stepping sequences of Figures 6A and B. Check for the actuator to advance a minimum of 13°.

4. Reduce the clutch current to 15 ± 1 mA and check for the actuator to return to the idle position. Measure and record this position referenced to the reading of test III.B.2.h.2.

3 TEST PROCEDURES AND REQUIREMENTS (cont'd)**C. Audit Tests****1. Clutch Subassembly Audit Test (reference Figure 3)
(Performed at Factory Ambient Temperature)****a. Pull in voltage**

Apply a voltage to the clutch terminal contacts at a rate of 0.5 volts per second and record the voltage the clutch engages.

**2. Motor/Housing Assembly Audit Tests
(Performed at Factory Ambient Temperature)****a. Inductance at 1 kHz (Set Inductance Meter for Series Connection)**

Align the motor shaft in the phase A detent position and measure the phase A inductance. Repeat for phases B and C.

b. Motor Static Torque

Apply 2 + 0.05 amps to phase A. Measure and record the peak torque developed at the motor shaft. Repeat for Phases B and C.

c. Motor Dynamic Torque

This test certifies the motor dynamic torque as assembled in the housing. Because the developed motor torque is dependent on motor speed and drive circuit, the motor stepping sequences are to be executed exactly per Figures 5A and the power drive suppression circuits are the same as shown in Figure 5.

With reference to Figures 5 and 6A, use a supply voltage of 13+0.1 volts. Step the motor at constant speed as indicated in figure 6A and apply a torque load to the motor output shaft. Measure the pull out torque by increasing the torque load until a stepping error occurs. Record the developed pull out torque.



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3 TEST PROCEDURES AND REQUIREMENTS (cont'd)

D. In-Process Tests (Performed at 22°C)

1. Clutch In-Process Tests (cont'd)

a. Dielectric test

This test is designed to measure dielectric strength of the clutch and is sometimes referred as a "HIROF" test.

Make an electrical connection across one lead of the clutch and the clutch shaft. Apply 1500 volts, 60 Hz a.c. to the connection and measure the resultant current flow. The high voltage stimulus is not to exceed a duration of 1 second.

b. Dynamic Surge Test

Use a Slaughter Co. Model 1646-1.5 Dynamic Surge Tester for this test. This test verifies consistency in the device magnetics and is most sensitive to detection of shorted turns. It is a GO/NO-GO type test calibrated using GO/NO-GO masters.

Gage Masters

The GO and the NO-GO calibration masters are to be verified as dimensionally correct. The GO master is to be verified magnetically and electrically correct using a high voltage RF inductance meter. The NO-GO master shall be constructed to contain 30 shorted turns. The specific details for construction of these masters is the responsibility of the supplier and documentation to be available to Ford NLD upon request.

Calibration

Calibrate the Slaughter Model 360 using the provided Phase and Balance controls to consistently pass the GO master and reject the NO-GO master. The transient wave form of the GO master is to be digitally stored in the tester memory for use during the normal test cycle. The tester reject limits must be verified to consistently reject a part containing 30 shorted turns.

Stimulus

Stimulate the part under test using a single 500 volt, 1 millisecond impulse. The test equipment will automatically compare the tested part transient wave form to the digitally stored wave form produced by the "GO" master during calibration. The deviation in the wave form shall be less than the "NO-GO" master containing 30 shorted turns.

Active Tests.

c. Pull in Voltage

Apply 7 ± 0.1 Volts DC and verify the clutch engages.

d. Release voltage

1. To initialize the clutch magnetics, energize the coil to $16.0 \pm .1$ Volts and verify the output gear engages with the pole piece face teeth and is fully clamped.

2. With the face teeth fully engaged, reduce the voltage to 140 ± 1 mV, the clutch must release instantly

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3 TEST PROCEDURES AND REQUIREMENTS (cont'd)**D. In-Process Tests (cont'd)****1. Clutch In Process Tests (cont'd)****Free Motion Tests**

The clutch assembly contains three parts which must demonstrate free relative motion. These are the output gear, coil bobbin, and shaft/pole pieces.

e. Output Gear

When de-energized, the output gear must freely rotate 360 degrees relative to the output shaft.

2. Stator (Performed at Factory Ambient Temperature)**a. Electrical Isolation**

Hi Pot test at 1000 VAC and 95 mA for one second duration

b. Phase Resistance

1. Resistance value to be checked for each of the three phases.

2. Check the phase to phase resistance variance.

c. Dynamic Surge Test

Use a Slaughter Co. Model 1648-1.5 Dynamic Surge Tester for this test. This test verifies consistency in the device magnetics and is most sensitive to detection of shorted turns. It is a GO/NO-GO type test calibrated using GO/NO-GO masters.

Gage Masters

The GO and the NO-GO calibration masters are to be verified as dimensionally correct. The twelve poles of the stator are to be connected electrically into a single series connection. The GO master is to be verified magnetically and electrically correct using a high voltage RF inductance meter. The NO-GO master shall be constructed to contain 6 (six) shorted turns. The specific details for construction of these masters is the responsibility of the supplier and documentation to be available to Ford ELD upon request.

Calibration

Calibrate the Slaughter Model 360 using the provided Phase and Balance controls to consistently pass the GO master and reject the NO-GO master. The transient wave form of the GO master is to be digitally stored in the tester memory for use during the normal test cycle. The tester reject limits must be verified to consistently reject a part containing 6 (six) shorted turns.

Stimulus

The twelve poles of the stator are to be connected electrically into a single series connection. Stimulate the part under test using a single 500 volt, 1 millisecond impulse. The test equipment will automatically compare the tested part transient wave form to the digitally stored wave form produced by the "GO" master during calibration. The deviation in the wave form shall be less than the "NO-GO" master containing 6 (six) shorted turns.

**3 TEST PROCEDURES AND REQUIREMENTS (cont'd)****D. In-Process Tests (cont'd)****3. Motor/Housing Assembly (Performed at Factory Ambient Temperature)**

- a. **Inductance at 1 kHz (Series Method)**
Align the motor shaft in the phase A detent position and measure the phase A inductance. Repeat for phases B and C.
- b. **Motor Static Torque**
Apply 2 ± 0.05 amps to phase A. Measure and record the peak torque developed at the motor shaft. Repeat for Phases B and C.
- c. **Dielectric Test**
This test is designed to check the dielectric strength of the motor stator windings and is sometimes referred to as a "HIVOR" test.
Make an electrical connection to the motor windings and the motor housing. Apply 600 volts AC for a period of 1 second.

**4. Actuator Assembly End of Line Tests
(Performed at Factory Ambient Temperature)****Passive tests****a. Electrical Isolation**

Electrical isolation from phases to shaft to be checked at 500 volts DC.

End Of Line Active Tests:

Setup the gearbox assembly with output shaft position sensor and load as shown in figure 4 and perform the following set of tests. Be sure an axial load of $22 \pm 2N$ is transferred to the actuator output pulley per figure 4, all motor stepping sequences are executed exactly per Figures 6A & 6B and the power drive suppression circuits are the same as shown in Figure 5.

b. Minimum Pull Voltage:

1. With the actuator output shaft unloaded and clutch disengaged, save the shaft angular position for use in the "No Load deactivate to Idle" test III.D.4.e.

2. Apply a load to the actuator as shown in Figure 7, keep the clutch disengaged, and save the output shaft position for use in test III.D.4.c.9.

3. Power up the clutch using a constant current source set for 287 ± 1 ma and dwell 150ms minimum to allow time for the clutch to close.

4. Set the motor supply voltage to 14 ± 0.1 volts.

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3 TEST PROCEDURES AND REQUIREMENTS (cont'd)D. In-Process Tests (cont'd)4. Actuator Assembly End of Line Tests (cont'd)End Of Line Active Tests: (cont'd)b. Minimum Pull Voltage:

5. To pickup the load and minimize all lash within the actuator assembly and test equipment, advance the output shaft angle making an initial move of 50 motor steps per starting/stopping phase stepping sequences of Figures 6A and B. Save the output shaft angle for use in test III.D.4.c.8.

6. Reduce the motor supply voltage to $9.5 \pm .05$ volts.

7. Advance the motor shaft 50 steps per starting/stopping phase stepping sequences of Figures 6A and B.

8. Measure the angular rotation of the loaded output shaft. To verify there were no step errors, for each 50 steps, the angle of rotation must be $18.65 \pm 0.75^\circ$.

c. Maximum Stroke Test:

Continuing from the "Minimum Pull Voltage" test III.D.4.c.8, return the motor supply to 14 ± 0.1 volts and verify the maximum allowable angular displacement from the idle position is attainable. The shaft angle measurement is to be referenced to the saved reading in test step III.D.4.c.2. The steps required to achieve full stroke should be calculated. It is not intended that the actuator be driven into the internal high end hard stop by the motor. Calculate the required number of steps using:

$$\text{Steps Needed} = \left\lceil \frac{\text{Upper Spec. - Total angle from III.D.4.c.9}}{\text{limit}} \right\rceil \times 2.61$$

d. No Load Deactivate to Idle:

Continuing from the "Maximum Stroke" test III.D.4.c.4, remove the load from the actuator.

Remove power from the motor and clutch and verify the internal actuator return spring moves the output to the idle position saved in test III.D.4.c.1.

3 TEST PROCEDURES AND REQUIREMENTS (cont'd)**D. In-Process Tests (cont'd)****4. Actuator Assembly End of Line Tests (cont'd)****End Of Line Active Tests: (cont'd)****a. Full Load Deactivate to Idle:**

1. Power up the clutch using a constant current source set for 287 ± 1 mA and dwell 150ms minimum to allow time for the clutch to close.
2. Apply a load to the gearbox as shown in Figure 7 and save the shaft position of the actuator with the output shaft loaded and clutch disengaged for use in test III.D.2.f.4.
3. Advance the motor shaft 74 steps per starting/stopping phase stepping sequences of Figures 6A and B. Check for the actuator to advance a minimum of 13°.
4. Reduce the clutch current to 15 ± 1mA and check for the actuator to return to the idle position. Measure and record this position referenced to the reading of test III.D.2.f.2.

f. Motor Rub Test

Engage clutch at 7.0 ± 0.1 volts. Step the motor at 140 steps per second using specified voltage into driver card & no current limiting. Step the motor for 1.7 seconds clockwise and then turn clutch voltage supply to 150 mv. Step the motor for 1.3 seconds counter-clockwise. The rotor must rotate freely in both directions with no binding or resonances (pulses or jerky motion) and the clutch must return to the rest position.

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3 TEST PROCEDURES AND REQUIREMENTS (cont'd)

B. Durability Tests

Unless otherwise specified, the Speed Control assembly shall pass section III.B after sustaining any of the following durability tests. Under no circumstances shall a Speed Control unit, subjected to any of these durability tests, be shipped for vehicle installation.

1. 6 Hour Accelerated Life Test

The purpose of the test is to identify any supplier/process defects before shipment of a lot. The test will cause servo wear out shortly after the 6 hour test cycle but not before 5 hours. The wear out should occur in various focus indicating the stress on the different components is balanced. The test cycle and fixture is determined by the supplier. For reference, use the accelerated test fixture shown in Figure 5 and the load applied to the Servo assembly depicted in Figure 7. The test cycle of Table 1 is for reference.

2. Humidity Test

Expose the Servo to 85°C and 85% relative humidity for 96 Hours. Immediately after removal from the test chamber, the Servo must pass performance test per III.B.2 at 25°C only.

3. Phase Resistance

Resistance value to be checked for each of the three phases.

4 REVALIDATION REQUIREMENTS

The manufacturing source and the design-responsible Component Engineering and Manufacturing Operations will jointly determine which potential changes to the process, materials or material sources would have significant impact on the product's function, performance, durability or appearance. The supplier will describe these conditions in the Control Plan, along with either

- (1) the revalidation plan that would be followed in each case, or
- (2) a provision to submit an amended Control Plan for approval if any of those process changes are planned.

The Control Plan must include a provision that, for any significant change in processing, ELO-CERO and the manufacturing location (internal or supplier) shall jointly determine if PV re-testing is required, and, if so, to what degree, i.e., Full or Mini-PV.

No change to processing may be allowed without prior engineering approval of the process changes and the attendant Control Plan changes.

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5 INSTRUCTIONS AND NOTES

A. Control Plans

Control Plans address all significant design and process characteristics, which include all ES tests and Control Item characteristics. They describe the process potential studies that will be performed for product validation (including PV tests) and the ongoing product and process evaluation for continuing improvement (including IP tests). They include acceptance criteria, sample sizes, frequencies, data analysis methods and reaction plans.

The Control Plan is developed, and updated as necessary, by the manufacturing source in conjunction with the design responsible Component Engineering and Manufacturing Operations and other appropriate functions such as SVA. The Control Plan defines the management of the upstream production process and part variables (significant process characteristics) that affect the outcome of the ES tests or other significant design characteristics. The Control Plan also identifies the specific ES tests, with their sample sizes and frequencies, that will be performed in order to:

1. Confirm whether the process is being managed effectively.
2. Further identify significant process characteristics.
3. Evaluate performance of marginal processes.
4. Better anticipate the customer effect of proposed process improvements.

For any part on which ES tests have been specified, the manufacturing source must present the Control Plan and any revisions to the design responsible Product Design Office for approval. This Component Engineering and Manufacturing Operations has flexibility to honor business relationships with suppliers having proprietary processes.

B. Lot Definition

A lot consists of no more than one shift of production. The size of the lot does not affect the minimum sample sizes. The audit sample sizes are not to be reduced due to short production runs even though 100 percent inspection results.

5 INSTRUCTIONS AND NOTES (cont'd)**C. Test Reporting and Record Retention**

Recording and record retention shall conform to Ford QS-9000 Section 4.2. In addition:

1. Production Validation

All PV samples and the test results and data from Production Validation testing must be submitted in report form to ELD-CENO prior to PSW. Component Engineering and Manufacturing Operations shall have final authority to approve PV testing.

2. In-Process

The IP test variable data produced as a result of performing the sample lot test requirements outlined in Section II must be collected and stored as defined in QS-9000 for ELD-STA review.

3. Report Contents for Lot Control Testing

Equipment serial numbers, most recent date of calibration and test sample serial number must be recorded on all data sheets. Test summaries must be sorted by test temperatures -40°C, 25°C, 150°C or 170°C, and contain:

- 1) Sample Size
- 2) X - BAR
- 3) High Reading
- 4) Low Reading
- 5) Standard Deviation
- 6) Cp and Cpk
- 7) Upper Test Limit
- 8) Lower Test Limit

The records must be stored such that all parametric data for any one sample piece may be recalled with traceability to the lot in which the sample was taken.

D. Test Correlation

Test equipment correlation between on-line and audit test equipment shall be performed by supplier. The procedure must be documented in the supplier control document.

E. Returns - ELD/Body & Assembly Division/Field

The supplier shall have the capability to analyze all returns and shall identify the root cause of the returns. A report for each identified root cause is to be delivered to ELD-CENO on a timely basis. All test methods and data used to identify the root cause will be submitted together with a report in an SD format. Summary data of these results must be provided to ELD-CENO monthly. Destructive analysis not allowed without prior approval from ELD-CENO.

5. INSTRUCTIONS AND NOTES (cont'd)**F. Traceability**

The manufacturer shall institute a traceability program per Vistacon QS-9000 3.14 for all components:

Bearings, shafts, housings, gears, wire, molded parts, retainers, connector inserts, pole pieces, adhesives, stampings, clips, springs.

In addition, each time a module is subjected to any of the daily IP Sample Tests 3.5, the test number, test results, (parametric data), and date tested shall be traceable from the clearly and permanently marked assembly.

G. Repairs**1. Definition**

A repair is defined as the rework required for a module to pass a test requirement.

2. Procedure

Repair of the modules may not be done until the manufacturers repair procedure is approved by ELD-CEMO.

VI. COMPILED LIST OF REFERENCE DOCUMENTS

ES-F2VF-9AB19-AA HOUSING ASY-SPEED CONTROL ACTUATOR
ES-F2VF-9C735-AA SERVO ASSEMBLY SPEED CONTROL
ES-F2VF-9D844-AA AMPLIFIER SPECIFICATION
CE-F2VF-9D844-AA AMPLIFIER MONITOR AND MEMORY MAP
ES-F10P-1316-AA ELECTROMAGNETIC COMPATIBILITY CONFORMANCE
QS-9000 1990 VISTECN QUALITY CONTROL
SREIA Form #1638, or approved equivalent
PMRA Form #GFD-9366 or approved equivalent
CONTINUING PROCESS CONTROL AND PROCESS CAPABILITY IMPROVEMENT, INC
VISTECN RELIABILITY METHODS, INC
PLANNING FOR QUALITY, VISTECN AUTOMOTIVE SYSTEMS
PPF 3-145, SEC. VII, GUIDELINES FOR PART NUMBER IDENTIFICATION ON PARTS

NOTE: Outside suppliers should request all reference information from the Purchasing activity. Where necessary, Purchasing requests these documents from the affected Component Engineering and Manufacturing Operations.

Printed on 3/10/00 at 11

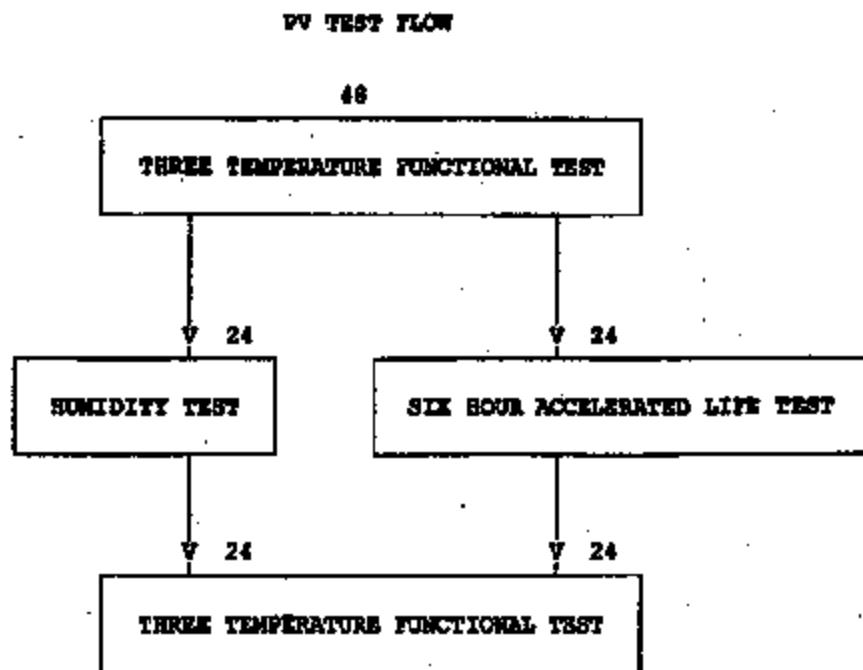
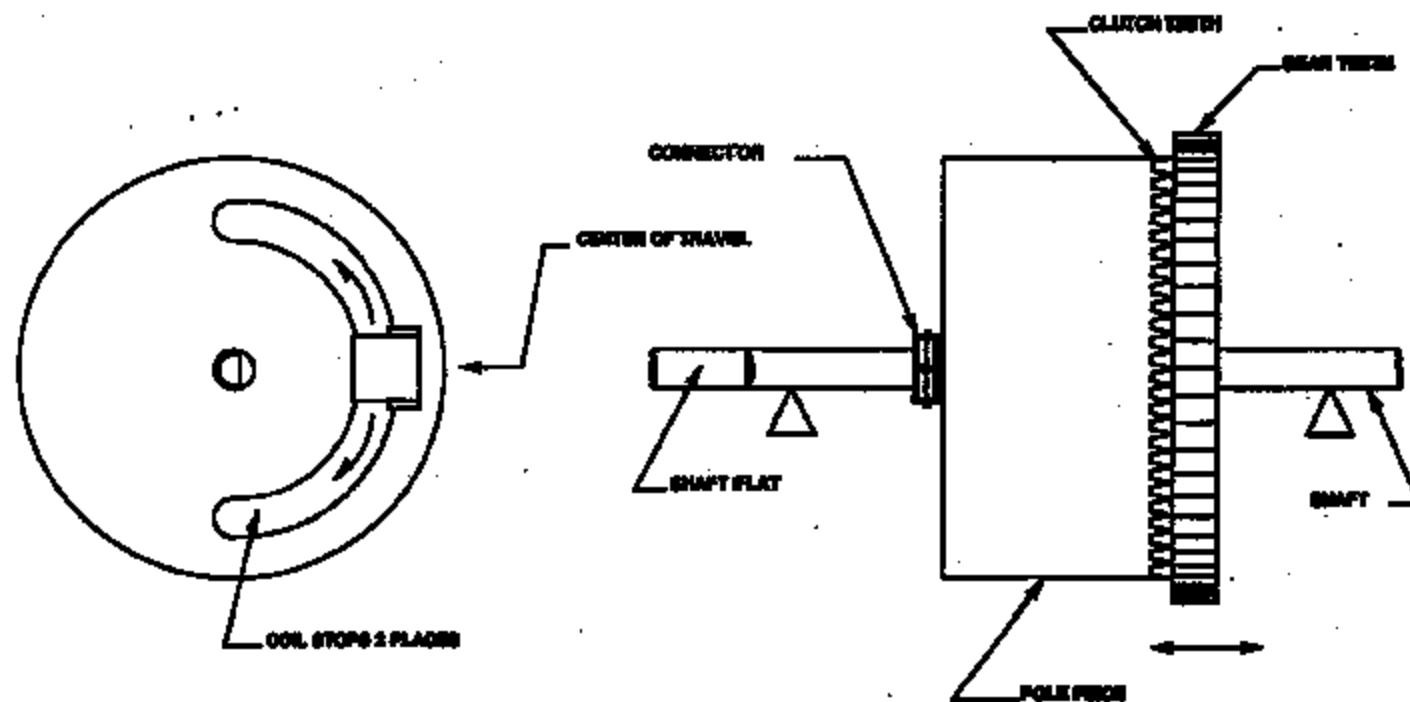
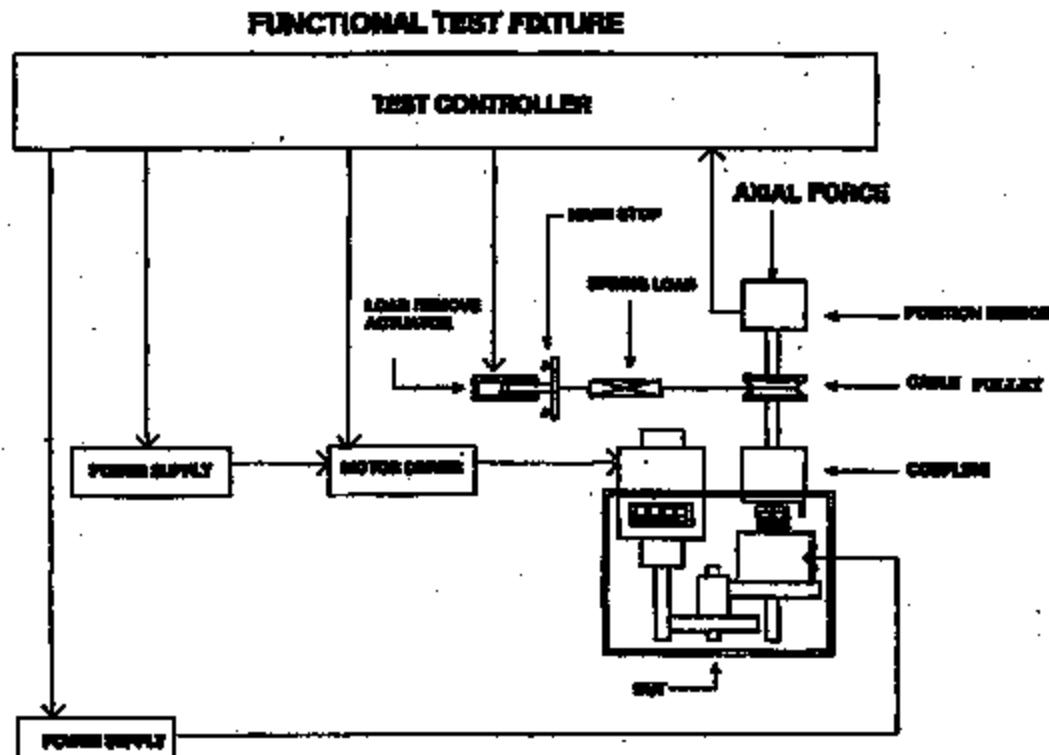


FIGURE 2

CLUTCH TEST SETUP**FIGURE 3**

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Printed on 3/10/00 at 10



FUNCTIONAL TEST DRIVE CIRCUIT

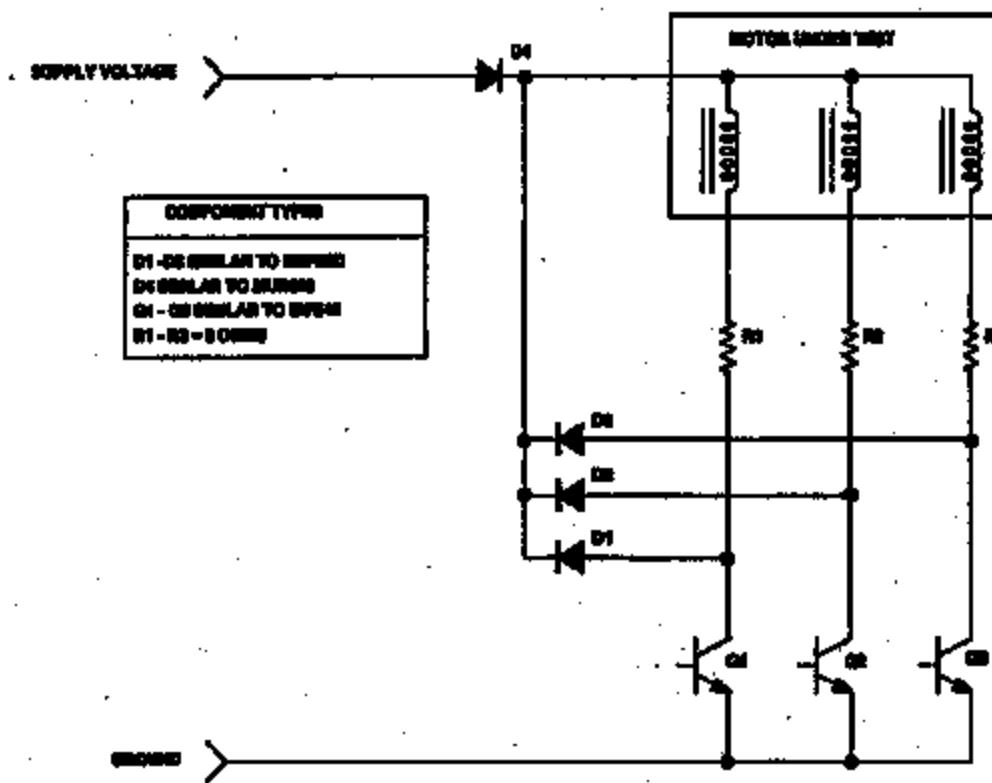
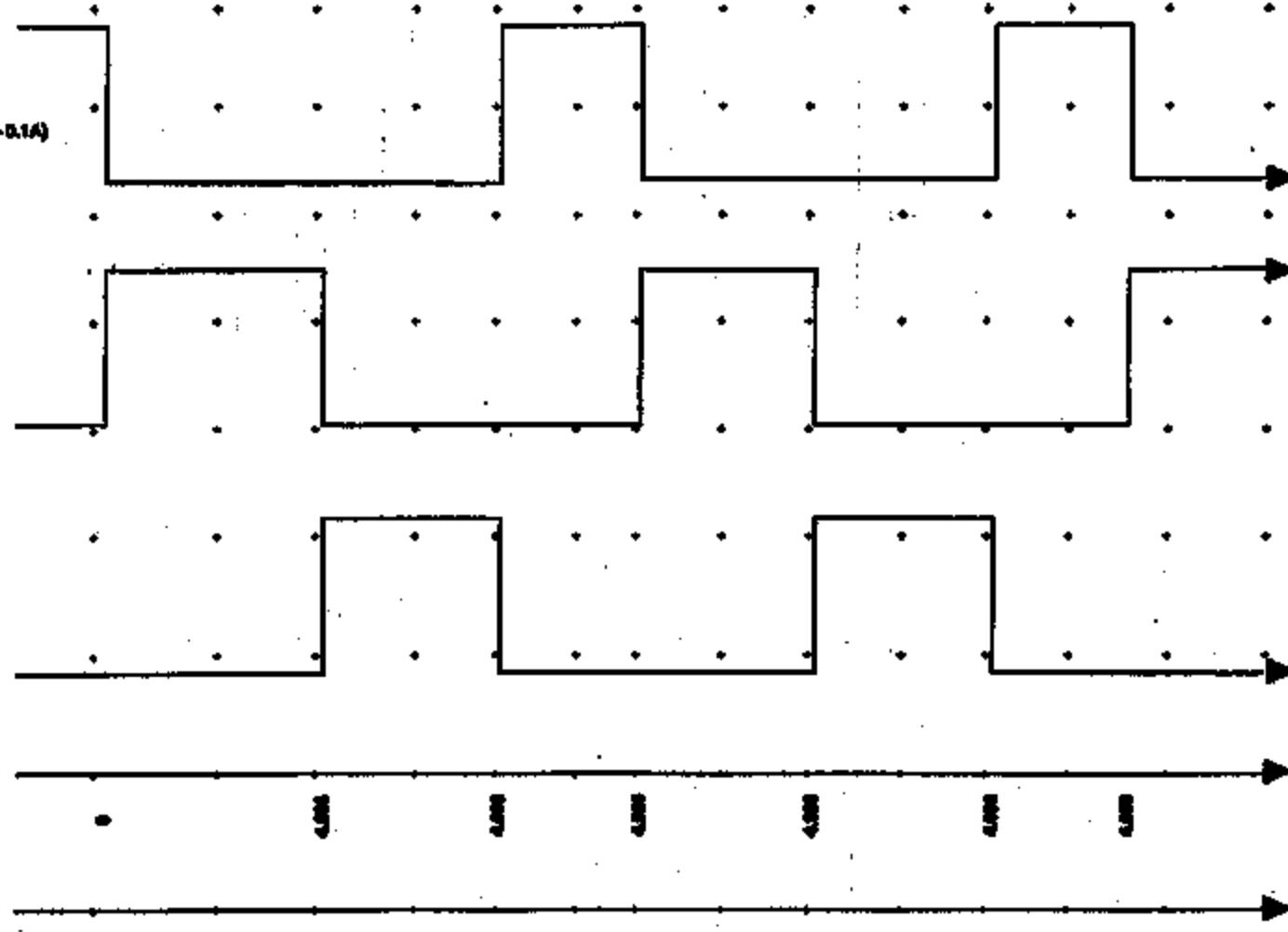


FIGURE 5

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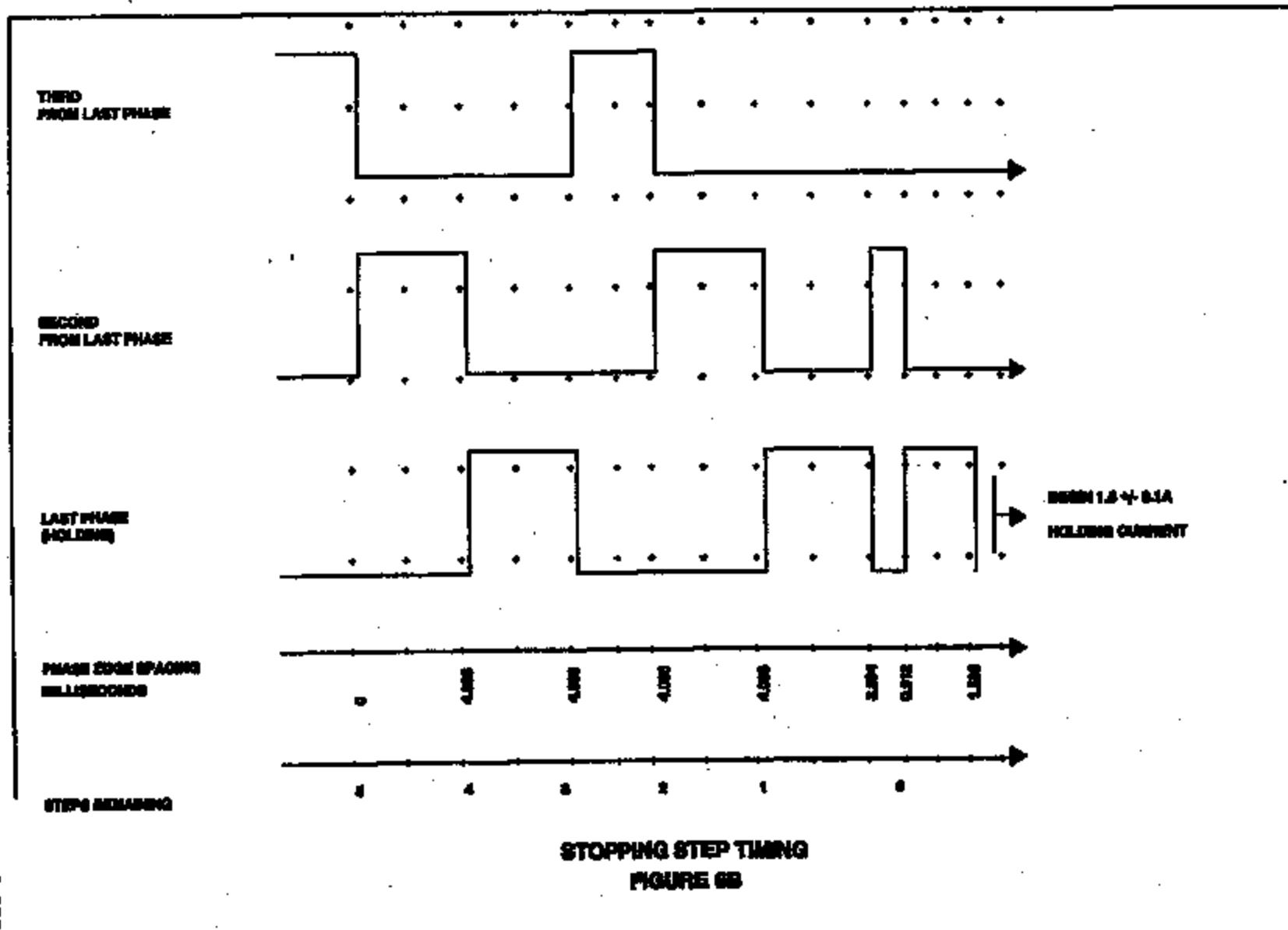


INITIAL HOLDING
PHASE A
(HOLDING CURRENT
CONTROLLED AT 1.6 ± 0.1A)



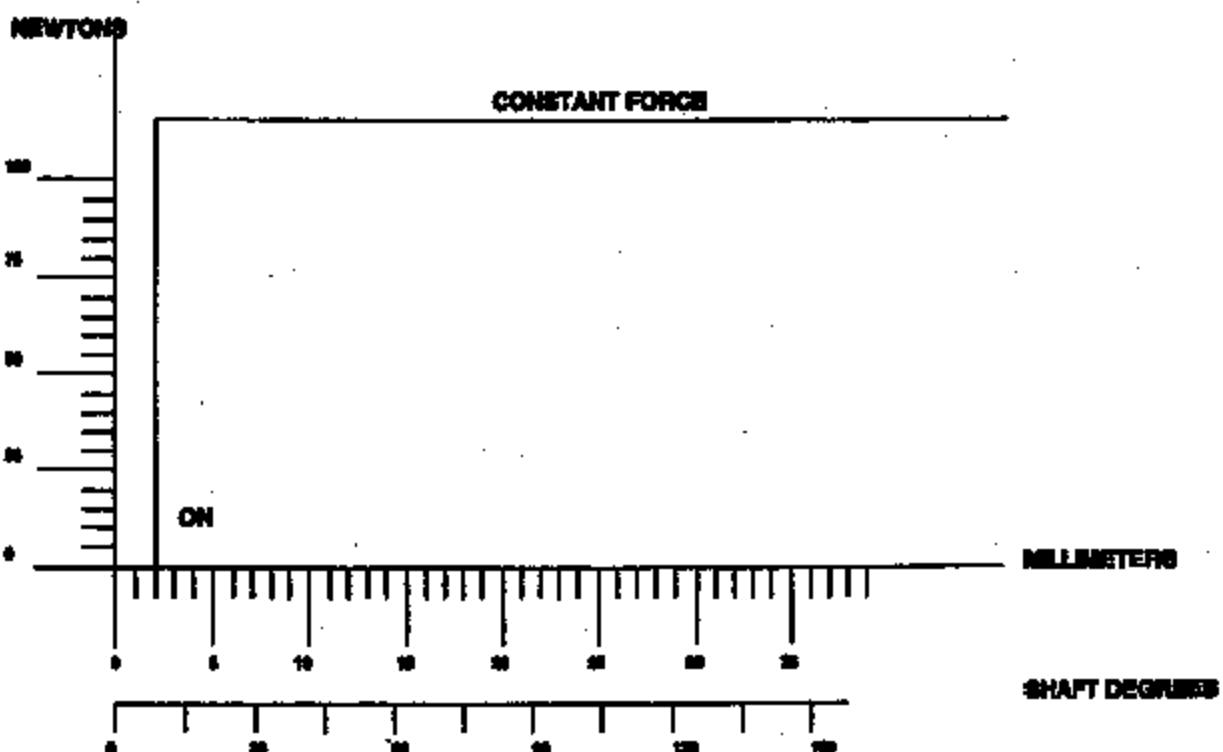
STARTING STEP TIMING
FIGURE 6A

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Printed on 3/10/00 at 11

TEST	FORCE
ELB2	194 N MM.
ELD4	124 N MM.

**LOAD LINE****FIGURE 7**

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REV C

NAME: _____

DATE: _____

PAGE: _____

OF _____

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ACCELERATED LIFE TEST FIXTURE

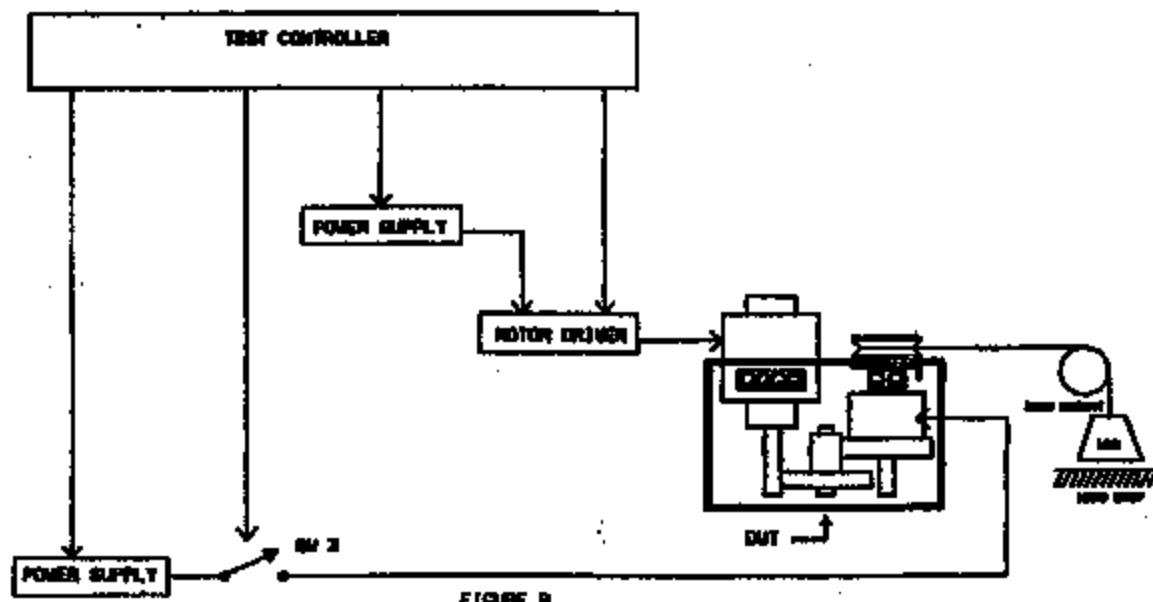


FIGURE 9

Table 1

The accelerated durability test cycle is comprised of segments as indicated below:

- Power up the servo clutch to 500 mA.
- Stroke the servo to W.O.T. (500 steps).
- Stroke the servo toward idle 420 steps and remove the clutch power by opening SW3. This will cause a hard return of the servo against the idle stop of the test fixture.
- Remove power from the module and return to segment "a" of this test cycle.

Part (c)(5)

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ENGINEERING SPECIFICATION

***PART NAME
SPECIFICATION - AMPLIFIER ASSEMBLY - SPEED CONTROL
(KICK OPERATION)**

Part Number

8-777-2001-1

REV.	K	K	T	U	N	N	C	C	T	T	T	N	C	C	H	V		
PR.	1	1A	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17
REV.	T	W	W	W	W	W	T	T	T	T	T	T	D	D	I	T	D	T
PR.	1A	1B	20	21	22	23	24	25	26	27	28	29	2A	2B	2C	2D	2E	2F
REV.																		
PR.																		
REV.																		
PR.																		
PR.																		
PR.																		
DATE	REV.	PR.	REVISIONS												RR.	EE.	DESCRIPTION	
	K	1B	REV FIG-6														REVIEWED BY	
	K	2A	REV FIG-6 TOM SMIUTK (11/11/84-5/1/85)														REVIEWED BY	
9/30/84	L	1C	REV FIGURE 6 TOM SMIUTK (11/11/84-5/1/85) DEC02 102 38817-000												11/1/84		REVIEWED BY	
11/20/84	M	1B	REV FIGURE 6 TOM SMIUTK (11/11/84-5/1/85)												11/20/84		REVIEWED BY	
11/20/84	M	2B	REV FIGURE 6 TOM SMIUTK (11/11/84-5/1/85)												11/20/84		REVIEWED BY	
9/30/84	N	2	REV TABLE OF CONTENTS												11/20/84		REVIEWED BY	
N	37	REV FIG 1-3															REVIEWED BY	
N	43	REV SECTION 11. A. 2. A															REVIEWED BY	
11/20/84	O	1	REV SECTION 11. A. 2. A TOM SMIUTK (11/11/84-5/1/85) DEC02 102 38817-000												11/20/84		REVIEWED BY	
11/20/84	P	1B	REV FIG-5														QUALITY CONTROL/RR	
11/20/84	P	2B	REV FIG-5														QUALITY CONTROL/RR	
11/20/84	P	3B	REV FIG-5														QUALITY CONTROL/RR	
11/20/84	P	4B	REV FIG-5 TOM SMIUTK (11/11/84-5/1/85) DEC02 102 38817-000												11/20/84		QUALITY CONTROL/RR	
11/20/84	Q	1B	REV FIG-5														QUALITY CONTROL/RR	
11/20/84	Q	2B	REV FIG-5														QUALITY CONTROL/RR	
11/20/84	Q	3B	REV FIG-5														QUALITY CONTROL/RR	
11/20/84	Q	4B	REV FIG-5 TOM SMIUTK (11/11/84-5/1/85) DEC02 102 38817-000												11/20/84		QUALITY CONTROL/RR	
11/20/84	R	2	REV TABLE OF CONTENTS														QUALITY CONTROL/RR	
R	10/17	REV SECTION 11															QUALITY CONTROL/RR	
R	1B	REV FIG-5															QUALITY CONTROL/RR	
R	2B	REV FIG-5 - ADDED FRAME 201															QUALITY CONTROL/RR	
R	3B	REV FIG-5 - ADDED FRAME 202															QUALITY CONTROL/RR	
R	4B	REV FIG-5 - ADDED FRAME 203															QUALITY CONTROL/RR	
11/20/84	S	1	REV FIGURE 6 TOM SMIUTK (11/11/84-5/1/85) DEC02 102 38817-000												11/20/84		QUALITY CONTROL/RR	
11/20/84	T	2	REV TABLE OF CONTENTS														QUALITY CONTROL/RR	
T	3	REV TABLE OF CONTENTS															QUALITY CONTROL/RR	
T	4	UPDATE SECTION 11															QUALITY CONTROL/RR	
T	10	REV SECTION 11. A. 2. A															QUALITY CONTROL/RR	

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Engineering Specifications

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ENGINEERING SPECIFICATION

PART NUMBER

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- 3 TEST REQUIREMENTS AND PROCEDURES

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- 3.1.1.2 Temperature
- 3.1.1.3 Voltage
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- 3.3.2.22 Brake Pull-up Test
- 3.3.2.23 FET Leakage Test
- 3.3.2.24 Decoupling Leakage Test
- 3.3.2.25 FET Avalanche/Diode VF Test
- 3.3.2.26 Redundant Brk'n Test
- 3.3.2.27 Brake Open Harness Isolation Test

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3.3.4 Reliability Engineering

3.4 Environmental Tests (per ES-PAY-12214-AA and ES-PAY-12209-AA)

- 3.4.3.14 RSD
- 3.4.3.6 Thermal Shock Resistance
- 3.4.3.7 Thermal Shock Endurance
- 3.4.3.8 Humidity and Temperature Cycle
- 3.4.6.1.1 Endurance Vibration
- 3.4.6.3.3 Shock Step
- 3.4.8.1 High Temperature Endurance



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2	PRODUCTION VALIDATION ABILITY TESTS / SEQUENCES
3	ENVIRONMENTAL TESTS
4	FUNCTIONAL TEST CIRCUIT
5	FUNCTIONAL TEST SET-UP TEST TABLE - FAMILIES G,F,G
5a	FUNCTIONAL TEST SET-UP TEST TABLE - FAMILY H
6	FUNCTIONAL TEST LIMITS - FAMILIES G,F,G
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7	SOFTWARE VERSION VALUES - FAMILIES G,F,G
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1. GENERAL

This specification governs the speed control amplifier assembly. It is a subassembly to an electronic Speed Control system which regulates vehicle speed. The amplifier subassembly is comprised of a leadframe housing, aluminum baseplate, solid state electronic circuit and protective encapsulant.

This Engineering Specification is a supplement to the released drawing or the released part, and all requirements herein must be met in addition to all other requirements of the part drawing. Minimum measures necessary for demonstrating compliance to these requirements are given in each section.

The Engineering Specification is intended to evaluate specific characteristics as a supplement to normal material inspection, dimensional checking, and in-process controls, and should do no way adversely influence other inspection operations.

Preparation and submission of an acceptable Control Plan are the responsibility of the manufacturing source. Control Plan approved by the Department Engineering & Manufacturing Operations and by other activities according to QD-9040 is a prerequisite for initial sample review and approval. The manufacturing source will retain the original of the approved control plan and any later revisions per QD-9040 and provide a copy to the design responsible CEMO.

2. PRODUCTION VALIDATION AND IN-PROCESS TESTS

Production Validation (PV) tests are used to obtain an initial estimate of the process potential to produce parts that conform to engineering requirements, and to identify causal or predictive relationships between significant design and process characteristics (to be used for process control). These tests must be completed satisfactorily using initial parts from production tooling and processes before Part Substitution Waiver (PSW) approval and authorization of production parts can be issued. Sampling plans for PV testing must be included in the Control Plan.

In-process (IP) tests are used to further understand the relationship between significant design and process characteristics and to establish a basis for continuing improvement. Tests must be completed with production parts on an on-going basis. Sampling plans for both IP testing and evaluation of the significant process characteristics must be included in the Control Plan. When the process is found to be out of control or the test acceptance criteria are not met, the reaction plan approved in the Control Plan shall be followed.

Figures 1 and 1a list the tests required for production validation (PV) and in-process (IP) testing. Refer to section 3.5 for descriptions of each test.

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Figure 1 - Production Validation and In-Process Tests - Facilities G, F, & E					
Test Number	Test Name	Run	Master See Fig. 6	Minimum Conformance to Tolerance	Suggested Frequency / Sample Size *
3.3.1	Three Temperature Functional	PP/EP			3/
3.3.1.1	HT Filter Depositor	PP/EP		Opt > 1.33	
3.3.1.2	Driver Command Bias Test	PP/EP		Opt > 1.33	
3.3.1.3	Module Quiescent Current	PP/EP		Opt > 1.33	
3.3.1.4	Software Version	PP/EP		3/	
3.3.1.5	Micro ROM, ROM, & A/R Read, Write	PP/EP		3/	
3.3.1.6	Resistor Test	PP/EP		Opt > 1.33	
3.3.1.7	Supply Voltage A/B Test	PP/EP		3/	
3.3.1.8	Ground Voltage A/B Test	PP/EP		3/	
3.3.1.9	Over Voltage Detector A/B Test	PP/EP		3/	
3.3.1.10	Sensitizing Switch Threshold Test	PP/EP		3/	
3.3.1.11	Speed Sensor High threshold Test	PP/EP		Opt > 1.33	
3.3.1.12	Solenoid Sink Int. Voltage Test	PP/EP		3/	
3.3.1.13	Speed Sensor Low threshold Test	PP/EP		Opt > 1.33	
3.3.1.14	Acc. Driver Saturation Voltage Test	PP/EP		3/	
3.3.1.15	Set Indicator Activation Test	PP/EP		3/	
3.3.1.16	Trans. Interface Saturation Test	PP/EP		3/	
3.3.1.17	Watchdog Timer Test	PP/EP		3/	
3.3.1.18	Trans. Interface Open Gate Volt.	PP/EP		Opt > 1.33	
3.3.1.19	Test	PP/EP		Opt > 1.33	
3.3.1.20	Set Indicator Open Gate Volt. Test	PP/EP		Opt > 1.33	
3.3.1.21	Sync Pull-up Test	PP/EP		3/	
3.3.1.22	PST Leakage Test	PP/EP		Opt > 1.33	
3.3.1.23	Deactivator Leakage Test	PP/EP		Opt > 1.33	
3.3.1.24	PST Avalanche/Noise VI Test	PP/EP		3/	
3.3.1.25	Inductance Spike Test	PP/EP		3/	
3.3.1.26	Brake Open Returns To Orbit Test	PP/EP			
3.3.3	End-of-Line Tests	IP		Same as 3.3.1	100%
3.3.4	Reliability Monitoring	IP		3/	3/
3.4.3.14	BBU - BBU	PP			2/Yr.
3.4.3.6	Thermal Shock Resistance	PP/EP		3/	18/Yr.
3.4.3.7	Thermal Shock Resistance	PP/EP		3/	4/Yr.
3.4.5.8	Humidity-Temperature Cycle	PP/EP		3/	18/Yr.
3.4.6.1.1	Vibration	PP/EP		3/	18/Yr.
3.4.6.3.3	Bump Drop	PP/EP		3/	18/Yr.

- ✓ 00 / 00-00 Test - All-Unit Pass
- ✓ Digital resolution of module resolution statistical significance - all must pass.
- ✓ Capability to be within 3 SIGMA of upper tolerance limit.
- ✓ Test 0.1, 0.2, 0.3 to be within 3 SIGMA of upper tolerance limit; 0.4: Opt > 1.33.
- ✓ Modules may be mixed generically for lot testing; see control plan. Subsequent facilities must be run in subsequent quarters.

* It is recommended that ES test sample sizes and frequencies be developed by the manufacturer, with concurrence by GM, and documented in the Control Plan.



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Figure 1a - Production Validation and In-Process Tests - Family A

Test Number	Test Name	See	Limits See Fig. 4	Minimum Conformance to Tolerance	Suggested Frequency / Sample Size *
3.3.2	Three Temperature Functional	IP			
3.3.2.1	IFT Firing Capability	IP/ID		Opk > 1.33	
3.3.2.2	Driver Command Max Test	IP/ID		Opk > 1.33	
3.3.2.3	Module Quiescent Current	IP/ID		Opk > 1.33	
3.3.2.4	Software Version	IP/ID		1/	
3.3.2.5	Micro ROM, ROM, & A/R Check. Therm	IP/ID		1/	
3.3.2.6	Resistor Test	IP/ID		Opk > 1.33	
3.3.2.7	System Voltage A/D Test	IP/ID		1/	
3.3.2.8	Ground Voltage A/D Test	IP/ID		1/	
3.3.2.9	Over Voltage Detector A/D Test	IP/ID		1/	
3.3.2.10	Deactivator Switch Threshold Test	IP/ID		1/	
3.3.2.11	ON/OFF Switch Threshold Test	IP/ID		1/	
3.3.2.12	2nd Command Switch Threshold Test	IP/ID		1/	
3.3.2.13	Speed Sensor Low Threshold Test	IP/ID		Opk > 1.33	
3.3.2.14	Solenoid Sink Set. Voltage Test	IP/ID		1/	
3.3.2.15	Speed Sensor High Threshold Test	IP/ID		Opk > 1.33	
3.3.2.16	Mtr. Driver Saturation Voltage Test	IP/ID		1/	
3.3.2.17	Set Indicator Schmittization Test	IP/ID		1/	
3.3.2.18	Trans. Interface Saturation Test	IP/ID		1/	
3.3.2.19	Watchdog Timer Test	IP/ID		1/	
3.3.2.20	Trans. Interface Open Gkt Volt.	IP/ID		Opk > 1.33	
3.3.2.21	Set Indicator Open Gkt Volt. Test	IP/ID		Opk > 1.33	
3.3.2.22	Brake Pull-up Test	IP/ID		Opk > 1.33	
3.3.2.23	IFT Leakage Test	IP/ID		1/	
3.3.2.24	Deactivator Leakage Test	IP/ID		Opk > 1.33	
3.3.2.25	IFT Avalanche/Biasd V _D Test	IP/ID		Opk > 1.33	
3.3.2.26	Resistor Brake Test	IP/ID		1/	
3.3.2.27	Brake Open Diode Induct Test	IP/ID		1/	
3.3.3	End-of-Line Tests	IP		Same as 3.3.2	100%
3.3.4	Reliability Monitoring	IP		1/	1/
3.4.3.13	EMI - ESD	IP		1/	2/Yr.
3.4.3.6	Thermal Shock Resistance	IP/ID		1/	12/Yr.
3.4.3.7	Thermal Shock Resistance	IP/ID		1/	6/Yr.
3.4.3.8	Humidity-Temperature Cycle	IP/ID		1/	12/Yr.
3.4.6.1.1	Vibration	IP/ID		1/	12/Yr.
3.4.6.3.3	Bench Drop	IP/ID		1/	12/Yr.

1/ OQ / NO-QC Test - All must pass

2/ Digital resolution of module restricts statistical significance - all must pass.

3/ Capability to be within 3 SDEV of upper tolerance limit.

4/ Test 0.1, 0.2, 0.3 to be within 3 SDEV of upper tolerance limit; 0.4: Opk > 1.33.

5/ Modules may be fitted generically for lot testing; see control plan. Subsequent families must be run in subsequent quarters.

- * It is recommended that QI test sample sizes and frequencies be developed by the manufacturer, with consensus by OEM, and documented in the Control Plan.



FIGURE 2- INSPECTION VALIDATION TESTS / FREQUENCY

Ref. No. 1/ 2/	Title	TESTING FREQUENCY DURING THE PERIOD				SUGGESTED FREQUENCY
		SUS- CGRP A	SUS- CGRP B	SUS- CGRP C	SUS- CGRP D	
	SAMPLE SIZE	NUMBER	SIX	THREE	THREE	
3.4.1.1.1/ 3.4.1.1.4	Performance/Functional Evaluations	1,3,7	1,3	1,3	1,3	Yearly
3.4.1.1.6	Inspections	0	4		4	Quarterly
3.4.5.8	Thermal Shock Resistance	3				Yearly
3.4.6.1	Vibration					
3.4.6.1.1	Vibration Endurance (3)	4				Yearly
3.4.6.3	Mechanical Shock/Drop					
3.4.6.3.3	Shock Drop	5				Yearly
3.4.5.8	Humidity-Temperature Cycle 1/	6				Yearly
3.4.5.7	Thermal Shock Endurance		3			Yearly
3.4.5.14	Electrostatic Discharge - 2/			2		Yearly
3.4.6.1	High-Temperature Endurance 1/				2	4/

1/ References: Electronic/Electro-Mechanical Test Methods ES-P2AF-1A259-AA

2/ For Electrical Environment Tests: Reference MIL-STD-204 - ELECTRICAL REQUIREMENTS -
Electronic/Electronic Components and Electromagnetic Compatibility Specification -
ES-P2AF-1A15-AA

3/ Power to Pins 7,8, Ground to pin 10, unmonitored.

4/ Not required for PV, informational purposes only as part of never-ending-improvement.

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3. TEST PROCEDURES AND REQUIREMENTS**3.1 General**

Every Speed Control Module assembly or subassembly shall be capable of passing the Functional, Production Validation, In-process and End of Line Tests specified. Factory ambient tests shall be conducted at 25°C +/- 10°. In addition to all the tests specified herein, all amplifier module assemblies must meet the Speed Control Assembly final assembly (mechanical cover attached) specification EE-PWV-92725-AA.

The following operating conditions and environmental test classifications apply to this module, per the System Design Specification / Product Verification Specification. For definitions of each refer to the MIL-STD-883C.

3.1.1 Operating Conditions**3.1.1.1 Environmental Test Classifications**

Functional Importance Class (FIC)	A
Temperature Class	V
Vibration Class	II
Mechanical Shock/Drop Class	II

3.1.1.2 Temperatures

Exposure Test	T3(min) = -40°C	T6(max) = 130°C ±
Operation Test	T1(min) = -40°C	T2(max) = 115°C
Performance Test	T3(min) = -40°C	T4(max) = 127°C
Functional Test	T1(min) = -40°C	T7(max) = 125°C

* Prolonged storage above 100°C is not recommended. No short term damage will be apparent, however heat aging will accumulate.

3.1.1.3 Voltages

Normal	V1 = 12 volts	V2 = 14 volts
	V3 = 11 volts	V4 = 15 volts
Short Term (survive)		15 to 18 volts
Emergency (1 second)		18 to 24 volts
Emergency Low (survive)		4 to 11 volts

3.1.1.4 Operational Life and Duty Cycle Testing

Hours	5000
Miles	130,000

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3 TEST PROCEDURE AND REQUIREMENTS (cont'd)

3.2 Test Setup / Test Conditions

Modules must meet this specification in the temperature range of -40°C to 125°C. Sample testing must be performed at -40°C, 25°C, and 125°C ambient. Unless the procedure detailed below is used, the environmental chamber soak time when performing functional tests at temperature extremes shall be 2 hours. This allows the servo to stabilize at the final test temperature for most chamber capacities and loading. The limiting factor being the chamber cooling capacity when fully loaded.

The soak time in the QD audit area may be reduced for three temperature functional testing if the time required to reach the temperature extreme, both hot and cold, is determined using a thermocouple type thermometer and a thermocoupled sample module. Procedure:

- Prepare a test sample module by drilling and tapping a #6-32 thread in an area of the module casting having the thinnest cross section next to the motor. (This test sample should be saved for future use.)
- Using a #6-32 screw and washer, clamp a thermocouple under the washer 2mm against the module. (Alternate methods for attachment are not permitted).
- Load the chamber with the necessary fixtures, the maximum number of modules to be tested including the temperature verification module having the threaded hole in the casting and the thermocouple clamped using a screw and washer. In any the module containing the thermocouple is mounted at the station closest to the door.
- Reduce the time required for the verification module to stabilize within 2 degrees of final value.
- Take the stabilization times for hot and cold and adjust by multiplying each by 1.1 to account for unknown factors that will occur during normal testing.
- Use the adjusted time as the soak requirement. Post the soak time and date of validation and date of next re-validation on the front of the test equipment. Submit the adjusted soak times to QDR.

The chamber soak time must be revalidated as follows:

- Every 6 months
- If any chamber service is done to correct a chamber problem,
- If the thermal loading of the chamber is increased (more things added to chamber since the last time validated),
- If a different chamber is used.

**3 TEST PROCEDURE AND REQUIREMENTS (cont'd)****3.3 Functional Evaluation Tests**

The following tests are required for making a functional evaluation of this module as required by any of the environmental tests called out in section 3.4. Reference Figure 4 for the electrical test circuit. For Facilities C, F, G, (These) reference Figure 5 for test circuit stimulus and Figure 6 for test limits. For Facility K (Canada), reference Figure 1a for test circuit stimulus and Figure 6a for test limits. See Figure 11 for the Module Pinout Specification. For all modules used in all facilities, see Figures 3, 1a, 4, & 6 for details.

The tests have three categories: unexpected tests, monitor mode tests, and speed control mode tests.

3.3.1 Three Temperature Functional Test - Facilities C, F, G

Note: Tests 3.3.1.1.1 through 3.3.1.1.7 are run without power to the modules:

3.3.1.1 EMI Filter Capacitors

Measure the input capacitors as:

- 3.3.1.1.1 INPUT IN LINE
- 3.3.1.1.2 SPEED SENSOR
- 3.3.1.1.3 COMMAND SIGNAL
- 3.3.1.1.4 BRAKE INPUT
- 3.3.1.1.5 TRANSMISSION INTERFACE
- 3.3.1.1.6 INDICATOR OUTPUT
- 3.3.1.1.7 DEACTIVATOR SWITCH INPUT

- * To verify speed sensor capacitor, measure & record input impedance at a frequency of 1720 Hz.

Tests in the Monitor Mode (see Section 3.10):

Note: On Reset, the module requires about 1 second to perform internal self tests on RAM, ROM, and A/D. After completion, for a period of three seconds, the module will permit wake up of the monitor. The monitor will stay awake if monitor commands are received at least every three seconds. If there are any system errors, the monitor shuts off and speed control mode is entered. To save time after power up, perform tests 3.3.1.2 and 3.3.1.3 while the micro-controller is executing self tests, then start the monitor at test 3.3.1.4.

3.3.1.2 Active Command Line Test

- 3.3.1.2.1 Measure open circuit voltage at the COMMAND INPUT.
- 3.3.1.2.2 Measure short circuit current at the COMMAND INPUT.

3.3.1.3 Module Quiescent Current Test

With all external loads removed, measure the current draw of the module.

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3 TEST PROCEDURES AND REQUIREMENTS (cont'd)

3.3 Functional Evaluation Tests (cont'd)

3.3.1 Drive Temperature Functional (-40, 25, 100°C) - Facilities C, D, E (cont'd)

3.3.1.4 Software Version

Take up the monitor and record the software version number.

3.3.1.5 Motor Hall, ROM, and A/D Operator Tests

Record a pass or fail status for these internal tests according to the following:

- 1 - Failed A/D
- 2 - Failed ROM
- 3 - Failed ROM and A/D
- 4 - Failed RAM
- 5 - Failed RAM and A/D
- 6 - Failed RAM and ROM
- 7 - Failed RAM, ROM, and A/D
- 8 - Passed DC Self Test

3.3.1.6 Encoder Test

Apply a speed signal at the RPM SENSOR input. Fetch a two byte Speed value from RAM via the monitor and convert from hex to decimal. Calculate and record the encoder frequency using the equation below.

$$\text{Encoder Frequency} = (\text{RPM value}) \times (\text{Speed Signal Frequency}) \times 1$$

3.3.1.7 System Voltage A/D Test

Record the SYSTEM VOLTAGE A/D conversion via the monitor.

3.3.1.8 Current Voltage A/D Test

- 3.3.1.8.1 With the DRIVER COMMAND input open circuit, record the DRIVER CURRENT VOLTAGE A/D conversion via the monitor. Verify the balance of the DRIVER CURRENT conversion to the SYSTEM VOLTAGE conversion of test 3.3.1.7 by recording the difference between the two measurements of test 3.3.1.7 and 3.3.1.8.1.

$$\text{Result} = \begin{array}{ll} \text{SYSTEM VOLTAGE} & \text{DRIVER CURRENT} \\ \text{conversion} & \text{conversion} \\ \text{(test 3.3.1.7)} & \text{(test 3.3.1.8.1)} \end{array}$$

- 3.3.1.8.2 Present a SET command to the DRIVER COMMAND input. Read the conversion and subtract the open circuit conversion from test 3.3.1.8.1.

$$\text{Result} = \begin{array}{ll} \text{"SET" command} & \text{DRIVER COMMAND} \\ \text{conversion} & \text{conversion} \\ \text{(test 3.3.1.8.2)} & \text{(test 3.3.1.8.1)} \end{array}$$

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3 TEST PROCEDURES AND VERIFICATIONS (cont'd)**3.3 Functional Evaluation Tests (cont'd)****3.3.1 Drive Temperature Functional (40, -25, 125°C) - Testline 0, P_0, R (cont'd)****3.3.1.9 Over Voltage Test**

Record the over voltage A/B connection via the monitor.

3.3.1.10 Reactimeter Switch Threshold

3.3.1.10.1 Set the REACTIMETER input to the high threshold, and read the deactivate input via the monitor.

3.3.1.10.2 Set the REACTIMETER input to the low threshold and read the deactivate input via the monitor.

3.3.1.11 Speed Sensor High Threshold Test

Apply a positive slope voltage ramp to the SPEED SENSOR input and record the voltage of the ramp the instant the SOLINOID RELAY output switches from high to low.

3.3.1.12 Solenoid Stick Saturation Voltage Test

With the SOLINOID RELAY output low, measure the output voltage.

3.3.1.13 Speed Sensor Low Threshold Test

Apply a negative slope voltage ramp to the SPEED SENSOR input and record the voltage of the ramp the instant the SOLINOID RELAY output switches from low to high.

3.3.1.14 Motor Driver Saturation Voltage Test

3.3.1.14.1 Turn motor PHASE A on via monitor, measure the saturation voltage at PHASE A output, then turn motor PHASE A off via monitor.

3.3.1.14.2 Turn motor PHASE B on via monitor, measure the saturation voltage at PHASE B output, then turn motor PHASE B off via monitor.

3.3.1.14.3 Turn motor PHASE C on via monitor, measure the saturation voltage at PHASE C output.

3.3.1.14.4 With motor PHASE C on, measure the MOTOR MODE Forward voltage (Vf). Turn off PHASE C via monitor.

3.3.1.15 Indicitor Saturation Test

Turn the INDICATOR on via monitor, measure the saturation voltage at the INDICATOR output, then turn INDICATOR off via monitor.

3.3.1.16 Transmission Interface Saturation Test

Record the voltage of the TRANSMISSION INTERFACE output.

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3 TEST PROCEDURE AND EQUIPMENT (cont'd)**3.3 Functional Evaluation Tests (cont'd)****3.3.1 Three-Phase-Current Functional (-40°, 25, 105°C) - Function G, F, E (cont'd)****3.3.1.17 Braking Time Test**

Via the monitor, place the micro-controller in an endless loop causing the switching to time out. Record the time required for the TRANSMISSION INTERFACE to switch from high to low verifying a micro-controller issue.

NOTE: The remaining tests are performed in the speed control mode. Normally on boot the micro-controller performs a first set of internal self checks and an completion waits three seconds for wake up of the monitor. If no wake up occurs, speed control mode is entered requiring a second set of internal self tests. Testing time can be reduced if the following procedure is used.

- Immediately after watchdog reset, perform tests 3.3.1.18 through 3.3.1.21. Consequently the micro-controller will take one second to perform internal self tests.
- Wake up the monitor and "jump" directly into the speed control mode eliminating the three second monitor time out.
- Perform test 3.3.1.22 while the internal speed filter reaches steady state, (requires 1.5 seconds).
- Finish the remainder of the tests.

3.3.1.18 Transmission Interface Open Circuit Voltage Test

Measure the open circuit voltage at the TRANSMISSION INTERFACE output.

3.3.1.19 Set Indicator Open Circuit Voltage Test

Measure the open circuit voltage at the SET INDICATOR output.

3.3.1.20 Brake Pedal Test

Measure the open circuit voltage at the BRAKE input.

3.3.1.21 EET Leakage Test

- 3.3.1.21.1 Measure the leakage current at GND/SHLD SINK
- 3.3.1.21.2 Measure the leakage current at PHASE A
- 3.3.1.21.3 Measure the leakage current at PHASE B
- 3.3.1.21.4 Measure the leakage current at PHASE C

3.3.1.22 Braking Pedal Leakage Test

Measure the leakage current at the BRAKE/VEHICLE input.

3 TEST PROCEDURE AND REQUIREMENTS (cont'd)**3.3 Electrical Evaluation Tests (cont'd)****3.3.1 Drive Requirements Procedure 1-40, 15, 12761 - English E., F., G (cont'd)****3.3.1.23 HVY Avalanche/Block HV Test**

- 3.3.1.23.1 Power amplifier through SOLID STATE input.
- 3.3.1.23.2 Open HVY IN HV input.
- 3.3.1.23.3 Ground SOLID STATE power.
- 3.3.1.23.4 Apply current at SOLID STATE, record VF.
- 3.3.1.23.5 Open SOLID STATE power and record avalanche of SOLID STATE.
- 3.3.1.23.6 Ground MOTOR COMB.
- 3.3.1.23.7 Apply current at PHASE A, record VF.
- 3.3.1.23.8 Open MOTOR COMB & record avalanche of PHASE A.
- 3.3.1.23.9 Ground MOTOR COMB.
- 3.3.1.23.10 Apply current at PHASE B, record VF.
- 3.3.1.23.11 Open MOTOR COMB & record avalanche of PHASE B.
- 3.3.1.23.12 Ground MOTOR COMB.
- 3.3.1.23.13 Apply current at PHASE C, record VF.
- 3.3.1.23.14 Open MOTOR COMB & record avalanche of PHASE C.
- 3.3.1.23.15 Power amplifier through HV IN HV.
- 3.3.1.23.16 Open COMMAND SIGNAL input and dwell 100ms.

3.3.1.24 Rebound Brake Test

- 3.3.1.24.1 Apply speed and 100ms "ON" command at the COMMAND SIGNAL input.
- 3.3.1.24.2 Open circuit the COMMAND SIGNAL input for 100ms.
- 3.3.1.24.3 Apply a 100ms "OFF" command at the COMMAND SIGNAL input.
- 3.3.1.24.4 Open circuit the COMMAND SIGNAL input for 100ms and check that the SOLID STATE switches from high to low within max. time limit.
- 3.3.1.24.5 After the SOLID STATE switches from high to low, dwell 1.1s.
- 3.3.1.24.6 Reduce the speed frequency and check that the SOLID STATE switches high within the maximum time limit and remains high.

3.3.1.25 Brake-Open Sensors Initialization Test

- 3.3.1.25.1 Apply speed; a 100ms "reverse" command signal and check that the SOLID STATE switch from high to low with in the maximum time limit. The time duration of this step shall not exceed the maximum time limit.
- 3.3.1.25.2 Open the COMMAND SIGNAL input, apply brake and check that the SOLID STATE switches high within the maximum time limit and remains high.

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DATE: 10/10/97



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3 TEST PROCEDURES AND REQUIREMENTS (cont'd)

3.3 Functional Evaluation Tests (cont'd)

3.3.2 Drive Components Functional Test - Family H

Note: Tests 3.3.2.1.1 through 3.3.2.1.7 are run without power to the module.

3.3.2.1 DC Filter Capacitors

Measure the input capacitors as:

- 3.3.2.1.1 INPUT DC FILTER
- 3.3.2.1.2 SPEED SENSOR
- 3.3.2.1.3 CURRENT SENSOR
- 3.3.2.1.4 BRAKE PEDAL
- 3.3.2.1.5 TRANSMISSION SELECT
- 3.3.2.1.6 KEY-INTERLOCK SWITCH
- 3.3.2.1.7 BRAKE/THROTTLE INPUT
- 3.3.2.1.8 TACHO/GEAR SELECT
- 3.3.2.1.9 CH/CHT SWITCH INPUT

* To verify speed sensor capacitor, measure & record input impedance at a frequency of 1720 Hz.

Enter in the Monitor Mode (see Section 3.10):

Note: On reset, the module requires about 1 second to perform internal self tests on RAM, ROM, and A/D. After completion, for a period of three seconds, the module will permit wake up of the monitor. The monitor will stay awake if monitor commands are received at least every three seconds. If there are any system errors, the monitor shorts and speed control mode is entered. To save time after power up, perform tests 3.3.2.2 and 3.3.2.3 while the micro-controller is executing self tests, then start the monitor at test 3.3.2.4.

3.3.2.2 Driver Command Bus Test

- 3.3.2.2.1 Measure the open circuit voltage at the outputs INERT, COM, and GND.
- 3.3.2.2.2 Measure the short circuit current at the outputs INERT, COM, and GND.

3.3.2.3 Module Overcurrent Current Test

With all external loads removed, measure the current draw of the module.

3.3.2.4 Software Version

Wake up the monitor and record the software version number.

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3 TEST PROCEDURES AND REQUIREMENTS (cont'd)

3.3 Functional Evaluation Tests (cont'd)

3.3.3 Three Resonator Functional (-40, -25, 120°C) - Parallel II (cont'd)

3.3.3.5 Clear RAM, ROM, and A/D Converter Test

Record a pass or fail number for those internal tests according to the following:

- 1 - Failed A/D
- 2 - Failed ROM
- 3 - Failed RAM and A/D
- 4 - Failed RAM
- 5 - Failed RAM and A/D
- 6 - Failed ROM and RAM
- 7 - Failed RAM, ROM, and A/D
- 8 - Passed 10 Self Test

3.3.3.6 Resonator Test

Apply a speed signal at the STIMULUS input. Read a two byte speed value from RAM via the monitor and convert from hex to decimal. Calculate and record the resonator frequency using the equation below.

$$\text{Resonator Frequency} = (\text{RAM value}) \times (\text{Speed Signal Frequency}) \times .6$$

3.3.3.7 System Voltage A/D Test

Record the SYSTEM VOLTAGE A/D conversion via the monitor.

3.3.3.8 Driver Command Inputs Test

3.3.3.8.1 With the DRIVER COMMAND input open, read the DRIVER COMMAND conversion via the monitor. Record the A/D conversion.

3.3.3.8.2 Set the DRIVER COMMAND input to VHigh/line. Read the conversion via the monitor. Record the A/D conversion.

3.3.3.8.3 Present a "SET" COMMAND to the DRIVER capture input. Read the conversion via the monitor. Record the A/D conversion.

3.3.3.9 Over Voltage Test

Record the OVER VOLTAGE A/D conversion via the monitor.

3.3.3.10 Deactivation Input Threshold

3.3.3.10.1 Set the DEACTIVATION input to the high threshold, and read the deactivator input via the monitor.

3.3.3.10.2 Set the DEACTIVATION input to the low threshold and read the deactivator input via the monitor.

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3 TEST PROCEDURE AND REQUIREMENTS (cont'd)

3.3 Functional Evaluation Tests (cont'd)

3.3.2 Three Temperature Functional (-40, 25, 125°C) - Family_H (cont'd)

3.3.2.11 On/Off Switch Input Test

3.3.2.11.1 Set ON/OFF input to Upper Threshold and record the ON/OFF input via the monitor.

3.3.2.11.2 Open ON/OFF input and record the ON/OFF input via the monitor.

3.3.2.12 Encoder Command Switch Input Test

3.3.2.12.1 Open ENCODED COMMAND SWITCH input and record the ENCODED COMMAND SWITCH input via the monitor.

3.3.2.12.2 Set ENCODED COMMAND SWITCH input to Lower Threshold and record the ENCODED COMMAND SWITCH input via the monitor.

3.3.2.12.3 Set ENCODED COMMAND SWITCH input to Upper Threshold and record the ENCODED COMMAND SWITCH input via the monitor.

(Note: Order of Tests 3.3.2.13 & 3.3.2.15 is opposite that of 3.3.1.11 & 3.3.1.13)

3.3.2.13 Speed Sensor Low Threshold Test

Apply Low Threshold Voltage to the SPEED SENSOR input and capture the SOLARISD SINK output switches from high to low.

3.3.2.14 Relays Off Sink Saturation Voltage Test

With the RELAYSD SINK output low, measure the output voltage.

3.3.2.15 Speed Sensor High Threshold Test

Open circuit the SPEED SENSOR input and capture the SOLARISD SINK output switches from low to high.

3.3.2.16 Motor Driver Saturation Voltage Test

3.3.2.16.1 Turn motor PHASE A on via monitor, measure the saturation voltage at PHASE A output, then turn motor PHASE A off via monitor.

3.3.2.16.2 Turn motor PHASE B on via monitor, measure the saturation voltage at PHASE B output, then turn motor PHASE B off via monitor.

3.3.2.16.3 Turn motor PHASE C on via monitor, measure the saturation voltage at PHASE C output.

3.3.2.16.4 With motor PHASE C on, measure the MOTOR RIDES forward voltage (VE). Turn off PHASE C via monitor.

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**3 TEST PROCEDURES AND REQUIREMENTS (cont'd)****3.3 Functional Evaluation Tests (cont'd)****3.3.2 Drive Temperature Diagnostic (40, 25, 105°C) - Faulty N (cont'd)****3.3.2.17 Set Indicator Saturation Test:**

Turn the INDICATOR on via monitor, measure the saturation voltage at the INDICATOR output, then turn INDICATOR off via monitor.

3.3.2.18 Transmission Interface Saturation Test:

Record the voltage of the TRANSMISSION INTERFACE output.

3.3.2.19 Matching Timer Test:

Via the monitor, place the micro-controller in an audience loop setting the matching to time out. Record the time required for the TRANSMISSION INTERFACE to switch from high to low verifying a micro-controller reset.

Note: The remaining tests are performed in the speed control mode. Normally on reset the micro-controller performs a first set of internal self checks and on completion waits three seconds for wake up of the monitor. If no wake up occurs, speed control mode is entered requiring a second set of internal self tests. Testing time can be reduced if the following procedure is used.

- Immediately after watching reset, perform tests 3.3.2.20 through 3.3.2.23. Generally the micro-controller will take one second to perform internal self tests.
- Wake up the monitor and "jump" directly into the speed control mode eliminating the three second monitor time out.
- Perform test 3.3.2.23 while the internal speed filter reaches steady state. (requires 1.5 seconds).
- Finish the remainder of the tests.

3.3.2.20 Transmission Interface Open Circuit Voltage Test:

Measure the open circuit voltage at the TRANSMISSION INTERFACE output.

3.3.2.21 Set Indicator Open Circuit Voltage Test:

Measure the open circuit voltage at the SET INDICATOR output.

3.3.2.22 Brake Pull-up Test:

Measure the open circuit voltage at the BRAKE input.

3.3.2.23 HV Leakage Test:

- 3.3.2.23.1 Measure the leakage current at VOLTAGE 200V
- 3.3.2.23.2 Measure the leakage current at PHASE A
- 3.3.2.23.3 Measure the leakage current at PHASE B
- 3.3.2.23.4 Measure the leakage current at PHASE C

Figure 4 Annualized Total Returns - 1990 to 2009

Table 6. Recommended Test Conditions

Test Parameter	Type A			Type B			Type C		
	Min	Max	Step	Min	Max	Step	Min	Max	Step
Driver Control Input	0.00	1.00	0.10	0.00	1.00	0.10	0.00	1.00	0.10
Vehicle Reference Velocity	0.00	1.00	0.10	0.00	1.00	0.10	0.00	1.00	0.10
Reference Velocity	0.00	1.00	0.10	0.00	1.00	0.10	0.00	1.00	0.10
Steer Off Axis	0.00	1.00	0.10	0.00	1.00	0.10	0.00	1.00	0.10
Steering	0.00	1.00	0.10	0.00	1.00	0.10	0.00	1.00	0.10
Span Selection	0.00	1.00	0.10	0.00	1.00	0.10	0.00	1.00	0.10
Control Period	0.00	1.00	0.10	0.00	1.00	0.10	0.00	1.00	0.10
Overvoltage	0.00	1.00	0.10	0.00	1.00	0.10	0.00	1.00	0.10
Front, Critical Threshold	0.00	1.00	0.10	0.00	1.00	0.10	0.00	1.00	0.10
Rebound Off Axis	0.00	1.00	0.10	0.00	1.00	0.10	0.00	1.00	0.10
Span Error Threshold	0.00	1.00	0.10	0.00	1.00	0.10	0.00	1.00	0.10
Span Error Test	0.00	1.00	0.10	0.00	1.00	0.10	0.00	1.00	0.10
Test Indicator Test	0.00	1.00	0.10	0.00	1.00	0.10	0.00	1.00	0.10
Transmission Selection Test	0.00	1.00	0.10	0.00	1.00	0.10	0.00	1.00	0.10
Winding Test	0.00	1.00	0.10	0.00	1.00	0.10	0.00	1.00	0.10

Power 6 Received Test Units -09/06 to 12/06

Test	Run	Outputs	App Type A			App Type B			App Type C			App Type D			
			Min	Max	Avg	Min	Max	Avg	Min	Max	Avg	Min	Max	Avg	
API Filter Capabilities	Run A	Pass	1.5	2.7	2.1	1.8	2.5	2.1	1.9	2.6	2.1	1.8	2.5	2.1	1.8
Driver Command Input	Run B	Pass	1.5	2.7	2.1	1.8	2.5	2.1	1.9	2.6	2.1	1.8	2.5	2.1	1.8
Mobile Network Connect	Run C	Pass	1.5	2.7	2.1	1.8	2.5	2.1	1.9	2.6	2.1	1.8	2.5	2.1	1.8
Software Version	Run D	Pass	1.5	2.7	2.1	1.8	2.5	2.1	1.9	2.6	2.1	1.8	2.5	2.1	1.8
Micro SD Card Test	Run E	Pass	1.5	2.7	2.1	1.8	2.5	2.1	1.9	2.6	2.1	1.8	2.5	2.1	1.8
Processor	Run F	Pass	1.5	2.7	2.1	1.8	2.5	2.1	1.9	2.6	2.1	1.8	2.5	2.1	1.8
System Voltage	Run G	Pass	1.5	2.7	2.1	1.8	2.5	2.1	1.9	2.6	2.1	1.8	2.5	2.1	1.8
General Health	Run H	Pass	1.5	2.7	2.1	1.8	2.5	2.1	1.9	2.6	2.1	1.8	2.5	2.1	1.8
Voltage	Run I	Pass	1.5	2.7	2.1	1.8	2.5	2.1	1.9	2.6	2.1	1.8	2.5	2.1	1.8
Power Output	Run J	Pass	1.5	2.7	2.1	1.8	2.5	2.1	1.9	2.6	2.1	1.8	2.5	2.1	1.8
Processor Threshold	Run K	Pass	1.5	2.7	2.1	1.8	2.5	2.1	1.9	2.6	2.1	1.8	2.5	2.1	1.8
Network Link Test	Run L	Pass	1.5	2.7	2.1	1.8	2.5	2.1	1.9	2.6	2.1	1.8	2.5	2.1	1.8
Speed Sensor Threshold	Run M	Pass	1.5	2.7	2.1	1.8	2.5	2.1	1.9	2.6	2.1	1.8	2.5	2.1	1.8
Output Driver Test	Run N	Pass	1.5	2.7	2.1	1.8	2.5	2.1	1.9	2.6	2.1	1.8	2.5	2.1	1.8
			Run A	Pass	1.5	2.7	2.1	1.8	2.5	2.1	1.9	2.6	2.1	1.8	2.5
			Run B	Pass	1.5	2.7	2.1	1.8	2.5	2.1	1.9	2.6	2.1	1.8	2.5
			Run C	Pass	1.5	2.7	2.1	1.8	2.5	2.1	1.9	2.6	2.1	1.8	2.5
			Run D	Pass	1.5	2.7	2.1	1.8	2.5	2.1	1.9	2.6	2.1	1.8	2.5
Car Battery Test	Run E	Pass	1.5	2.7	2.1	1.8	2.5	2.1	1.9	2.6	2.1	1.8	2.5	2.1	1.8
Transmission Gearbox Test	Run F	Pass	1.5	2.7	2.1	1.8	2.5	2.1	1.9	2.6	2.1	1.8	2.5	2.1	1.8
Braking Test	Run G	Pass	1.5	2.7	2.1	1.8	2.5	2.1	1.9	2.6	2.1	1.8	2.5	2.1	1.8

FIGURE 6. Estimated Tax Rates - 1970 to 1979

TABLE 4 Standard Test Data -40°C to 125°C

Test	Ref.	Min.	Max.	Output	Ref.	Min.	Max.	Output	Ref.	Min.	Max.	Output	Ref.	Min.	Max.	Output
API Filter Capacitors																
Driver Ground Input		-	-	-	Ref. 1	-	-	-	Ref. 2	-	-	-	Ref. 3	-	-	-
Module Reference Current		-	-	-	Ref. 1	-	-	-	Ref. 2	-	-	-	Ref. 3	-	-	-
Software Version		-	-	-	Ref. 1	-	-	-	Ref. 2	-	-	-	Ref. 3	-	-	-
Micro Code Test		-	-	-	Ref. 1	-	-	-	Ref. 2	-	-	-	Ref. 3	-	-	-
Imputer		-	-	-	Ref. 1	-	-	-	Ref. 2	-	-	-	Ref. 3	-	-	-
Power Voltage		-	-	-	Ref. 1	-	-	-	Ref. 2	-	-	-	Ref. 3	-	-	-
Ground Return		-	-	-	Ref. 1	-	-	-	Ref. 2	-	-	-	Ref. 3	-	-	-
Overvoltage		-	-	-	Ref. 1	-	-	-	Ref. 2	-	-	-	Ref. 3	-	-	-
Power Output		-	-	-	Ref. 1	-	-	-	Ref. 2	-	-	-	Ref. 3	-	-	-
Threshold		-	-	-	Ref. 1	-	-	-	Ref. 2	-	-	-	Ref. 3	-	-	-
Speed Driver Threshold		-	-	-	Ref. 1	-	-	-	Ref. 2	-	-	-	Ref. 3	-	-	-
External Disk Test		-	-	-	Ref. 1	-	-	-	Ref. 2	-	-	-	Ref. 3	-	-	-
Small Driver Threshold		-	-	-	Ref. 1	-	-	-	Ref. 2	-	-	-	Ref. 3	-	-	-
Large Driver Test		-	-	-	Ref. 1	-	-	-	Ref. 2	-	-	-	Ref. 3	-	-	-
Ref. Reflector Test		-	-	-	Ref. 1	-	-	-	Ref. 2	-	-	-	Ref. 3	-	-	-
Termination Resistance Test		-	-	-	Ref. 1	-	-	-	Ref. 2	-	-	-	Ref. 3	-	-	-
Working Time		-	-	-	Ref. 1	-	-	-	Ref. 2	-	-	-	Ref. 3	-	-	-



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3 TEST PROCEDURE AND EQUIPMENT (cont'd)

3.3 Functional Evaluation Tests (cont'd)

3.3.2 Three Temperature Functional (-40, -15, 127°C) - Readily H (cont'd)

3.3.2.24 BrakeTorque Test

Measure the torque current at the BRAKETORQUE input.

3.3.2.25 DET Avalanche/Short VT Test

- 3.3.2.25.1 Power amplifier through COMMAND SIGNAL input.
- 3.3.2.25.2 Open NOT IN SWR input.
- 3.3.2.25.3 Ground SOLIDSTATE POWER.
- 3.3.2.25.4 Apply current at SOLIDSTATE SWR, record VT.
- 3.3.2.25.5 Open SOLIDSTATE power and record avalanche of SOLIDSTATE SWR.
- 3.3.2.25.6 Ground MOTOR COMMON.
- 3.3.2.25.7 Apply current at PHASE A, record VT.
- 3.3.2.25.8 Open MOTOR COMMON & record avalanche of PHASE A.
- 3.3.2.25.9 Ground MOTOR COMMON.
- 3.3.2.25.10 Apply current at PHASE B, record VT.
- 3.3.2.25.11 Open MOTOR COMMON & record avalanche of PHASE B.
- 3.3.2.25.12 Ground MOTOR COMMON.
- 3.3.2.25.13 Apply current at PHASE C, record VT.
- 3.3.2.25.14 Open MOTOR COMMON & record avalanche of PHASE C.
- 3.3.2.25.15 Power amplifier through NOT IN SWR.
- 3.3.2.25.16 Open COMMAND SIGNAL input and dwell 100ms.

3.3.2.26 Inductance Brake Test

- 3.3.2.26.1 Apply speed and lock "ON" command at the CB/CW switch Input.
- 3.3.2.26.2 Apply a 100ms "DET" command at the COMMAND SIGNAL input (500 ohm to ground at COMMAND SIGNAL)
- 3.3.2.26.3 Open circuit the COMMAND SIGNAL input for 100 ms and check that the SOLIDSTATE SWR switches from high to low within the maximum time limit.
- 3.3.2.26.4 After SOLIDSTATE SWR switches from high to low, dwell for 1,100 ms.
- 3.3.2.26.5 Reduce the speed frequency and check that the SOLIDSTATE SWR switches high within the maximum time limit and remains high.

3.3.2.27 Brake Open/Hydraulic Test

- 3.3.2.27.1 Apply speed, a 100 ms "DET" command signal and check that the SOLIDSTATE SWR switches from high to low within the maximum time limit. The time duration of this step shall not exceed the maximum time limit.
- 3.3.2.27.2 Open the COMMAND SIGNAL input, remove the brake load, and check that the SOLIDSTATE SWR switches high within the maximum time limit and remains high.

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Figure 4 (cont'd.) Functional Test Units -000 to 009

some Gold and silver-colored Units are unique and differ from model type A.
some Gold Units are listed for comparison.

Figure 6 (cont'd) Functional Test Limits -40°C to 200°C

Test	Type	Type A			Type B			Type C			Type D			Type E		
		Min	Max	Delta	Min	Max	Delta	Min	Max	Delta	Min	Max	Delta	Min	Max	Delta
Transistor Interface		-	1.12-1.4	-	4.30	6.30	2.00	4.70	5.40	0.70	4.30	5.10	0.80	4.30	5.10	0.80
Set Indicator	HI LO	-	1.11-1.4	-	12.30	14.30	2.00	4.50	5.20	0.70	4.30	5.10	0.80	4.30	5.10	0.80
Reset Set-up		-	1.14-1.4	-	10.2	11.2	1.0	12.2	13.2	1.0	10.2	11.2	1.0	10.2	11.2	1.0
Set Voltage	HI LO	1.00	1.00	0.00	1.00	1.00	0.00	1.00	1.00	0.00	1.00	1.00	0.00	1.00	1.00	0.00
Reset, Indicators		-	1.12-1.4	-	1.12	1.12	0.00	1.12	1.12	0.00	1.12	1.12	0.00	1.12	1.12	0.00
Reset, Voids		-	1.12-1.4	-	1.12	1.12	0.00	1.12	1.12	0.00	1.12	1.12	0.00	1.12	1.12	0.00
Output Drive		-	1.12-1.4	-	1.12	1.12	0.00	1.12	1.12	0.00	1.12	1.12	0.00	1.12	1.12	0.00
Standby		-	1.12-1.4	-	1.12	1.12	0.00	1.12	1.12	0.00	1.12	1.12	0.00	1.12	1.12	0.00

--- Bold and underlined units are values that differ from unit type A.

--- All others are listed for comparison.

Power & Clegg, 2006. *Reassessing Bush's shifts -40% to 55%*

~~bold and underlined terms are values that differ from point type A.
all terms are valid for questions.~~

Phase 3 ~~Phase 3~~ ~~Phase 3~~ ~~Phase 3~~ ~~Phase 3~~ ~~Phase 3~~ ~~Phase 3~~

~~and Gold and regular Gold Status are values that differ from each other.
and HSI Units are listed for employees.~~

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Figure 6 (cont.) Functional flow chart of the system.

one bold and underlined Units are values that differ from model type A. The all Units are listed for comparison.

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3 TEST PROCEDURES AND REQUIREMENTS (cont'd)**3.3 Functional Evaluation Tests (cont'd)****3.3.3 End of Line Test**

End of line testing shall consist of all the functional evaluation tests described in 3.3.1 within 2 minutes after each at 1000.

3.3.4 Reliability Monitoring

The modules will be subjected to the unpowered thermal shock process as defined by the plant and approved by the ACO-CMO. Reliability monitoring is a daily metric where 12 modules/shift are tested in accordance with three temp. functional (3.3.1, 3.3.2) and 12 modules/shift thermal shocked five times then tested in accordance with three temp. functional (3.3.1, 2) Shock temperature range is -40 °C to +125 °C with 30 min. hot soak and 30 min. cold soak. Total test time is 5 hours with a 2 chamber system.

3.4 Environmental Tests

Prior to durability testing the modules must be permanently marked as durability test units and must not be shipped for vehicle installation. Functional test data for every module must be saved prior to and after every durability test.

The following table lists the environmental tests required for Production Validation (PV) and In-Process (IP) testing. Refer to the indicated specifications for descriptions on how the tests are performed.

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PART 2.3

3 TEST REQUIREMENTS AND PROCEDURES (cont'd)

3.4 Environmental Tests (cont'd)

FIGURE 3 - ENVIRONMENTAL TESTS

TEST NUMBER	REFERENCE SPECIFICATION	TEST CLASS	TEST
3.4.3.1A	ES-P2AP-1A116-0A, Specs. - ENO Section 3.4.3 (also MIL-STD-464B-007 Kics, Environ. Protection Sections 4.2 - 4.4)	A	3.4.3.1A - ELECTROSTATIC DISCHARGE, DIRECT 3 Discharges of +15 KV, -15 KV each. 1 Micro to ground after each discharge.
3.4.5.6	ES-P2AP-1A2044-0A Section 3.4.5 Mechanical Environment	V	3.4.5.6 - THERMAL SHOCK PERFORMANCE 25-40° C, 75-115° C 6 cycles / 2 hour each @ each temp. >10° C/min.
3.4.5.7		V	3.4.5.7 - THERMAL CYCLE PERFORMANCE 25-40° C, 75-115° C 1000 cycles / 20 min each @ each temp. >10° C/min.
3.4.5.8		V	3.4.5.8 - HUMIDITY/TEMPERATURE CYCLE 3 cycles per defined Time/Temp./Humidity Profile Mount Complete Up. NOTE: VIBRATION TEST, FORCED ONLY
3.4.6.1.1	ES-P2AP-1A2044-0A Section 3.4.6 Mechanical Environment	II	3.4.6.1.1A - VIBRATION PERFORMANCE Method (A)
3.4.6.3.3		IV	3.4.6.3.3 - DROPOUT TEST 20 cm per surface
3.4.8.1	ES-P2AP-1A2044-0A Section 3.4.8 Decommissioned 140s	N/A	3.4.8.1 - HIGH-TEMPERATURE PERFORMANCE 25-115° C 1000 hrs. at Temperature NOTE: VIBRATION TEST, FORCED ONLY

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4 REVALIDATION REQUIREMENTS

Conditions requiring revalidation include changes in part design, material (or source), or manufacturing process that could affect part function, performance or durability.

The manufacturing source and the design responsible Product engineering Office will jointly determine which potential changes to the process, materials or material sources would have significant impact on the product's function, performance, durability or appearance. The supplier will describe these conditions in the Control Plan, along with either:

- (1) the revalidation plan that would be followed in each case, or
- (2) a provision to submit an amended Control Plan for approval if any of those process changes are planned.

The Control Plan must include a provision that, for any significant change in processing, ACO-CMO and the manufacturing location (internal or supplier) shall jointly determine if PW re-testing is required, and if so, to what degree, i.e., Full or Mini PW.

No retesting may be allowed without prior engineering approval of the process changes and the attendant Control Plan changes.

5 INSPECTION AND TESTS

5.1. General Plans

Control Plans address all significant design and process characteristics, which include all EII tests and Control Item characteristics. They describe the process potential studies that will be performed for product validation (including IV tests) and the ongoing product and process evaluation for continuing improvement (including IP tests). They include acceptance criteria, sample sizes, frequencies, data analysis methods and reaction plans.

The Control Plan is developed and updated as necessary by the manufacturing source in conjunction with the design responsible Component Engineering & Manufacturing Operations and other appropriate functions such as R&D. The Control Plan defines the management of the various production process and part variations (significant process characteristics that affect the outcome of the EII tests or other significant design characteristics). The Control Plan also identifies the specific EII tests, with their sample sizes and frequencies, that will be performed in order to:

1. Confirm whether the process is being managed effectively.
2. Further identify significant process characteristics.
3. Evaluate performance of marginal processes.
4. Better anticipate the customer effect of the proposed process improvements.

For any part on which EII tests have been specified, the manufacturing source must present the Control Plan and any revisions to the design responsible Component Engineering & Manufacturing Operations for approval. This Component Engineering & Manufacturing Operations has flexibility to honor business relationships with suppliers having proprietary processes.

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ENGINEERING SPECIFICATION	FILE NUMBER ME-P2P7-99044-IA	REV REV 2.5
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3 INSTRUMENTATION AND TESTS (cont'd)

3.2 Lot Definition

A lot consists of no more than eight hours of production per QI-980.

3.3 Test Reporting and Record Retention

Reporting and record retention shall conform to QI-980. In addition:

3.3.1 Production Validation

All IV samples and the test results and data from production validation testing must be submitted in report form to ACD-CMIO prior to review. Component Engineering & Manufacturing Operations shall have final authority to approve IV testing.

3.3.2 Inspections

The IV test variable data produced as a result of performing the sample lot test requirements outlined in Section II must be collected and stored for ACD-CMIO review.

3.3.3 Test Report Generation

Equipment serial numbers, most recent date of calibration and test sample serial number must be recorded on all data sheets. Test summaries must be sorted by test temperatures -40°C, 25°C or 125°C, and contain:

- 1) Sample Size
- 2) X - BAR
- 3) High Reading
- 4) Low Reading
- 5) Standard Deviation
- 6) Up and Opt
- 7) Upper Test Limit
- 8) Lower Test Limit

The records must be stored such that all parametric data for any one sample piece may be readily traced to the lot in which the sample was taken.

3.3.4 Reporting Frequency

Once a month a summary of the reject rates for incoming inspection, line follow-up, repair stations, final test and audit tests, separated by part numbers and suppliers, shall be transmitted to ACD-CMIO and NIA.

3.4 Test Specification

Equipment calibration must be demonstrated at the beginning and middle of each shift by the supplier. Also, test equipment correlation between on-line and audit test equipment shall be performed by supplier. The procedure must be approved by ACD-CMIO and documented in the supplier control document.

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5 INSPECTION AND TESTS (cont'd)**5.5 Fallow Analysis****5.5.1 In-Line Fallow**

The assembly supplier is required to analyze all in-line fallow at the module level. All components from "isolated cause" fallow and a sufficient quantity of "pattern" fallow must be analyzed to determine the root cause. All test methods and data used to identify the root cause will be submitted together with a report in an ED format. Summary data of these results must be provided to ACD-QM0 monthly.

5.5.2 Returns - Daily & Assembly Rework/Field

The supplier shall have the capability to analyze all returns and shall identify the root cause of the returns. A report for each identified root cause is to be delivered to ACD-QM0 on a timely basis. All test methods and data used to identify the root cause will be submitted together with a report in an ED format. Summary data of these results must be provided to ACD-QM0 monthly.

5.6 Traceability

The manufacturer shall fortify a traceability program per QD-0000 3.14 for all components:

Bushings, baseplates, adhesives, encapsulant, pastes, ceramics, ICs, transistors, diodes, resonators, resistors and capacitors.

In addition, each time a module is subjected to any of the following tests, the test, test results, (parametric data), and date tested shall be traceable from the clearly marked bar coded module serial number. The module serial number shall be contained in the bar code permanently marked on the module housing.

1. Daily IP Sample Tests 3.3.1
2. Daily Reliability Monitoring 3.3.4

5.7 Repair**5.7.1 Definition**

A repair is defined as the work required for a module to pass a test requirement. The following restrictions apply.

- a. A module may be repaired no more than a total of 3 times.
- b. Including wire bending and THT applications, all repairs to the electronic circuit must be done before the substrate/THT is mounted to the baseplate.
- c. No component may be replaced more than once.
- d. No wire bending surface may be repaired more than once.
- e. Any component which has been replaced during repair must be marked for visual identification.
- f. Solder touch up to a given location may be done only once.
- g. The substrate may not be reflowed on the reflow belt for repair.

3. INSPECTION AND TEST (CONT'D)**3.3 Failure Analysis****3.3.1 In-line Failure**

The assembly supplier is required to analyze all in-line failures at the module level. All components from "isolated cause" failures and a sufficient quantity of "pattern" failures must be analyzed to determine the root cause. All test methods and data used to identify the root cause will be submitted together with a report in an AS format. Summary data of these results must be provided to ACO-000 monthly.

3.3.2 Returns - Body & Assembly Division/Final

The supplier shall have the capability to analyze all returns and shall identify the root cause of the returns. A report for each identified root cause is to be delivered to ACO-000 on a timely basis. All test methods and data used to identify the root cause will be submitted together with a report in an AS format. Summary data of these results must be provided to ACO-000 monthly.

3.4 Traceability

The manufacturer shall institute a traceability program per QJ-9000 1.34 for all components:

Housings, baseplates, adhesives, compound, paste, cements, ICs, transistors, diodes, resistors, capacitors and connectors.

In addition, each time a module is subjected to any of the following types, the test, test results, (parametric data), and date tested shall be traceable from the clearly marked bar coded module serial number. The module serial number shall be contained in the bar code permanently marked on the module housing.

1. Daily IF Sample Tests 3.3.1
2. Daily Reliability Monitoring 3.3.4

3.7 Repair**3.7.1 Definitions**

A repair is defined as the work required for a module to pass a test requirement. The following restrictions apply.

- a. A module may be repaired no more than a total of 3 times.
- b. Reclining wire bending and THT applications, all repairs to the electrolytic circuit must be done before the substrate/WB is mounted to the baseplate.
 - c. No component may be replaced more than once.
 - d. No wire bending surface may be repaired more than once.
 - e. Any component which has been replaced during repair must be marked for visual identification.
 - f. Solder touch up to a given location may be done only once.
 - g. The substrate may not be reflowed on the reflow belt for repair.

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5 INSPECTION AND REPAIR (cont'd)**5.7 Repairs (cont'd)****5.7.2 Procedure**

Repair of the modules may not be done until the manufacturers repair procedure is approved by ACD-CMDO.

The repair procedure must:

- a. Identify the work station and report weekly results to the manufacturing responsible engineer and be available to ACD-CMDO on request.
- b. Define how the repair is to be performed for each component at each station reporting.
- c. Define an acceptance standard to verify the repair was done to the proper component on the proper module.
- d. Provide a method of identification and retrieval of the defective component part.
- e. Identify the responsible party for investigating the defective component.

5.8 Packaging and Shipping

The packaging and shipment of parts must conform to the packaging and shipping guide, latest revision, as defined by the Material Handling Engineering Department, Manufacturing Engineering Office. The packaging must also be approved by SLD-FSD before SHIP.

5.9 Other Engineering Test Requirements

This section should be understood as an engineering requirement controlled by ACD-CMDO.

1. Equipment limit test: PW, Lot Testing and IP Test Stations.
2. All procedures (i.e., calibration, maintenance, equipment set up, station aids etc.) must be completed for production and IP test stations. The above procedures must be on display at all times or as specified by SLD-FSD.
3. An RKE, batch bundle, must default to rejecting assemblies. The method must be approved by ACD-CMDO.
4. The PW pilot run must be performed with the same methods and control documents and quality inspection as during production. ACD-CMDO must be informed of the pilot run one week prior and be allowed to observe.
5. The supplier must establish a key yield point weekly report form and submit the report to ACD-CMDO monthly or as requested.

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3 INSTRUMENTS AND MONITOR (cont'd)**3.10 SYSTEM MONITOR OPERATION - FUNCTIONS 0, 1, 2, 3, 4****3.10.1 General**

The system monitor is utilized by the Functional In-Process tester and Accelerated Life Testers for communication with the amplifier microcontroller. The communication is RS232.

3.10.2 Format and Configuration

The system monitor uses a synchronous serial communication interface in the microcontroller. Figure 11 illustrates the diagram of the system interface. For Functions 0, 1, 2 and 3 (READ and WRITE), the REQUEST DATA (RDY) line shares the Receive Input pin (J1-4) and the TRANSMIT DATA OUT (TDO) line shares the Transmitter Interface output pin (J1-2). The communication has the following format:

- A character has 1 start bit, 8 data bits, 1 stop bit, no parity.
- All characters are in uppercase ASCII format.
- Data is transmitted and received Least Significant Bit first.
- Transmitter/Receiver rate is 2400 baud.
- Header and Data bytes are sent Most Significant Byte First.

3.10.3 Entering System Monitor (Sections 3.3.1.4, 3.3.2.4)

The system monitor is entered with the following sequence:

1. Apply power to the module.
2. Transmit an "R" to the module until the module replies with a "P" prompt. The power-up reset takes approximately 1 second.
3. Transmit a "PP" as the 2 character password.
4. Once the password matches, the module will respond with a SOFTWARE VERSION LEVEL (1 byte that is 2 ASCII characters) and the result of the microcontroller's self-test ("P" = Pass, "F" = Fail, and the micro's RAM/ROM/A-D failure code).
5. The monitor routine is now activated and ready to receive instructions.

Once the monitor is active, it must receive a valid instruction character every 3 seconds. If a time-out occurs or an invalid instruction character is received, monitor mode will be aborted and the module will enter normal speed control mode. A JUMP instruction can be issued to keep the monitor from timing out.

3.10.4 System Monitor Commands

The system monitor routine will respond to three types of commands: Read, write, and jump. The following is the format for each command:

Command	Character String	Module Response		
READ	RDATA	DATA	AA,AAA	- address
WRITE	WDATA	DATA	BB,BBB	- data
PROGRAM	PDATA	DATA	CC,CCC	- carriage return
JUMP	JDATA	DATA		

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3 INITIALIZATION AND TESTS (CONT'D)

3.10 SYSTEM MONITOR OPERATION - FORD 1000 C, E, G, H

3.10.3 Functional Tests

Refer to Figures 5, 7 and 9a for addresses and port bit patterns. Figures 10 and 10a for command examples.

- A. Frequency Test: Perform one "WRITE" at the specified address. The most significant byte is read first. The value is Manchester encoded. This is the micro time count. Use the following equation to calculate the microwave frequency:

$$\text{Frequency} = (\text{MSB-value}) \times (\text{Speed Signal Frequency}) \times 8$$

- B. A/D Tests (System Voltage, Ground Bonds, Over Voltage Detectors): These are analog inputs to the microcontroller. Use the following routine to decode the inputs:

- Perform a WRITE command to the specified memory location with the specified Channel number.
- Perform a JUMP to `OVERVOLT` at the specified address.
- Perform a READ at the specified memory location to obtain the 8 bit sample.

- C. Reading/Writing to Digital Ports: To READ the Reactivator Switch Threshold, the Brake On/Off or 2nd Ground Switch inputs, perform a READ instruction at the specified port address. The Motor Driver Phases A, B, C, Solenoid Drive, Transistor Interface, and Gun Indicator outputs are turned ON or OFF by performing a write with bits 1 or 0 to the specified bit and port address.

- D. Transistor Interface Activation/Watchdog Timer Test: Turn SCI TDO off by performing a WRITE test to SCI control register in the micro to turn off the transmitter. Immediately following this instruction, there will be no more responses from the module for instruction inputs. Set the TRANSMISSION INTERFACE to ON/OFF by performing a WRITE test to the specified Data Direction Register of the port. Turn on the TRANSMISSION interface by placing a 1 in the specified bit of the specified port using a WRITE instruction. Note a measurement of the TRANSMISSION ACTIVATION TIME/ON at the specified module pin.

Perform a JMP to the Watchdog subroutine, to allow the watchdog to time out and reset the microcontroller. The time it takes for the transmission output to switch from low to high indicates the watchdog timeout.

After watchdog timeout reset, enter normal speed control mode by logging into monitor mode (3.10.3) and then perform a JMP to the specified address to avoid the 3 second start-up.



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4 CONSOLIDATION OF EXISTING DOCUMENTS

EE-P2PF-94619-AA	DRIVING ACT-SPEED CONTROL ACTS
EE-P2PF-96735-AA	SEAT BELT ACTUATOR SYSTEM CONTROL
EE-P2AF-13116-AA	ELECTROMAGNETIC COMPATIBILITY CONFORMITY
EE-P2AF-1A269-AA	ELECTROMAGNETIC/ELECTRO-MECHANICAL ENVIRONMENTAL TEST METHODS
WIRELESS, QMCA-B07	WIRELESS DESIGN REQUIREMENTS -
Q99000	ENVIRONMENTAL REQUIREMENTS (Vehicle electrical & electronic systems)
	QUALITY STATUS REQUIREMENTS

SQCIA Form 01630, or approved equivalent

SQCIA Form 01631 or approved equivalent

CONTINUOUS PROCESS CONTROL AND PROCESS CAPABILITY IMPROVEMENT, TPS

TOTAL RELIABILITY METHODS, TRM

PLANNING FOR QUALITY, FORD MOTOR COMPANY

PPF 3-345, SEC. VII, GUIDELINES FOR PART NUMBER IDENTIFICATION ON PARTS

NOTE: Outside suppliers should request all reference information from the Purchasing activity. Where necessary, Purchasing requests these documents from the affected Component Engineering & Manufacturing Operations.

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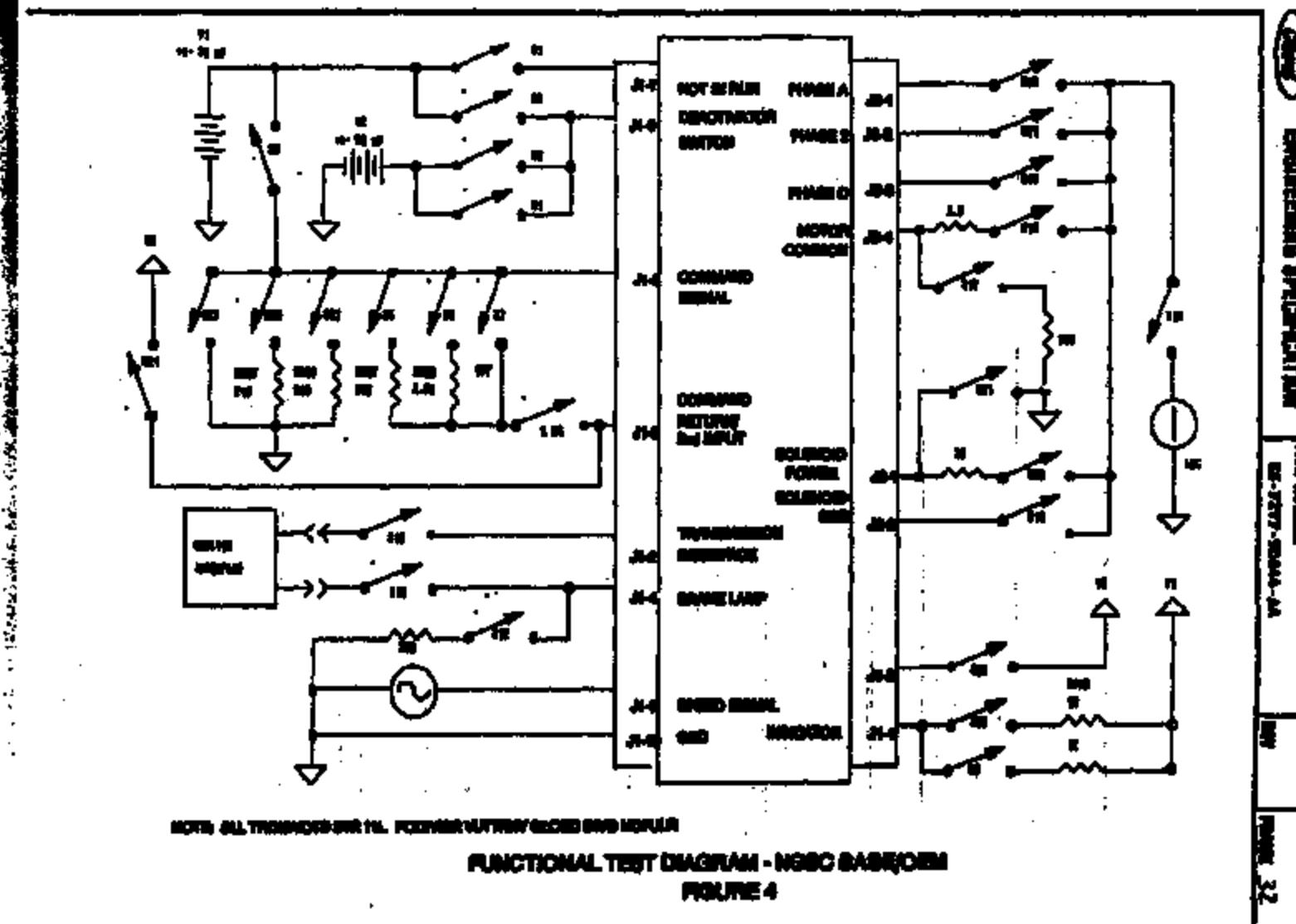


TABLE E - Recommended Test Selection and Sequence Matrix - FORD CORTINA 2.0 LTR				
Test	Run	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16 17 18 19 20 21 22 23 24 25 26 27 28 29 30 31 32 33 34 35 36 37 38 39 40	Run 1	Run 2
Oil Filter Change	1	1 1	1 1	1 1
Other General Tests e.g. oil level, water level, oil pressure	2	1 1	1 1	1 1
Brake Caliper Service	3	1 1	1 1	1 1
Brake Master Cylinder	4	1 1	1 1	1 1
Brake Pad Level	5	1 1	1 1	1 1
Brake Pedal Position	6	1 1	1 1	1 1
Brake Master Leakage	7	1 1	1 1	1 1
General Voltage Check	8	1 1	1 1	1 1
Ground Connection Test	9	1 1	1 1	1 1
Headlight Threshold	10	1 1	1 1	1 1
Speed Sensor Threshold	11	1 1	1 1	1 1
Relay Disk Test	12	1 1	1 1	1 1
Speed Sensor Threshold	13	1 1	1 1	1 1
Steer ABS Operation	14	1 1	1 1	1 1



FORD MOTOR COMPANY
RECOMMENDED TEST SELECTION AND SEQUENCE MATRIX

1970-1971
FORD CORTINA 2.0 LTR

1970-1971
FORD CORTINA 2.0 LTR

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Form 1 - Standard Test Schedule and Instructions Sheet - MILEAGE TEST									
Test	1	2	3	4	5	6	7	8	9
One Minute Starts									
Two Minute Starts									
Mileage Summary Sheet									
1 min	0.0000000000	0.0000000000	0.0000000000	0.0000000000	0.0000000000	0.0000000000	0.0000000000	0.0000000000	0.0000000000
2 min	0.0000000000	0.0000000000	0.0000000000	0.0000000000	0.0000000000	0.0000000000	0.0000000000	0.0000000000	0.0000000000
Mileage Summary Sheet									
1 min	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
2 min	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00

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FORD MOTOR COMPANY
TECHNICAL SPECIFICATION

M-7000-1000-1A

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		DODGE 50 - Standard Test Schedule and Performance Data - 1966 Models																		
Test	Type	100	101	102	103	104	105	106	107	108	109	110	111	112	113	114	115	116	W.M.T.S.	Range
Speed Break Threshold	100	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	100-100	100-100
Power P/T Acceleration	100	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	100-100	100-100
Front	100	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	100-100	100-100
Rear	100	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	100-100	100-100
Side Indicator Test	100	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	100-100	100-100
Transmission Test	100	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	100-100	100-100
Steering Test	100	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	100-100	100-100
Braking - Front Cyl.	100	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	100-100	100-100
Braking - Rear Cyl.	100	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	100-100	100-100
Brake Hold-up Test	100	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	100-100	100-100
Power P/T Lateral	100	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	100-100	100-100
Steering Column	100	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	100-100	100-100
Steering Wheel	100	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	100-100	100-100

FORD MOTOR COMPANY - FORD DIVISION - ENGINEERING - FORD 1000 TRACTOR

Part No.	Description	FORD 1000 TRACTOR																		Quantity	Unit																																																																																
		1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18																																																																																		
1000-1000-A	FORD 1000 TRACTOR	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24	25	26	27	28	29	30	31	32	33	34	35	36	37	38	39	40	41	42	43	44	45	46	47	48	49	50	51	52	53	54	55	56	57	58	59	60	61	62	63	64	65	66	67	68	69	70	71	72	73	74	75	76	77	78	79	80	81	82	83	84	85	86	87	88	89	90	91	92	93	94	95	96	97	98	99	100
1000-1000-B	FORD 1000 TRACTOR	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24	25	26	27	28	29	30	31	32	33	34	35	36	37	38	39	40	41	42	43	44	45	46	47	48	49	50	51	52	53	54	55	56	57	58	59	60	61	62	63	64	65	66	67	68	69	70	71	72	73	74	75	76	77	78	79	80	81	82	83	84	85	86	87	88	89	90	91	92	93	94	95	96	97	98	99	100

FORD MOTOR COMPANY - FORD DIVISION - ENGINEERING - FORD 1000 TRACTOR

1000-1000-A
1000-1000-B

18-10-50704

Form A - Detailed Test Matrix - Version 2.0.0													
		Test Type 1				Test Type 2				Test Type 3			
Test	No.	Inputs	No.	Inputs	No.	Inputs	No.	Inputs	No.	Inputs	No.	Inputs	
MT-Print Cap.	MT-21-001	1.1.1.1	1.1.1.2	1.1.1.3	1.1.1.4	1.1.1.5	1.1.1.6	1.1.1.7	1.1.1.8	1.1.1.9	1.1.1.10	1.1.1.11	
Driver Standard File Test	MT-21-011	1.1.1.1	1.1.1.2	1.1.1.3	1.1.1.4	1.1.1.5	1.1.1.6	1.1.1.7	1.1.1.8	1.1.1.9	1.1.1.10	1.1.1.11	
Module Calibration Control	MT-21-012	1.1.1.1	1.1.1.2	1.1.1.3	1.1.1.4	1.1.1.5	1.1.1.6	1.1.1.7	1.1.1.8	1.1.1.9	1.1.1.10	1.1.1.11	
Software Revision	MT-21-013	1.1.1.1	1.1.1.2	1.1.1.3	1.1.1.4	1.1.1.5	1.1.1.6	1.1.1.7	1.1.1.8	1.1.1.9	1.1.1.10	1.1.1.11	
Memory Test	MT-21-014	1.1.1.1	1.1.1.2	1.1.1.3	1.1.1.4	1.1.1.5	1.1.1.6	1.1.1.7	1.1.1.8	1.1.1.9	1.1.1.10	1.1.1.11	
Parameter Test	MT-21-015	1.1.1.1	1.1.1.2	1.1.1.3	1.1.1.4	1.1.1.5	1.1.1.6	1.1.1.7	1.1.1.8	1.1.1.9	1.1.1.10	1.1.1.11	
Current Voltage AD	MT-21-016	1.1.1.1	1.1.1.2	1.1.1.3	1.1.1.4	1.1.1.5	1.1.1.6	1.1.1.7	1.1.1.8	1.1.1.9	1.1.1.10	1.1.1.11	
Power Voltage AD	MT-21-017	1.1.1.1	1.1.1.2	1.1.1.3	1.1.1.4	1.1.1.5	1.1.1.6	1.1.1.7	1.1.1.8	1.1.1.9	1.1.1.10	1.1.1.11	
Parameter Control	MT-21-018	1.1.1.1	1.1.1.2	1.1.1.3	1.1.1.4	1.1.1.5	1.1.1.6	1.1.1.7	1.1.1.8	1.1.1.9	1.1.1.10	1.1.1.11	
Power Power Init Test	MT-21-019	1.1.1.1	1.1.1.2	1.1.1.3	1.1.1.4	1.1.1.5	1.1.1.6	1.1.1.7	1.1.1.8	1.1.1.9	1.1.1.10	1.1.1.11	
Normal Init Test	MT-21-020	1.1.1.1	1.1.1.2	1.1.1.3	1.1.1.4	1.1.1.5	1.1.1.6	1.1.1.7	1.1.1.8	1.1.1.9	1.1.1.10	1.1.1.11	
Power Power Low Test	MT-21-021	1.1.1.1	1.1.1.2	1.1.1.3	1.1.1.4	1.1.1.5	1.1.1.6	1.1.1.7	1.1.1.8	1.1.1.9	1.1.1.10	1.1.1.11	
Power Off Recovery	MT-21-022	1.1.1.1	1.1.1.2	1.1.1.3	1.1.1.4	1.1.1.5	1.1.1.6	1.1.1.7	1.1.1.8	1.1.1.9	1.1.1.10	1.1.1.11	
Self Initiator Test	MT-21-023	1.1.1.1	1.1.1.2	1.1.1.3	1.1.1.4	1.1.1.5	1.1.1.6	1.1.1.7	1.1.1.8	1.1.1.9	1.1.1.10	1.1.1.11	

BASIC TEST SPECIFICATION

20-7200-001A AL

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TEST A - DUTY CYCLE TEST													
			TEST A DUTY CYCLE			TEST B DUTY CYCLE			TEST C DUTY CYCLE				
Test	Min	Max	Min	Max	Min	Max	Min	Max	Min	Max	Min	Max	Min
RF Filter Type	RF 20 dB	RF 21 dB	RF 22 dB	RF 23 dB	RF 24 dB	RF 25 dB	RF 26 dB	RF 27 dB	RF 28 dB	RF 29 dB	RF 30 dB	RF 31 dB	RF 32 dB
Driver Current Max Test	1.5A 1.5	1.5A 1.5	1.5A 1.5	1.5A 1.5	1.5A 1.5	1.5A 1.5	1.5A 1.5	1.5A 1.5	1.5A 1.5	1.5A 1.5	1.5A 1.5	1.5A 1.5	1.5A 1.5
Module Reference Current	1.5A 1.5	1.5A 1.5	1.5A 1.5	1.5A 1.5	1.5A 1.5	1.5A 1.5	1.5A 1.5	1.5A 1.5	1.5A 1.5	1.5A 1.5	1.5A 1.5	1.5A 1.5	1.5A 1.5
Software Version	1.5A 1.5	1.5A 1.5	1.5A 1.5	1.5A 1.5	1.5A 1.5	1.5A 1.5	1.5A 1.5	1.5A 1.5	1.5A 1.5	1.5A 1.5	1.5A 1.5	1.5A 1.5	1.5A 1.5
Power Grid Type	1.5A 1.5	1.5A 1.5	1.5A 1.5	1.5A 1.5	1.5A 1.5	1.5A 1.5	1.5A 1.5	1.5A 1.5	1.5A 1.5	1.5A 1.5	1.5A 1.5	1.5A 1.5	1.5A 1.5
Processor Test	1.5A 1.5	1.5A 1.5	1.5A 1.5	1.5A 1.5	1.5A 1.5	1.5A 1.5	1.5A 1.5	1.5A 1.5	1.5A 1.5	1.5A 1.5	1.5A 1.5	1.5A 1.5	1.5A 1.5
Output Voltage AV	1.5A 1.5	1.5A 1.5	1.5A 1.5	1.5A 1.5	1.5A 1.5	1.5A 1.5	1.5A 1.5	1.5A 1.5	1.5A 1.5	1.5A 1.5	1.5A 1.5	1.5A 1.5	1.5A 1.5
Ground Voltage AV	1.5A 1.5	1.5A 1.5	1.5A 1.5	1.5A 1.5	1.5A 1.5	1.5A 1.5	1.5A 1.5	1.5A 1.5	1.5A 1.5	1.5A 1.5	1.5A 1.5	1.5A 1.5	1.5A 1.5
Power Min/Max AV	1.5A 1.5	1.5A 1.5	1.5A 1.5	1.5A 1.5	1.5A 1.5	1.5A 1.5	1.5A 1.5	1.5A 1.5	1.5A 1.5	1.5A 1.5	1.5A 1.5	1.5A 1.5	1.5A 1.5
Ground Power Threshold	1.5A 1.5	1.5A 1.5	1.5A 1.5	1.5A 1.5	1.5A 1.5	1.5A 1.5	1.5A 1.5	1.5A 1.5	1.5A 1.5	1.5A 1.5	1.5A 1.5	1.5A 1.5	1.5A 1.5
Ground Power Max Test	1.5A 1.5	1.5A 1.5	1.5A 1.5	1.5A 1.5	1.5A 1.5	1.5A 1.5	1.5A 1.5	1.5A 1.5	1.5A 1.5	1.5A 1.5	1.5A 1.5	1.5A 1.5	1.5A 1.5
Ground Power Min Test	1.5A 1.5	1.5A 1.5	1.5A 1.5	1.5A 1.5	1.5A 1.5	1.5A 1.5	1.5A 1.5	1.5A 1.5	1.5A 1.5	1.5A 1.5	1.5A 1.5	1.5A 1.5	1.5A 1.5
Driver PWR Generation	1.5A 1.5	1.5A 1.5	1.5A 1.5	1.5A 1.5	1.5A 1.5	1.5A 1.5	1.5A 1.5	1.5A 1.5	1.5A 1.5	1.5A 1.5	1.5A 1.5	1.5A 1.5	1.5A 1.5
DCS Initiator Test Test	1.5A 1.5	1.5A 1.5	1.5A 1.5	1.5A 1.5	1.5A 1.5	1.5A 1.5	1.5A 1.5	1.5A 1.5	1.5A 1.5	1.5A 1.5	1.5A 1.5	1.5A 1.5	1.5A 1.5